

# **Smart Shop Series:**

SmartShop SS2 (B Axis/Syntec)

Basic SS2 Operation with B Axis & Syntec Controller.



#### **Owner's Manual**

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#### **General Information**

### SAVE THESE INSTRUCTIONS

#### Refer to them often and use them to instruct others.

Please read and understand all warnings and operation instructions before using any tool or equipment. Always follow basic safety precautions to reduce the risk of personal injury. Improper operation, maintenance or modification of tools or equipment could result in serious injury and property damage. There are certain applications for which tools and equipment are designed. This product should **NOT** be modified and/or used for any application other than for which it was designed.

**NOTICE!** It is important for you to read and understand this manual. The information it contains is provided for your safety while assembling and operating this machine.

### Safety Signs and Call-Outs:

**DANGER** 

An imminently hazardous situation which, if not avoided, will result in death or serious injury.

**CAUTION** 

A potentially hazardous situation which, if not avoided, could result in death or serious injury.

△WARNING A potentially hazardous situation which, if not avoided, may result in minor or moderate injury.

A helpful tip from our technical staff. Sometimes displayed as **NOTICE!** instead.

0=5	Disconnect from power before proceeding.		Wear ear protection.
¥0	Be aware of possible laceration danger.		Wear Eye Protection.
S	Be aware of possible crushing danger.		Wear a full face shield.
	Electrical Hazard.		Wear lung protection.
		<b>M</b> .X	Requires X People

## Safety Rules

# PLEASE READ AND UNDERSTAND ALL SAFETY WARNINGS AND OPERATING INSTRUCTIONS BEFORE USING THIS MACHINE

**FAILURE** to follow all instructions listed below, may result in electric shock, fire, and/or serious personal injury or property damage. Woodworking can be dangerous if safe and proper operating procedures are not followed. As with all machinery, there are certain hazards involved with the operation of the product. Using the machine with respect and caution will considerably lessen the possibility of personal injury. However, if normal safety precautions are overlooked or ignored, improper operation or assembly of this machine could result in personal injury to the operator. Safety equipment such as guards, push sticks, hold downs, feather boards, goggles, dust masks and hearing protection can reduce your potential for injury. But even the best guard won't make up for poor judgment, carelessness or inattention.

**ALWAYS** use common sense and exercise caution in the workshop. If a procedure feels dangerous, don't try it. Consult a professional to find an an alternative procedure which is safer and more efficient.

## **NOTICE!** Your personal safety is YOUR responsibility.

This machine was designed for certain applications only. We strongly recommend that this machine not be modified and/or used for any application other than that for which it was designed. If you have any questions relative to a particular application, **DO NOT** use the machine until you have first contacted the manufacturer to determine if it can or should be performed on the product.

**A WARNING!** If you have any questions relative to its application **DO NOT** use the product until you have contacted the manufacturer and we have advised you. When using an electrical machine, basic precautions should always be followed, including the following:

Read and understand all warnings and operation instructions before using any tool or equipment. Always follow basic safety precautions to reduce the risk of personal injury. Improper operation, maintenance or modification of tools or equipment could result in serious injury and property damage. There are certain applications for which tools and equipment are designed. This product should NOT be modified and/or used for any application other than for which it was designed. It is important for you to read and understand this manual. The information it contains relates to protecting your safety and preventing problems.

#### **Machine & Workshop Safety Instructions**

READ AND UNDERSTAND ALL WARNINGS AND OPERATING INSTRUCTIONS BEFORE USING THIS EQUIPMENT. FAILURE TO

FOLLOW ALL INSTRUCTIONS LISTED BELOW, MAY RESULT IN ELECTRIC SHOCK, FIRE, AND/OR SERIOUS PERSONAL INJURY OR PROPERTY DAMAGE.

# MACHINERY CAN BE DANGEROUS IF SAFE AND PROPER OPERATING PROCEDURES ARE NOT FOLLOWED. AS WITH ALL

MACHINERY, THERE ARE CERTAIN HAZARDS INVOLVED WITH THE OPERATION OF THE PRODUCT. USING

THE MACHINE WITH

RESPECT AND CAUTION WILL CONSIDERABLY LESSEN THE POSSIBILITY OF PERSONAL INJURY. HOWEVER, IF NORMAL

SAFETY PRECAUTIONS ARE OVERLOOKED OR IGNORED, PERSONAL INJURY TO THE OPERATOR MAY RESULT. SAFETY

EQUIPMENT SUCH AS GUARDS, PUSH STICKS, HOLD-DOWNS, FEATHER BOARDS, GOGGLES, DUST MASKS AND HEARING

PROTECTION CAN REDUCE YOUR POTENTIAL FOR INJURY. BUT EVEN THE BEST GUARD WON'T MAKE UP FOR POOR

JUDGMENT, CARELESSNESS OR INATTENTION. ALWAYS USE COMMON SENSE AND EXERCISE CAUTION IN THE WORKSHOP.

IF A PROCEDURE FEELS DANGEROUS, DON'T TRY IT. FIGURE OUT AN ALTERNATIVE PROCEDURE THAT FEELS SAFER.

REMEMBER: YOUR PERSONAL SAFETY IS YOUR RESPONSIBILITY.

OWNER'S MANUAL. READ AND UNDERSTAND THIS OWNER'S MANUAL BEFORE USING MACHINE.

TRAINED OPERATORS ONLY. UNTRAINED OPERATORS HAVE A HIGHER RISK OF BEING HURT OR KILLED. ONLY ALLOW

TRAINED/SUPERVISED PEOPLE TO USE THIS MACHINE. WHEN MACHINE IS NOT BEING USED, DISCONNECT POWER.

REMOVE SWITCH KEYS, OR LOCK-OUT MACHINE TO PREVENT UNAUTHORIZED USE—ESPECIALLY AROUND CHILDREN. MAKE

YOUR WORKSHOP KID PROOF!

**DANGEROUS ENVIRONMENTS**. DO NOT USE MACHINERY IN AREAS THAT ARE WET, CLUTTERED, OR HAVE POOR LIGHTING.

OPERATING MACHINERY IN THESE AREAS GREATLY INCREASES THE RISK OF ACCIDENTS AND INJURY.

**MENTAL ALERTNESS REQUIRED**. FULL MENTAL ALERTNESS IS REQUIRED FOR SAFE OPERATION OF MACHINERY. NEVER

OPERATE UNDER THE INFLUENCE OF DRUGS OR ALCOHOL, WHEN TIRED, OR WHEN DISTRACTED.

**ELECTRICAL EQUIPMENT INJURY RISKS**. YOU CAN BE SHOCKED, BURNED, OR KILLED BY TOUCHING LIVE ELECTRICAL

COMPONENTS OR IMPROPERLY GROUNDED MACHINERY. TO REDUCE THIS RISK, ONLY ALLOW QUALIFIED SERVICE

PERSONNEL TO DO ELECTRICAL INSTALLATION OR REPAIR WORK, AND ALWAYS DISCONNECT POWER BEFORE ACCESSING

OR EXPOSING ELECTRICAL EQUIPMENT.

**DISCONNECT POWER FIRST**. ALWAYS DISCONNECT MACHINE FROM POWER SUPPLY BEFORE MAKING ADJUSTMENTS.

CHANGING TOOLING, OR SERVICING MACHINE. THIS PREVENTS AN INJURY RISK FROM UNINTENDED START-UP OR

CONTACT WITH LIVE ELECTRICAL COMPONENTS.

**EYE PROTECTION**. ALWAYS WEAR ANSI-APPROVED SAFETY GLASSES OR A FACE SHIELD WHEN OPERATING OR OBSERVING

MACHINERY TO REDUCE THE RISK OF EYE INJURY OR BLINDNESS FROM FLYING PARTICLES. EVERYDAY EYEGLASSES ARE

NOT APPROVED SAFETY GLASSES.

**WEARING PROPER APPAREL**. DO NOT WEAR CLOTHING, APPAREL OR JEWELRY THAT CAN BECOME ENTANGLED IN MOVING

PARTS. ALWAYS TIE BACK OR COVER LONG HAIR. WEAR NON-SLIP FOOTWEAR TO REDUCE RISK OF SLIPPING AND LOSING

CONTROL OR ACCIDENTALLY CONTACTING CUTTING TOOL OR MOVING PARTS.

**HAZARDOUS DUST**. DUST CREATED BY MACHINERY OPERATIONS MAY CAUSE CANCER, BIRTH DEFECTS, OR LONG-TERM

RESPIRATORY DAMAGE. BE AWARE OF DUST HAZARDS ASSOCIATED WITH EACH WORKPIECE MATERIAL. ALWAYS WEAR A

NIOSH-APPROVED RESPIRATOR TO REDUCE YOUR RISK.

**HEARING PROTECTION**. ALWAYS WEAR HEARING PROTECTION WHEN OPERATING OR OBSERVING LOUD MACHINERY.

EXTENDED EXPOSURE TO THIS NOISE WITHOUT HEARING PROTECTION CAN CAUSE PERMANENT HEARING LOSS.

**REMOVE ADJUSTING TOOLS**. TOOLS LEFT ON MACHINERY CAN BECOME DANGEROUS PROJECTILES UPON STARTUP. NEVER

LEAVE CHUCK KEYS, WRENCHES, OR ANY OTHER TOOLS ON MACHINE. ALWAYS VERIFY REMOVAL BEFORE STARTING!

**USE CORRECT TOOL FOR THE JOB.** ONLY USE THIS TOOL FOR ITS INTENDED PURPOSE—DO NOT FORCE IT OR AN

ATTACHMENT TO DO A JOB FOR WHICH IT WAS NOT DESIGNED. NEVER MAKE UNAPPROVED MODIFICATIONS, MODIFYING

TOOL OR USING IT DIFFERENTLY THAN INTENDED MAY RESULT IN MALFUNCTION OR MECHANICAL FAILURE THAT CAN

LEAD TO PERSONAL INJURY OR DEATH!

**AWKWARD POSITIONS**. KEEP PROPER FOOTING AND BALANCE AT ALL TIMES WHEN OPERATING MACHINE. DO NOT

OVERREACH! AVOID AWKWARD HAND POSITIONS THAT MAKE WORKPIECE CONTROL DIFFICULT OR INCREASE THE RISK OF ACCIDENTAL INJURY.

CHILDREN & BYSTANDERS. KEEP CHILDREN AND BYSTANDERS AT A SAFE DISTANCE FROM THE WORK AREA.STOP USING

MACHINE IF THEY BECOME A DISTRACTION.

**GUARDS & COVERS**. GUARDS AND COVERS REDUCE ACCIDENTAL CONTACT WITH MOVING PARTS OR FLYING DEBRIS. MAKE

SURE THEY ARE PROPERLY INSTALLED, UNDAMAGED, AND WORKING CORRECTLY BEFORE OPERATING MACHINE.

FORCING MACHINERY. DO NOT FORCE MACHINE. IT WILL DO THE JOB SAFER AND BETTER AT THE RATE FOR WHICH IT WAS

DESIGNED.

**NEVER STAND ON THE MACHINE**. SERIOUS INJURY MAY OCCUR IF MACHINE IS TIPPED OR IF THE CUTTING TOOL IS

UNINTENTIONALLY CONTACTED.

**STABLE MACHINE**. UNEXPECTED MOVEMENT DURING OPERATION GREATLY INCREASES RISK OF INJURY OR LOSS OF

CONTROL. BEFORE STARTING, VERIFY MACHINE IS STABLE AND MOBILE BASE (IF USED) IS LOCKED.

**USE RECOMMENDED ACCESSORIES**. CONSULT THIS OWNER'S MANUAL OR THE MANUFACTURER FOR RECOMMENDED

ACCESSORIES. USING IMPROPER ACCESSORIES WILL INCREASE THE RISK OF SERIOUS INJURY.

**UNATTENDED OPERATION.** TO REDUCE THE RISK OF ACCIDENTAL INJURY, TURN MACHINE OFF AND ENSURE ALL MOVING

PARTS COMPLETELY STOP BEFORE WALKING AWAY. NEVER LEAVE MACHINE RUNNING WHILE UNATTENDED.

MAINTAIN WITH CARE. FOLLOW ALL MAINTENANCE INSTRUCTIONS AND LUBRICATION SCHEDULES TO KEEP MACHINE IN

GOOD WORKING CONDITION. A MACHINE THAT IS IMPROPERLY MAINTAINED COULD MALFUNCTION, LEADING TO SERIOUS

PERSONAL INJURY OR DEATH.

**DAMAGED PARTS**. REGULARLY INSPECT MACHINE FOR DAMAGED, LOOSE, OR WRONGLY ADJUSTED PARTS—OR ANY

CONDITION THAT COULD AFFECT SAFE OPERATION. IMMEDIATELY REPAIR/REPLACE BEFORE OPERATING MACHINE. FOR

YOUR OWN SAFETY, DO NOT OPERATE MACHINE WITH DAMAGED PARTS!

MAINTAIN POWER CORDS. WHEN DISCONNECTING CORD-CONNECTED MACHINES FROM POWER, GRAB AND PULL THE

PLUG—NOT THE CORD. PULLING THE CORD MAY DAMAGE THE WIRES INSIDE. DO NOT HANDLE CORD/PLUG WITH WET

HANDS. AVOID CORD DAMAGE BY KEEPING IT AWAY FROM HEATED SURFACES, HIGH TRAFFIC AREAS, HARSH CHEMICALS,

AND WET/DAMP LOCATIONS.

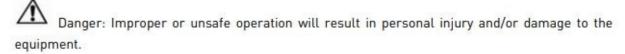
### **Additional Safety Rules**

# For safe operation of your machine, please read these instructions thoroughly <u>BEFORE</u> operating machine.

- 1.) The machine is supplied ready to go—all motion parameters have been set up by the supplier. If any modifications are required, please have a professional operator to perform such changes.
- 2.) Never operate the machine with the electrical cabinet door open as there is high voltage supply inside.
- 3.) Carefully read through all the safety instructions, warnings as well as signs attached to the machine before operating.
- 4.) Use machine only in clean areas free from excessive moisture or flammable objects.
- 5.) Machine must be properly grounded. Level the machine is the ground is uneven.
- 6.) Keep the machine and cabinet clear of unnecessary objects and keep all parts clean.
- 7.) Keep the machine, cabinet and cables away from excessive heat, flammable substance and sharp objects. Do not attempt to exceed limits of the machine.
- 8.) Safety-Check to ensure that objects and persons are clear of the machine during operation.
- 9.) Disconnect power to all system components when not in use, when changing accessories and before servicing.
- 10.) Do not loosen, remove or adjust machine parts or cables while power is on.
- 11.) Exercise care with machine controls and around keypad to avoid unintentional starting.
- 12.) Maintain equipment with care: Keep cutting tools clean and sharp. Lubricate and change accessories when necessary. Cables and cords should be inspected regularly. Keep controls clean and dry.

#### Safety Signs

•Pay attention to the safety signs before operating the machine to avoid injury or damage to the operator or the equipment.





Prohibited: prohibited under any circumstances.



Must-dos



High voltage power supply: Caution



Read thoroughly before operating. Do not operate machine if the operator is unfamiliar with the safety instructions and safety signs.

**NOTICE!** Users are required to keep a copy of this user manual for future reference. Failure to comply with the safety instructions may lead to personal injury and/or damage to the equipment.

### **Operator Safety**

#### NOTICE

#### Before operating the machine, the operator must:

Be familiar with the equipment and its installation, adjusting and operation, and be able to react in emergencies. Be properly trained, familiar with the operation, repair and maintenance of the machine:

#### The operator must also:

- 1.) Perform daily inspection of the Safety Device(s).
- 2.) **Stay Alert**at all times when operating the machine.
- 3.) Keep the table clear of debris or other unnecessary objects.
- 4.) Operate only after making sure the machine is clear of unnecessary objects.
- 5.) Wear Safety Glasses at all Times, but gloves are prohibited.
- 6. Keep the machine and cabinet free from unnecessary objects and keep all parts clean.
- 7. Not attempt to use the machine before proper inspection and preparation.
- 8. Know where the emergency stop switch is located.
- 9. Keep the machine from excessive moisture or use a filter to ensure this.

# **Electrical Safety**

- 1.) Do not operate the machine with Electrical Cabinet Door Open—High Voltage Supply Inside.
- 2.) The machine must have proper electrical grounding.

The power supply must be connected to permanently fixed electrical wire.

3.) The machine is supplied ready-to-go.

Adjustments and modifications are to be performed only by qualified personnel.

- 4.) Keep children and non-operators away from the machine.
- 5.) Carefully read through all the safety instructions and warnings. The **Safety Signs should be Attached** on places that are easy to spot.
- 6.) Operators must be familiar with the installation, operation and service of the machine.

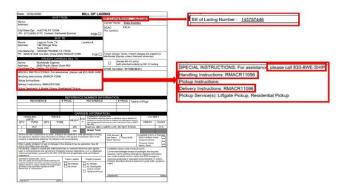
Only proper operation can guarantee the safe and smooth running of the machine.

# **Delivery Protocols**

Most large machinery will be delivering on a tractor trailer 48'-53' long. Please notify Sales Representative with any Delivery Restrictions.

Customer is required to have a forklift (6000lb. or larger is recommended) with 72" forks or fork extensions and operator.

Note any visible damage, torn packaging, scuffs or any abnormal marks on the delivery receipt or **Bill of Lading** (BOL).



# **Machine Specifications**

# **Machine Specifications**

I .			
Smartshop SS2 Machine (B-Axis/Syntec Controller) Specifications-			
Traveling Size	98.5 ln. x 49.60 ln. x 7.87 ln./11.81 ln.		
Working Size	97.63 ln. x 48.42 ln. x 7.09 ln./11.02 ln.		
Table Size	98.42 ln. x 48.42 ln.		
Optional Working Length	"N/A"		
Transmission	X/Y Rack and Pinion, "Z" Ball Screw Drive		
Table Structure	T-Slot Vacuum		
Spindle Power	9.6kW		
Spindle Speed	24000 rpm		
Traveling Speed	750 in/min.		
Working Speed	550 in/min.		
Driving System	Stepper System or Servo System		
Controller	Syntec		

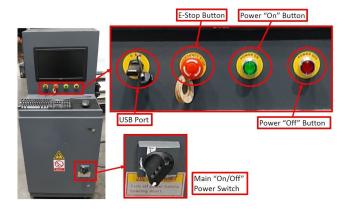
### **Machine Description**

#### **Machine Description:**

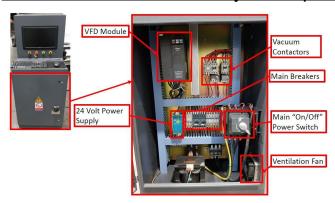
This model is an extremely cost-effective work center with 8-Slot tool changer. With Italian high power ATC spindle, and gear reducers, French Schneider electronic components and other imported parts, this machine has stable and reliable performance.

It is highly suitable for various processing procedures with versatile functions: routing, drilling, cutting, side milling, chamfering, etc. The T-slot vacuum table can either hold the materials of different sizes with strong suction power, or clamp materials of irregular shapes Laguna Tools SS2 with B-Axis & Syntec Control with fixtures.

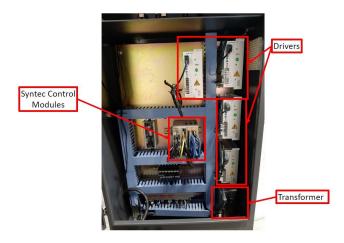
#### **Electrical Cabinet Layout & Operation**



#### **Electrical Cabinets Lower Interior Layout and Operation**



#### **Electrical Cabinets Back Door Interior Layout and Operation**



# Electrical Cabinets MPG (Manual Pulse Generator) Location and Operation



### **Operating the MPG**

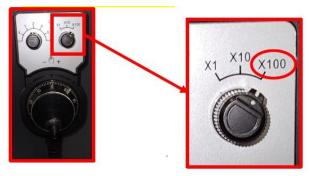
1.) From the Main Screen, press the "MPG Button".



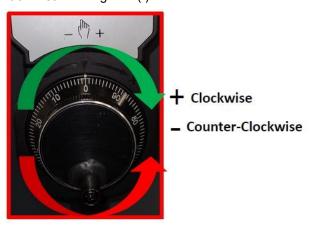
2.) Use the "Top Left Knob on the MPG" to select the axis to move.



3.) Use the "Top Right Knob on the MPG" to select speed, with 100X being the fastest.



4.) Rotate the "Bottom Knob, Clockwise" to move the Axis in the Positive (+) direction and "Counter-Clockwise" for Negative (-) direction.



# **Main Part Descriptions**

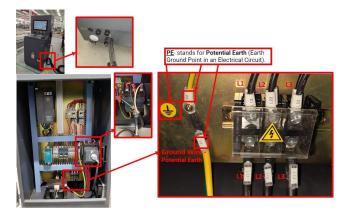
## **Main Part Machine Functions:**

Part	Description
Electro-Spindle Assembly	For cutting, engraving and other
,	operations. Its compact structure, light
	in weight, low vibration and noise, high
	rotation speed and high power have
	gained it wide popularity with the CNC
	Router users
Square Linear Guide Rail	Features high linear accuracy, rigidity
	and big dynamic load. The self-
	lubrication design achieves long service
	life and consistent accuracy. The machine features "solid welded steel
	structure". The material has been
	vibrated and heat-treated to release the
	inner stress.
Helical Rack:	This drives the machine. Each tooth is
	accurately geared, which enables
	smooth linear motion and minimum run
	noise. The load on each tooth is
	reduced and the movement is more
	steady.
Electric Cabinet	This houses the controller and other
	critical electronic components. The
	user-friendly design gives easy access
	to the operator. The electric fan located
	at the side of the cabinet guarantees effective air flow and keeps the inside
	cool.
Gantry	A rigid structure to carry the spindle's
, <b>,</b>	horizontal movement.
T-Slot Vacuum Table	Is able hold down the work pieces with
	either vacuum suction power or fixtures,
	which is easy to use.
Caterpillar Track	The caterpillar track runs along the side
	of the machine in a special trough and
	carries all the electrical cables and air
Vacuum Cartral Value	lines.
Vacuum Control Valves	The machine has six (6) vacuum control valves that can be used to direct the
	valves that can be used to direct the vacuum to the vacuum table zones.
Tool Rack ATC	Tool changer includes eight (8) tool
1001 Nack A10	stations to accommodate a large range
	of tools. Each of the stations includes a
	ISO-30 gripper assembly, and station
	positions are controlled the Laguna
	Touch CNC controller.

Part	Description	
Frame	The frame is a heavy steel all-welded	
	construction that provides a rigid	
	platform for the other components and	
	ensures accuracy as well as edge	
	finish.	

# **Electrical Installation**

Electrify the following lines (as shown in the figure). Please test to guarantee 220V stabilized voltage before electrification.



# **Connecting the Vacuum Pump**

### **Connecting the Vacuum Pump SV-400 Series:**

The machine is provided with a 2-inch hose for connection to the vacuum pump. The vacuum hose is connected to the manifold located under the table toward the front of the machine. Connect the free end to the vacuum hose to the vacuum pump inlet. Ensure that it is clamped securely.





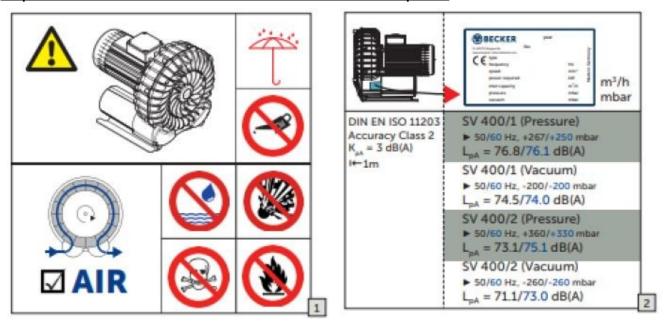




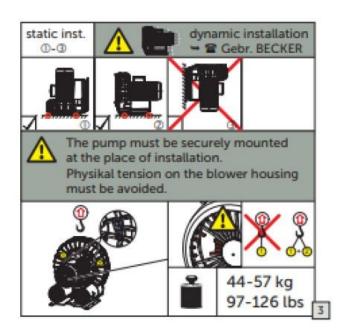
# SV-400 Series BECKER

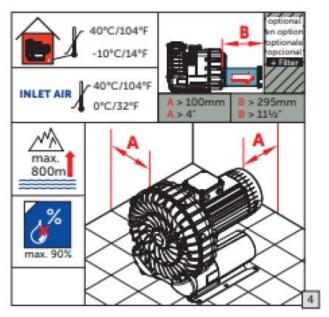
#### **Connection Instructions:**

Step One: Step Two:

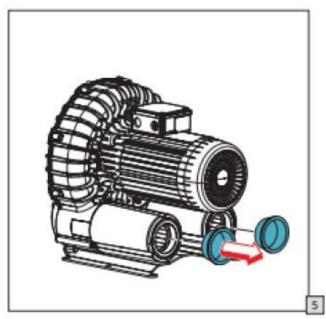


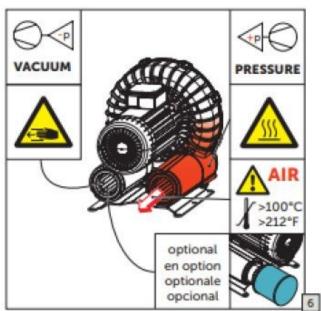
Step Three: Step Four:



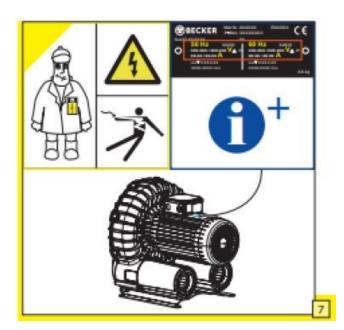


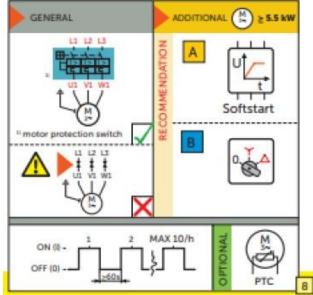
Step Five: Step Six:



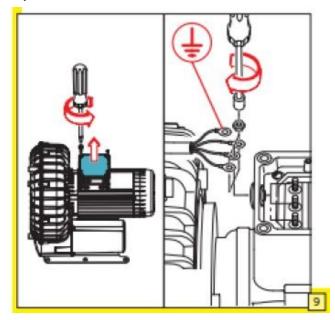


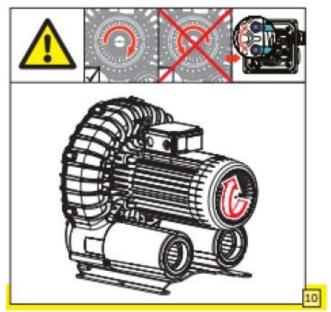
Step Seven: Step Eight:



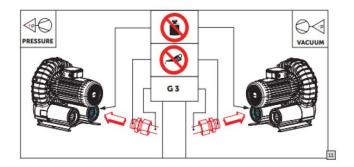


Step Nine: Step Ten:



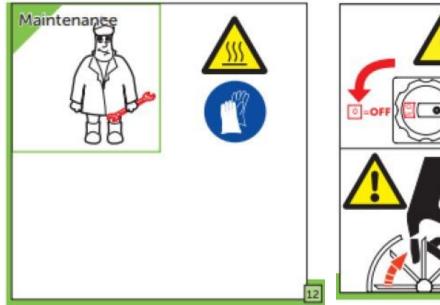


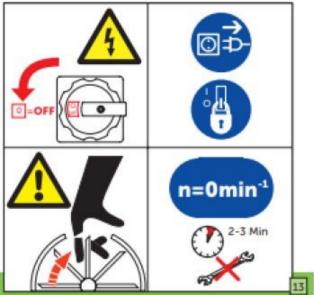
Step Eleven:



Step Twelve:

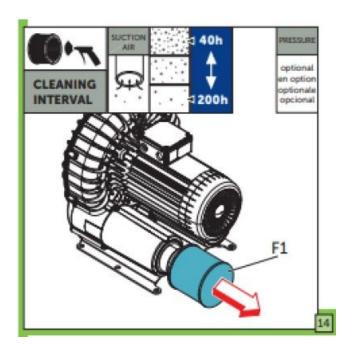
Step Thirteen:

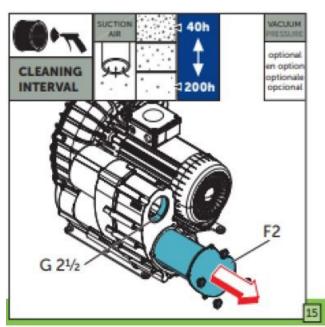




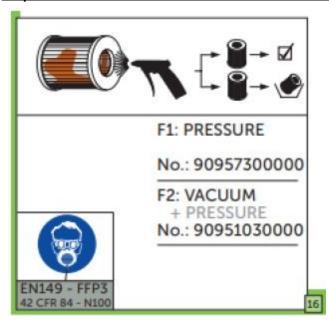
Step Twelve:

Step Thirteen:

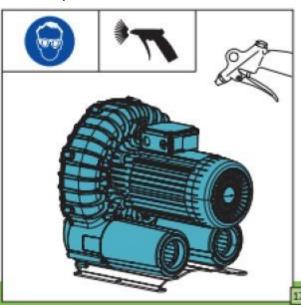




### Step Sixteen:



## Step Seventeen:



Step Eighteen:



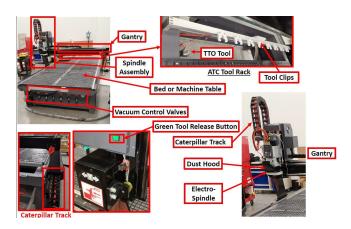
# **More Information:**



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# **Introduction to CNC Machines**

# SmartShop SS2 Machine (B-Axis/Syntec Controller)



## Smartshop SS2 Machine (B-Axis/Syntec Controller) Tool Kit

<u>Name</u>	Part No.	Part Name	Model	Qty.
Tool Kit	30505123	Toolbox (Domestic)	Rongyu	1
Collet	30505060	1/2" Inch Collet	ER32-12.7	1
Collet	30505065	7/8" Inch Collet	ER32-8	1
Collet	30505064	6 MM Collet	ER32-6	1
Collet	30505062	3.175 MM or 1/8" Inch Collet	ER32-3.175	1
Collet	30505063	1/4' or .250 Inch Collet	ER32-4	1
Collet/Spanner Wrench	30505028	Collet/Spanner Wrench	ER32-T2	1
Collet/Spanner Wrench	30505025	Collet/Spanner Wrench	30-32	1
Press Plate Screw	20202494	Press Plate Screw (Long Plate)	Long Board	8
Nut		Nut	M8	8
	40102475	11.00		-
Nut (Butterfly)	40102537	Nut (Butterfly)	M8	8
Screw (Hexagon)	40102536	Screw (Hexagon Socket)	M8-40	8
Wrench (Hexagon)	30505042	Wrench (Hexagon)	Hekko Machine Dedicated	1
Straight Screwdriver	4010303009	Screwdriver	Large	1
Phillips Screwdriver	4010303007	#10-Screwdriver	#10-Large	1
Automatic Drainer	30511147	Automatic Drainer	QAD400-04	1
DSP Hand-Held System	30505355	Handle DSP Row Type Tool Change System.	B57	1
USB Cable	30505356	Data Cable (with B57 Row Tool Change System).	нрмі	1
USB Flash Drive	30505219	USB Disk	4G	2
Grease Gun	30505310	Any Type of Grease Gun.		1
Dust Collector Hose	30511072	Vacuum Cleaner Tube	Ф102	12
Clip	30315039	Clip	90-110	4
Filter Cotton	30511039	Filter Sponge	115*115*16	12
Screwed Pipe	30405040	Threaded Pipe	ф54.5	4
Screwed Pipe Joint	30405048	Threaded Pipe Fittings	ф54.5	2
Rubber Seal	30315033	Glue-(6.5*8)	E2-1325-71	30
Plug	30315017	Plug	30-40	20
One Set Labels on Cabinet		A set of all the Labels affixed on the		1

#### **Machine Location**

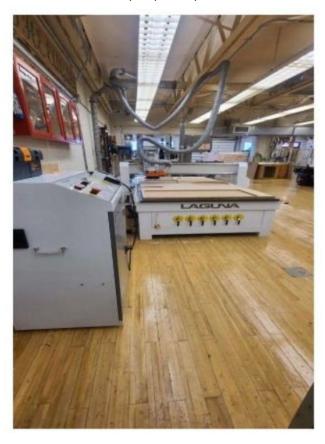
<u>△WARNING</u> Before unpacking the machine, select the area where the machine will be installed.

- 1)There should be an area around the machine suitable for the length of material that will be machined as well as any loading and unloading requirements.
- 2)There should be adequate lighting in the work area. The better the lighting, the better the productivity.
- 3)The floor area under the machine should be flat and solid so that the machine frame does not shift as the gantry and tool plate traverse. Concrete is preferable.
- 4)Consider the electrical and air supplies, vacuum pump location and dust collection when identifying an area to place the machine.

### **Installation Readiness & Set-up**

### **Installing your New CNC Machine**

1.) Determine location, machine should have at least 3 feet around all sides. If you can't bend down between the wall and the machine neither can a technician if you need any repairs completed. Pictured is a typical machine layout. Not pictured is the vacuum pumps what are typically positioned behind the machine. Down in a later step you will see how most pumps are placed.



2.) When you receive your machine it will come with leveling pads, bolts and nuts. Before setting the machine down on the floor screw the bolts and nuts, bolt head facing upwards towards the tabletop. The pad goes underneath the frame and, on the floor, center the pads with each bolt as pictured. Then level the machine.



3.) Once the machine is leveled and you place the electrical cabinet on the floor you will be ready for electric, air and placement of the vacuum pump or pumps. Tool changing machines will require air between 95 and 100 psi 5-7 CFM at the machine. Manual tool change spindle will not require air unless you have an option like a misting unit. Laguna supplies a poly tube connection this can be removed if you want to put in a quick disconnect airline yourself. You are required to supply main power cable to the electrical cabinet, power cables from the cabinet to each vacuum pump, airline and connection to the back of the machine. Attached are a few pictures where to land power cables and air lines.



Poly connection for incoming airline which can be removed if you are going to screw in quick disconnect airline fittings.

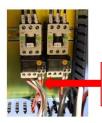


Once everything is wired do not turn on power. When the Technician arrives, she/hewill make sure everything is correct.

Contactors to Vacuum Pumps Single Phase will have VFD Drives to connect Power Cables.

Main disconnect where incoming power connects . Use insulated connectors to connect power cables to the disconnect bolts.

Use this bolt to land vacuum grounds and main power ground.



Once everything is wired do not turn on power. When the Technician arrives, she/he will make sure everything is correct.

Closer look at the vacuum contactor connection. Laguna doesn't provide the cables to the vacuum; your electrician will need to properly size the wires to the pump and main disconnect according to your local codes.



Typical Pump Wiring 208 to 240 Vac.
Jumpers should look like these wires will
land on u1, v1 and w1 ground will
connect where you see the ground
symbol

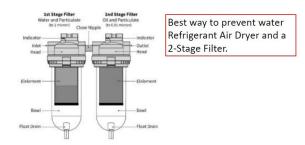


Standard location for vacuum pumps.



Do not place vacuum under your machine, vacuums can get over heated. This will cause exhaust to be trapped at temperatures up to 212° F. Inlet air temperature should be less than 104° F. Also worth noting is that you will have to service the filters, and this is much easier to do with better access.





4.) Dust collection hook up. It is best to use duct as close to the center of the machine as possible. Some places will have height clearance issues the first picture in this document shows one with high height clearance and it's not the best solution. You may have clogging issue from time to time which will require you to pull the hose down and clean it out from time to time. Below is a better picture that shows a snorkel that we offer which works nice. Or you can supply your own system.



5.) Last thing software if you haven't received your software email your salesman to get your software. If you paid for a technician to come out, you will want to be ready. You should have your software training completed before the technician comes out. Mozaik is usually booked out about 3 weeks in advance so you will want to contact them right away to schedule your training. Mozaik will want your machine configuration. Example blew is a Smart Shop 2 with Syntec controller. Below that are all machine configurations.



#### **Machine Configurations:**

Swift & M2 (Rich Auto) SS2 (B&R or Syntec) SUV (B&R) Auto loader (Syntec) SS3 (Fanuc) (is the type of Controller).

- •All machines Long Axis will be the Y-Axis.
- •SS2 with B&R, SUV B&R and SS3 with Fanuc will be in inches.
- •Swift, M2, SS2 with Syntec, Auto loader with Syntec will all be in millimeters.
- •All machines you will want to choose top of the Spoil board.
- •Auto Tool changer yes for all, except Swift.

**NOTICE!** Multi-Drill is only offered on the SS3 and Auto loader so if you have that option check yes. All other software programs please check our Laguna Tools Website at the link below: <a href="https://lagunatools.com/resources/cnc-software/">https://lagunatools.com/resources/cnc-software/</a>

Learning your Camming Software prior to the technician's arrival is your responsibility. Please have a working knowledge of the camming software so the technician can focus on the machine training. Technicians do have a working knowledge of Vectric Products and can assist, but they are not there for rudimentary software training.

All these steps must be completed before scheduling a technician to come out. If they are not completed a technician might not be able to complete all training and may have to schedule a second trip at the current daily rates plus travel expenses.

Like all machines, there is danger associated with the machine. Injury can be caused by lack of knowledge or familiarity. Use this machine with respect. If normal safety precautions are overlooked or ignored, serious personal injury may occur. As the CNC is under the control of the onboard machine controller, it is important that you are clear of the cutter when operating the machine.

#### **List of Additional Accessories:**

Clamps
Cutters & Collets
Memory Stick
Dust Hose Clamps
Tool Holders Wrenches

## **Unpacking Your Machine**

### **Unpacking the Machine:**

Unpacking the machine will require tin snips (to cut banding), a knife and an adjustable wrench. Follow the steps below:

- 1) Using the tin snips, cut the banding that is securing the machine to the pallet (if fitted).
- 2) WARNING: EXTREME CAUTION MUST BE USED BECAUSE THE BANDING CAN SPRING AND COULD CAUSE INJURY.
- 3) Remove the box from the CNC machine (if fitted) and any other packaging material. The parts ordered with the machine will be packed on or inside the machine. (Please note, the machine is heavy, and it is recommended that professional assistance [rigging] be used for unloading and placing the machine.).
- 4) Use a forklift with sufficient lifting capacity and forks that are long enough to reach the complete width of the machine before attempting to lift the machine.
- 5) Remove the securing bolts that attach the machine to the pallet (if fitted).
- 6) Approaching the machine from the side, lift the machine on the frame, taking care that there are no cables or pipes in the area of the forks.
- 7) Move the machine to the required position and install the leveling feet.
- 8) Then lower the machine gently to the floor.
- 9) Level the machine so that all the supporting feet are taking the weight of the machine and no rocking is taking place.

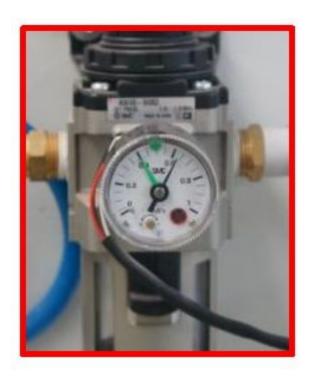
### **Test Run Instructions**

### **Preparation**

- 1.) Check if the appearance of the machine is intact and if all the moving parts are at the Home position.
- 2.) Check to make sure none of the electric components in the cabinet are loose or damaged, and none of the wire terminals get loose.
- 3.) Check if all the safety devices are complete and all the buttons and electric parts are in the right positions.
- 4.) Check if the tool clamps and fixtures are installed tightly and check if they are displaced or damaged.
- 5.) Check if any electric components are damaged or the wire terminals are loose.
- 6.) Check if the cables are connected tightly. The zero line should be N or P line. Connection must be made according to the right line numbers or else short circuit might occur.
- 7.) Disconnect the circuit breaker and see if there is any abnormality. If so, clear the error before one operates the machine. Have a thorough inspection of all the parts and electronics before turning on the power supply.
- 8.) Check the pressure of each pressure indicator (Spec. 85 psi-95 psi).
- 9.) Turn on the power supply and switch on the machine.



Main "On/Off" Power Switch



10.) Press the "GreenPower On" Buttonto turn on the power to the Controller Area, Press "Red Power Off" Buttonto cut off power to the Controller Area.



Wait for the system to boot, then release the "Emergency Stop Switch". To release "Emergency Stop Switch" turn the red knob a ¼ of turn "Clockwise" to release.



**NOTICE!** Press this "**E-Stop Button**" when one is in personnel danger or a problem occurs during the table operation, then all the electric controlling of the table will be cut off.

At this time, except the power of the controller, the power of the servo motor, spindle and metalworking fluids will be cut off to ensure personnel and machine safety.

11.) The Control Software Interface will automatically materialize on the computer screen when the machine is powered up and turned on.

To begin, select origin mode, "Home" then "Cycle Start". The Machine "B" Parameter Setting, will not be present, unless one selects the setting in a prior operation.



# **Machine Set-Up**

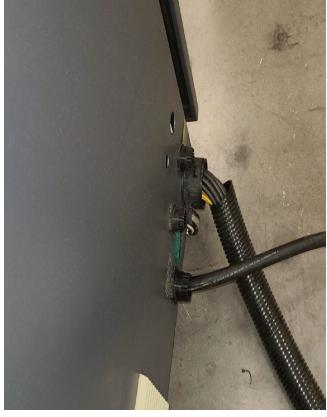
1.) Using Leveling Feet, Support and Level SS2 CNC Machine.





2.) SAFETY-Verify your shop/building has proper electrical supply. For confirmation on this, call customer service (1-800-234-1976) for diagrams verifying proper voltage & amperage requirements.





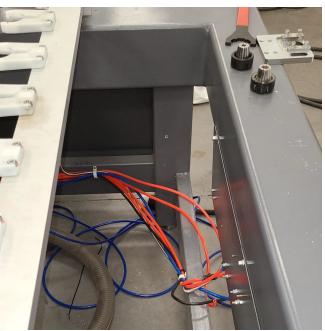
- 3.) Have a Certified Electrician wire from building breaker into control box (Does not need to hook up L1, L2, and L3, but they must run the wire into the box.)
- 4.) Have a Certified Electrician wire from contactor to vacuum. (Run wires to vacuum and into box, we can wire once the wires are inside to the contactor. Vacuum has a Legend-Plate, electrician must decide wire size).





5.) Hook up clean, dry air to compressor on rear of machine underneath tool rack. (We do not supply inlet connector) Needs to be 85 PSI-95 PSI.





6.) Verify all items that were purchased and are on the sales order were sent and included. Verify there is a dust hood on the spindle. (If any items are missing, call customer service (1-800-234-1976 for verification on missing items so they may be sent out)

- 7.) If providing own tooling, verify all proper tooling is available and readily available.
- 8.) Acquire adequate supply of materials to be cut during install including MDF Board for a Spoil Board to be placed on tabletop (Spec. .75" –1" Think).
- 9.) Install all software ahead of time. Review tutorials and gather basic understanding of software before technician arrives.
- 10.) "Read & Review Manuals" and try to familiarize with machine and basic components.
- 11.) Get 30W Oil for lubrication purposes (DO NOT USE WD-40 as a lubricant!).



The machine is supplied with an air regulator. The input air regulator regulates the air pressure that is supplied to the machine. You will require an air supply that can deliver a constant minimum pressure of 85 psi. The input air regulator will need to be adjusted to 85 psi-95 psi once you have connected your air supply to the machine.

**Note:** No air pipe is supplied, as the length will depend on your installation. To adjust the air pressure, pull the cap out (up) and rotate until the gauge reads the correct pressure. Once the pressure is adjusted, push the cap in. **Note:** It is strongly recommended that 90 psi is supplied to the SmartShop II and that the regulator then be set to 85 psi. This will ensure that the machine always has the minimum required air pressure. The input regulator has a moisture trap that must be emptied each day.

**Note:** It is important that the air that is supplied to the machine is clean and dry. The machine will not perform consistently if the air is wet or dirty, as any dirt and moisture will block the valves. Wet, damp or dirty air will damage your machine and cause inconsistent performance.

**Note:** The pneumatic system does not need any type of lubricant. Some types of lubricant can damage the machine and compromise the machine's functions.

Note: During maintenance, always disconnect the air supply.

#### Set-Up Instructions Cont'd:

- 1.) Per Unpacking Instructions make sure remove all protective coating and packaging.
- 2.) Make sure check if machine has all the tooling (kits, etc.) components that were placed in your order.
- 3.) Make sure that the building/shop have appropriate electrical voltage and amperage for machine(s) purchased. \*Electricians and service staff are welcome to contact our Customer Service if they have any questions (Toll Free: 1-800-234-1976).
- 4.) Make sure one has access to the main power source and available and can be pulled to the Electrical Cabinet and all Vacuum Pump(s) for use.
- 5.) All machine(s) must be leveled with the leveling feet installed.

#### **<u>∧</u>WARNING**

Clean Dry Air is vital for the machine(s) performance. Make sure the clean dry air is available & compressed and can be attached to the machine(s).

Prepare adequate supply of materials for practice cutting as well as several 3/4" Medium-Density Fiberboard(MDF) sheets for use as spoil boards (material to be cut and tested on).

Make sure the technician who is to be trained to operate purchased machines, learns the software prior to setup/training.

Should a technician representing Laguna Tools not be able to come to the site and work on the machines due to the lack of preparedness or inoperable equipment per the above and/or beyond Laguna Tools control any expenses incurred will be passed on to the customer.

### **Smart Shop SS2 Syntec Set-Up**

### **Syntec Setup and Running the Machine:**

First home machine click Home, cycle start

To jog go to Main, click jog then click on x, y or z positive or negative depending what direction you want to jog.

#### TTO Set-Up:

(F8) system admin, F3 Param, F5 goto param, type in 3411, enter 0 it will ask for password enter 520. This will set 3411 to 0.

Touch Off Tool, load end mill in the tool 1 position (Laguna Tools Technicians prefer to use the 3/8 compression, but any flat bottom end mill will work for this step.

Main, auto tool, MDI, monitor, mdi input, type in tool number T1, F1 confirm, cycle start.

This will pick up the tool and touch it off to the TTO (Tool Touch-Off) Switch. Once touched off jog the tool to the phenolic and subtract the machine coordinate by the tool length. To get the tool length go to Main, (F3)

Offset/Settings, (F2) Tool Set, Length Geometry for 1 is the Tool Length. The difference from tool length and machine zero is the value for 3411.

TTO switches that are raised above the phenolic will always be a positive number and below the will be a negative. After 3411 setting is entered, you will need to touch off the tool again.

At this time, you can touch off all new tools.

#### **Tool Position Setup:**

SET TOOL LOCATIONS-

SETTING > 520 (passcode) > F5 > 520 (passcode) > OK

MPG Handheld > Jog to Tool Position > Select "Set T#" > Repeat on Tools #2-#8.

### **Spoil Board Setup:**

- 1. Place a the 1.5" Inch Fly Cut Tool Bit in ATC Tool #8.
- 2. Make sure the external shift is set to Z0.
- 3. (F3) offset/settings, external shift set z to 0 (click on the z value so its highlighted then on the blue bar below type in 0 and enter this will set external shift to 0 if it's not already at 0. If it's set to 0 already skip this step.
- 4. Now pick up tool 8 make sure auto tool is off on the main screen.
- 5. Main, MDI, F4 monitor, F3 mdi input, type in tool number T8, F1 confirm, cycle start to pick up the tool.
- 6. Now set your XY 0 origin.
- 7. Jog the tool so it is centered with the front left corner of the MDF and set the P1 G54 position.
- 8. Go to (F3) offset/ settings and set the current machine x, y valve to the P1 G54 x and y.
- 9. If you always use this same origin and it's already set, you can skip this step.
- 10. Touch the fly cutter to the table, jog machine so the bit is near center of the table and lower Z about ½ inch above the spoil board. Turn on vacuum by clicking pump 1 and 2 if you don't have a second pump only turn on pump 1. You will want to bring the dust hood up to see the tool. To do this click the brusher button (When you want to bring the hood back down click it again).
- 11. Now click "MPG" and use the hand-held mpg to bring the z down until it's just touching the MDF Board. Once touching you will enter in the machine z value as the tool length.
- 12. To enter the tool length, you will go to Main, (F3) offset/settings, (F2) tool set,
- 13. Enter in machine Z value to the length h geometry for Tool #8. Once this is set you are ready to run the fly cut program.
- 14. Load fly cut program go to Main, click auto which is at top right corner of the screen, F2 Program, F8 file manager, click on fly cut program, F5 execute, now it's ready to run click cycle start. If the program isn't already loaded to the controller use your USB drive.
- 15. F2 Program, F8 File Manager, F4 File Transfer, F1 File Import
- 16. Click on the fly cut program, F1 copy, << 2 times, click on the file to run "flycut", F5 Execute

- 17. Cycle start to run program.
- 18. Once finished you need to set the external shift Z (external Shift Z is for your spoil board thickness)
- 19. Go to Main, click auto tool, MDI, F4 monitor, F3 mdi input, type in tool number T1, F1 confirm, cycle start this will touch off tool 1.
- 20. Jog Tool 1 and bring the bit down to the spoil board with the vacuum on. Subtract Tool 1 length by the machine Z value. This will be the thickness of your spoil board. This eliminates the need to use a caliper to measure your spoil board thickness and is a really accurate way to set your spoil board thickness.
- 21. Go to (F3) offset/ settings in external shift set Z to this value.

### Running A Program And Copying The File To Run:

- 1. Click "Auto".
- 2. Main, turn on vacuum pumps, start
- 3. (F2) Program, (F8) File Manager, (F4) File Transfer, (F1) File Import.
- 4. Click on the file you want, (F1) copy, << twice, click on the file to run, (F5) Execute.
- 5. Cycle start to run program.

#### **Delete A File:**

1. (F2) program, (F8) file manager, (F3) delete file, click the file again, (F4) delete file.

#### **MDI Command to Move Machine to Zero:**

Main, MDI, F4 monitor, F3 mdi input.

#### G54G0X0Y0

#### 4th-Axis Setup:

Wire the harness power wires to the 4th-Axis Drive wire may already be connected remove them and wire the harness here.



Then wire the sensor to the terminal strip 3 wires 0vdc, 24vdc, and H0. H0 wire will go to I/03.



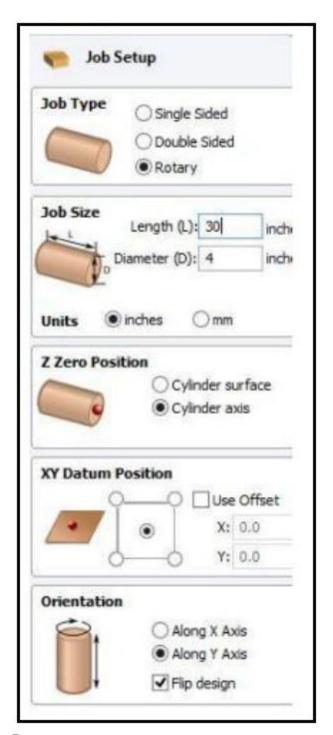
Once completed power up machine and change parameter 24 from 0 to 4 reboot machine and home machine and the 4th axis should be operational.

Write down the external shift Z setting so you can go back after running the 4th axis then set it to 0. V bit will work best make sure it has been touch off then bring the tool to the center of the 4th axis tail stock dead center point. Subtract Tool length by the machine Z value this is what you will enter into the external Z setting.



In aspire or v carve pro setup is really simple the attached picture is for a 4" inch diameter, 30" inch long piece of material. Before moving the head away from the tail stock end note the position of the X jog the head up so you can load your material and mark the center of the 30" inch length this will be your Y position. Jog the Z Up-Load the material and then jog the tool the center mark you just made. The machine X and Y will be your new P1 G54 X and Y value so write down what P1 G54 is so you can change back to this after running the 4th-Axis.

# **Syntec Set-Up Parameters**



### **Parameters**

F8 system admin, F3 Param, F5 goto param Password (520)

### TTO

2841 -X

2842 -Y

## **Max Cutting Feeds**

621 –X

622 -Y

623 –Z

## **Rapid Speeds**

461 -X (800 IPM) (20320 MM)

462 -Y (800 IPM) (20320 MM)

463 –Z (150 IPM) (3810 MM)

#### Y-Safe

3410

### Max RPM

3460 (240000 RPM)

## **Change to Inches**

[MAINTAIN]

[SYSTEM SETTINGS]

Change to '1'

## Rotary

24 (0 off) (4 on)

Must be Hooked Up to Enable 'Home' Sensor

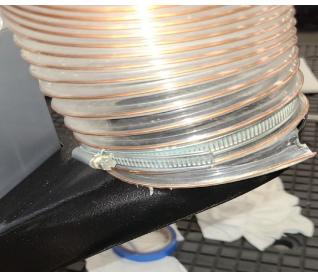
Must reboot.

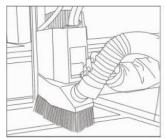
# **VFD Parameters**

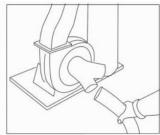
Number		Comment
00-02	9	
00-03	1	
00-20	1	
00-21	1	
00-23	1	
00-32	0	
1-00	800	
1-01	800	
01-02	220	
01-12	10	
1-13	10	
2-16	34	
2-17	3	
5-00	2	
05-01	25	
05-02	8	
05-03	17999	
5-04	4	
5-05	10	
06-06	4	
6-07	74	
6-08	6	
7-01	20	
7-02	0	
07-03	1	
09-00	1	
9-01	19.2kbps	
09-04	12	

## **Installing the Dust Hose**

- 1.) Take out the dust collector and install it according to the instruction. Balance it on the floor. Fit the dust shroud to thetwo air cylinder rods and clamp in position with the clamping nuts.
- 2.) Fit a 4-inch (not supplied) dust hose to the dust shroud and secure with the clamp. Ensure that it is tight; it is very inconvenient to have it fall off during production.





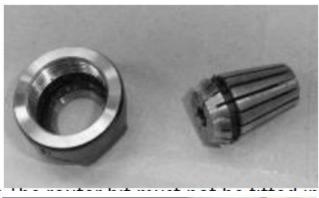


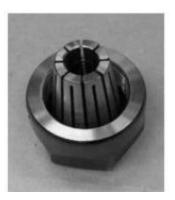
- 3.) The head of the machine will move across the complete table, and the dust hose will follow the head. If there is insufficient slack, the hose may break or damage the dust shroud. It is suggested that the hose be suspended from the ceiling of the shop with sufficient slack so that it will not restrict movement. It will also be out of the way and not causing a trip hazard.
- 4.) Connect one end of the hose to the dust collector and the other to the machine, as indicated below.
- 5.) Connect cable to the dust collector.
- 6.) Connect the cable to the power supply.
- 7.) Power on the machine to see if the motor rotates CW. If not, swap any two of the live wires.

## Installing the Router Bit

Installing the Router Bit in the Tool Holder **Caution:**Before changing or fitting the router bit, always **disconnect the power to the machine.** 

- 1) Select a router bit and its relevant collet.
- 2) Fit the collet into the spindle nut. Press the collet into the spindle nut until it snaps into place.







**Note:** The router bit must not be fitted into the collet until the collet has been fitted into the spindle nut. With the router bit fitted into the collet, the collet can not compress and "snap" into the spindle nut. The face of the collet and the face of the spindlenut will be close to flush.

**Note:** To remove the collet, hold the spindle nut and press the collet on the side. The collet will compress and pop out. Do not tryto remove the collet while a cutter is fitted, as the collet will not compress and pop out.

3) Fit the spindle nut and collet assembly onto the tool holder spindle thread by hand. Press the bit into the collet. Note that the flute of the router bit must not be inside the collet and should be a minimum of1/16" outside the collet. Hold the toolholder with the supplied wrench and tighten the collet with a second wrench. Do not over tighten.

**Note:** Use this process to install each of the router bits into the tool holders, being careful to use the correct collet size for each router bit. Note: Keep the collets clean and blow all dust out of the slots. Fine dust accumulates and may affect the clamping action.

## **Operation (Tutorials)**

## Read carefully before operating the machine:

1)Keep the working area clean and be sure adequate lighting is available.

- 2)Do not wear loose clothing, gloves, bracelets, necklaces or ornaments. Wear face, eye, respiratory and body protection devices as indicated for the operation or environment.
- 3)Be sure that the power is disconnected from the machine before tools are serviced or an attachment is to be fitted or removed.
  - 4) Never leave the machine with the power on.
  - 5) Do not use dull, gummy or cracked cutting tools.
  - 6) Be sure that the keys and adjusting wrenches have been removed and all the nuts and bolts are secured.

### **Software Operation:**

1.) About Syntec Folder: Please do not delete Disk "C" and Network in the : "D" Disk of the computer. Disk "C" Folder: System Interface File, Connect Controller, Modify Parameter Setting.

Network Folder: The process is stored here.

### Main Interface



#### **Processing Speed Adjustment:**

Press G1-or G1+to reduce and increase the processing speed.



#### **Idle Speed Adjustment:**

Press G0-or G0+to decrease and increase the Speed Spindle speed adjustment.



Press SP-or SP+to decrease and increase the rotation speed of the spindle.



RAPID: Fast moving machine X+Y+Z+B+ X-Y-Z-B-: In "JOG" mode, move the machine manually.





### **Button Overview:**



Button	Function
OVER TRAVEL	Cancel hardware overdrive alarm.
AUTO TOOL	Tool length is measured using an Auto Tool Sensor.
SPINDLE PREHEAT:	Preheat the spindle, if you do not use the machine for a long time, you need to use this function.
VACUUM1 OFF	Vacuum Pump1 On.
VACUUM2 OFF	Vacuum Pump2 On.
SUCT	Table vacuum on.

Button	Function	
SP. CW	Spindle Clockwise.	
SP. STOP:	Spindle Stop.	
BRUSHER	Spindle Brush Up and Down	
"O" PIN DOWN	Under positioning cylinder down.	

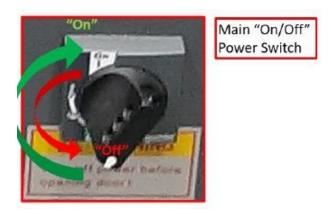
# **Tool Management Interface**



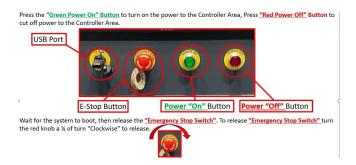
**Auto Tool Set** 

# **Machine Operation Instructions**

### **How to Power On:**



Release the emergency stop button and switch on the PC, and the system enters the main interface after the auto check.



### **How to Power Off:**

1.) Before machine stops, first press the "Emergency Stop Button.



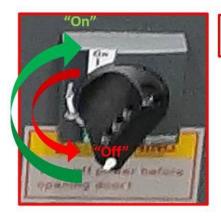
2.) Exit the System Operation Interface.



3.) Shut Down the Personal Computer (PC) "Off".



4.) Turn the knob on electric cabinet door Counter-Clockwise.



Main "On/Off" Power Switch

## **Emergency Stop:**

In case of safety emergency, press the "Emergency Stop Button/Switch" and all the machine parts except for the controller are disconnected from the power supply to ensure personal and machine safety. "Emergency Stop Button/Switch"



### **Auto Go Home:**

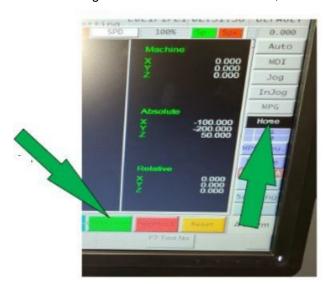
After the system self check is complete, it will direct you to the main screen. Release the "Emergency Stop Switch" (1/4 Turn Clockwise to the Right) .

The system will prompt you to go home.

All Axis **MUST**be homed before you start to operate the machine.

### Methods:

Click on the "Auto Go Home Button" and "Cycle Start Button", the Z Axis will go home. After Z Axis is homed, X and Y axes will begin.



JOG

Operator can jog the machine in the desired direction. Methods: Click on the "Manual Jog Button" to enter. Control the movement with axes directional keys-- $\llbracket X+,X-,Y+,Y-,Z+,Z- \rrbracket$ . Caution: Click on the "G0-" key to reduce the speed before entering this mode. If it is safe, you can use the "G0+" button to increase the speed.

#### Idle Speed Adjustment:

Press G0-or G0+to decrease and increase the Speed Spindle speed adjustment.





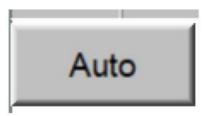
## MPG Handwheel

Operator can move the axes by spinning the "MPG Handwheel".

Methods: Select the "MPG MODE" Define the axis, direction and speed.

- i.) Spin the handwheel in the Clockwise (CW) direction, the machine will move in the positive direction.
- ii.) Spin in the Counter-Clockwise (CCW) direction, the machine will move in the negative direction.

The speed is determined by the selected speed value.



# Auto Mode

Operator can process a job under this mode. The machine will automatically run the NC program.

Methods: Select the program file you wish to process. Set the job origin and tool length offset value, then press "Auto Mode Button". This mode is only available after all axes have been homed.

Press the "Auto Mode Button" and the system will begin process the selected file.

#### **Buttons:**

<u>Button</u>	<u>Function</u>
MDI	This mode allows the operator to write one
	block and execute that block
Vacamp1	When you press this button, the vacuum will be turned on.
Vacamp2	Press once, the vacuum pump will be turned on. Press again, the pump will be turned off.
Pin	Press once, the pop-up pins will rise. Press again, the pins will go down.

<u>Button</u>	<u>Function</u>
Tools AutoTool	Press to access the Tool Screen.
Main	Press to go to the main screen.
Reset	Press to Reset.
	Under Auto and MDI Modes, press once to start processing the program
Feedfeld	Press to "Freehold Button" to pause the process.
external.	If you wish to restart, press "Cycle Start Button "for"Program Start" to restart.
Sp. Stop	Under manual continuous mode, manual jog mode and hand wheel mode, pressing this button can stop the spindle.
Sp. CW	Press to make the spindle spin in the Clockwise (CW) direction under manual continuous, manual jog and hand wheel modes.

**↑** CAUTION \*\*All axis must be homed after power is "On".\*\*

As tool setting and job coordinate setting must be done based on the mechanical reference point, after CNC is switched on, reference point must be confirmed with all axes going back "Home"

The Syntec Controller can't be started by auto NC program.

- 1.) Release the emergency switch. The system will display "READY".
- 2. Press the "HOME" softkey. Press the "Cycle start" softkey.

Note: "**HOME**" Z axis before other X, Y Axis to avoid interference.

- 3.) Note: The homing direction can be set in the CNC parameters.
- 4.) Note: The homing function homes all three axes together.
- 5.) Note: After homing, the mechanical coordinates are all "0".
- 6.) Note: The software limit switches of the machine are not enabled until all axis are reset.

<u>△WARNING</u> \*\*Do not engage the machine in movement too fast until the axis are reset.\*\*

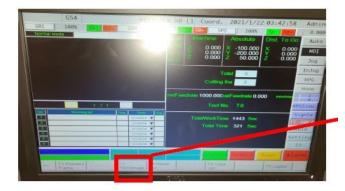


# **Part Program Selection**

### Select "F2 PROGRAM"









# Navagating the

- 1.) Select "F1" Operator Panel.
- 2.) Select Program , Select "F2" Program3.) Then Select "F3" File Manager.

Select the processing file, to "F1 Execute".

4.) Select File for Execution.



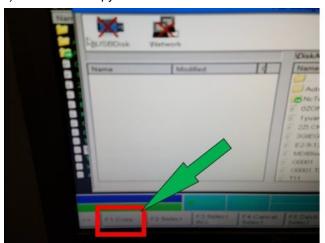
5.) Select F2-Copy File for Execution.



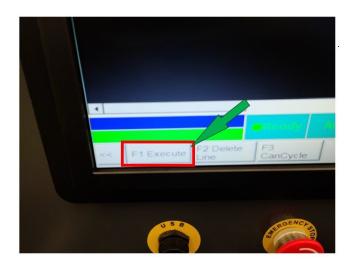
6.) Select "F1"-File Import for Execution.



7.) Select "F1"-Copy File for Execution.



8.) Select "**F1-Execute**"-To Execute File.



### **Job Origin Preset**

### Job Origin Preset

Click on the "F3 OFFSET/SETTING" softkey on the bottom menu of the main interface. And we use G54 as the "0" Point of Processing.



### And we use G54 as the "0" Point of Processing:



Press the "**Hand Wheel Mode**" to control and move the X/Y/Z axis to material processing surface, (For irregular materials, users need to set a center, and the workpiece origin should be benchmarked on the zero surface on which the tool is aligned with the workpiece).

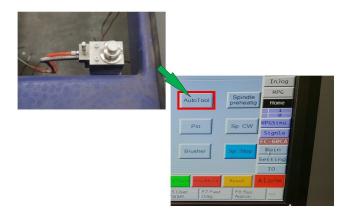
ENTER, When the yellow cursor has been moved to X, press FI on the panel (Latch Machine cord), and the following note will be shown:

Choose "Yes", and press "Enter" on the panel.



(Set Workpiece) Choose F5 (Set Workpiece).

### Spindle tool length measurement using auto tool sensor



Press the "AUTO TOOL Button" to enter the TOOL number to be measured in MDI mode.



Click F1"OK" and the machine will automatically measure the tool length.

After the measurement is completed, the machine will automatically enter the tool length into the system.



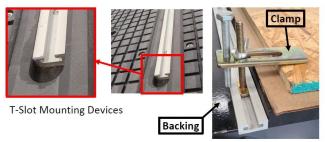
F3 OFFSET/SETTING F2 TOOL SET

# Vacuum Table T-Slots & Automatic Tool Changer (ATC)

The vacuum table has T-slot mounting devices incorporated into the tables to enable fixtures and material blanks to be clamped directly to the table.

Clamps are provided, but the table must be protected with a backer when using jacking bolts. If the jacking bolts come in contact with the composite or aluminum of the table, the materials could be damaged. The backer should be as large as possible to spread the load on the machine table.



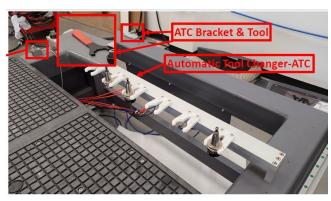


T-Slot Clamps

### **Automatic Tool Changer (ATC)**

The Automatic Tool Changer consists of a group of tool holder grippers mounted to a rigid bar. The machine control knows the location of each of the grippers and will load and unload tools automatically as required by the program.





**Tool Touch Off Switch-TTO** 

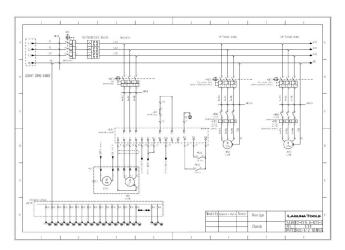
Subject: Automatic tool changing CNC maintenance overview.

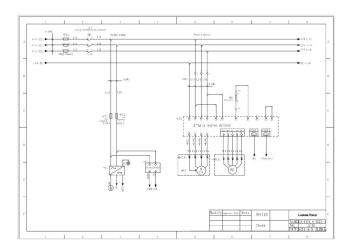
- 1.) Frame Rails and Oiling System.
- 2.) Axis Drive Points.
- 3.) Tool Holders and Spindle Points.
- 4.) Electrical Points.
- 5.) Vacuum System Points.
- 6.) Pneumatic System Points.

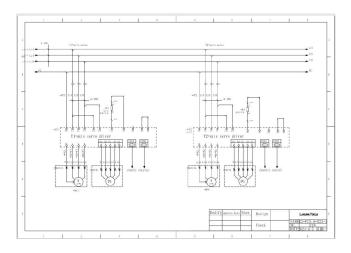
**NOTE:** Intervals are based on optimal shop conditions. If operating conditions are extreme, then the intervals should be decreased.

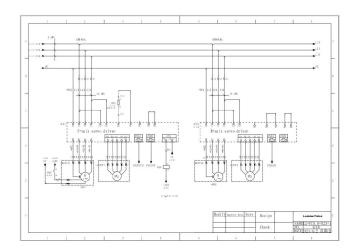
**ONLY**trained and qualified personnel should attempt the quarterly, and yearly procedures. Contact Laguna if you would like a P.M. preformed by our technicians.

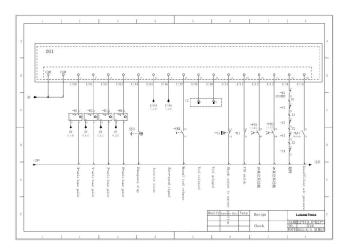
# **Electrical Diagrams**

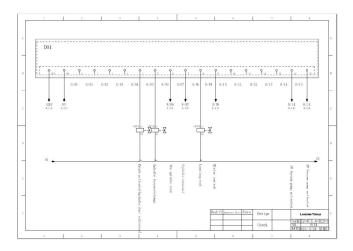


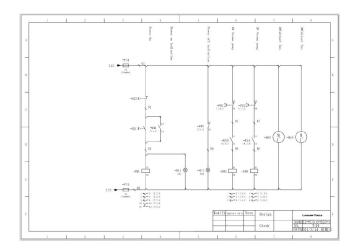


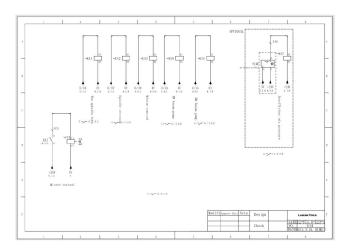


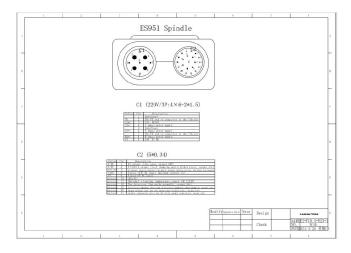


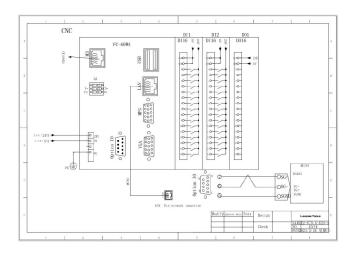


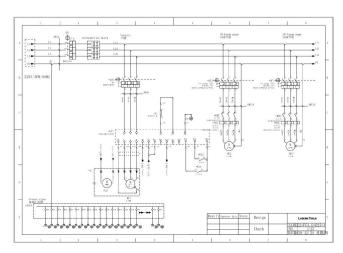


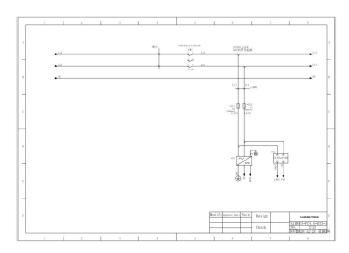


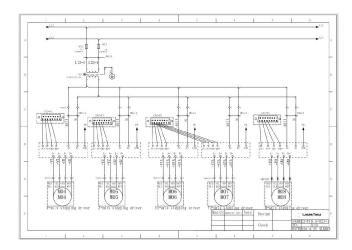


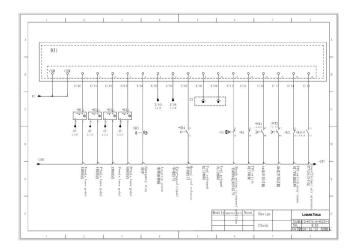


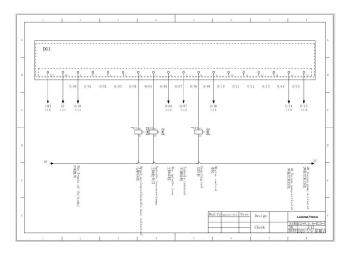


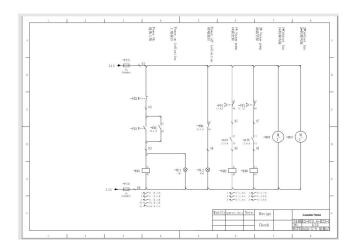


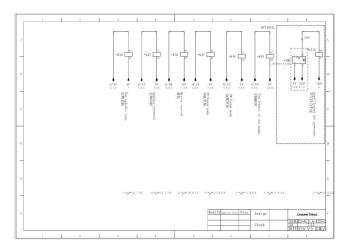


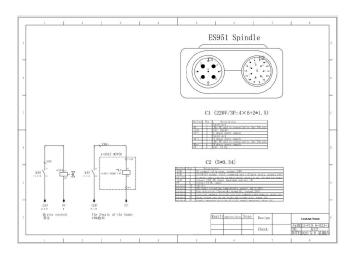


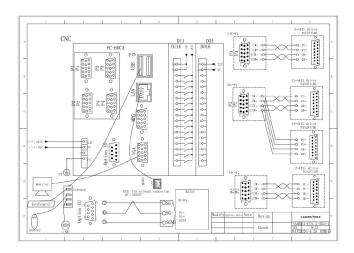


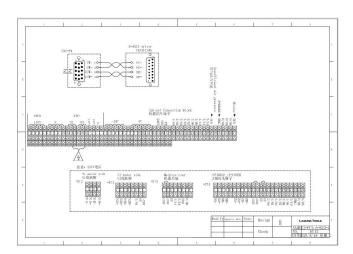


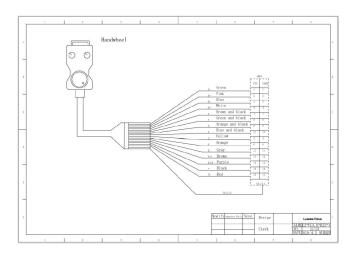


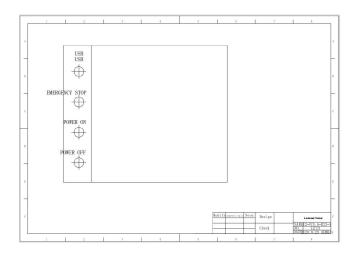


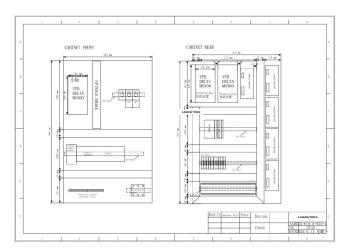












# Vacuum Tables & Spoil Boards

The more effective the vacuum table setup, the more secure the parts will be held in place. Follow the instructions below to obtain optimum results. The vacuum table has six (6) zones that can be used to configure the vacuum supply depending on the type of application.



The table has vacuum ports for each zone that extract the air and generate the vacuum. The table also has grooves to ensure that the air is extracted evenly across the zones. Each zone is controlled by a valve located at the front of the machine.



These Valves Controls the six "6" Zones.

### **Spoil Boards:**

Spoil Board Material and Precautions For machining parts from panel materials (cabinets, fixtures, case goods, etc.) a technology referred to as "Flow-Through" fixturing is employed.

A sheet of porous material (usually MDF [Medium-Density Fiberboard]) is placed on top of the vacuum table.



The panel material that is to be machined is actually placed on top of the MDF, and the vacuum passes through the MDF (Medium-Density Fiberboard) and holds the panel material down as it is machined.

\*\*\*Great care should be taken when machining parts free to limit the extension of the tool into the spoil board materials.

The purpose is to limit vacuum infiltration through grooves in the spoil board. This also allows the processing of various nests without any setup time on the machine.

This technology is the basis for Nested-Based Manufacturing (NBM)-Nested-based manufacturing refers to a system used to efficiently produce groups of rectangular and non-symmetrical parts from flat material, such as composite and solid wood panels or plastic sheets. The components are "Nested" together on the material (see the photo below), which means they are positioned in a pattern that achieves the best possible material utilization.



### **Functions of the Spoil Board:**

- 1) To protect the vacuum table from damage. The cutter extends only a few thousandths of an inch past the material thickness. Without the spoil board, the cutters could damage the surface of the vacuum table.
- 2) To transfer the vacuum from the table to the job. This means that the spoil board has to be porous to allow air flow to the panel material. Low cost MDF (Medium-Density Fiberboard) has proven to be a very good material for this purpose.
- 3) To provide a "Zero Setup" environment for processing panel products.

### **Spoil Board Preparation:**

When MDF is sourced for the spoil board, it should be (>) greater than 3/4" of an inch.

Contrary to what might seem logical, the thicker the MDF the better the suction that is created. "Flow-Through" fixturing maintains a careful balance between air flow through the MDF and the infiltration that occurs as the kerfs (GroovesorNotchesmadebyacuttingtool) are machined.

\*\*\*It is not recommended that the spoil board material be is thicker than 1 inch\*\*\*.

The MDF manufacturing process causes the top and bottom surfaces of the material to be compressed. It is necessary, therefore, to remove the compacted top and bottom surfaces.

This process is termed "fly-cutting" and requires the removal of approximately 0.060" from each surface. This process also ensures that the machining plane and spoil board surface are parallel.

The spoil board (MDF) edges are also very porous, and sealing them can improve the part holding ability.

\*\*\***Hard Candle Wax**-is an excellent product for sealing the spoil board edges because it contains no water and is very easy to apply\*\*\*.

**Never use a water-based product** to seal the edges of the board, as this will make the board expand and become unsuitable for use as a spoil board.

Even some glue products contain water and can affect the edges of the spoil board.

**Note:** Do not confuse flatness with bow. If the board is bowed, the vacuum may not pull the board flat on the table. Never try to use a bowed MDF panel as a spoil board.

#### Use the following Procedure for preparing the Spoil Board:

- 1)Cut the spoil board to the size of the table of the machine, if necessary.
- 2) Apply gasketing (The action of fitting or sealing with a gasket)to the outermost vacuum grooves on the table
- 3) Make sure that the table is clean and free from sawdust and dirt.
- 4) Place the spoil board on the vacuum table, being careful not to displace the vacuum gasketing.
- 5) "Turn On" the vacuum pump and check for leaks.
- 6) Fly cut the surface of the spoil board, removing approximately 0.060 lnch" to ensure that the compressed surface of the material is removed.
- 7) Once the material surface is machined, "**Turn Off**" the vacuum pump, turn the spoil board over and repeat the process for the other side. (\*\*\*Remember to ensure that the table and spoil board are clean.\*\*\*)

Spoil Board Use Each time a new job is machined, there may be shallow cuts into the spoil board in the areas that the cutter passes through the material.

Prior to placing a sheet of material on the spoil board, clean with a hand-held blower or vacuum cleaner. Dirt under the material will reduce the vacuum, and in extreme cases, parts may move during the machining process. In general, keeping everything clean is the key to achieving good, repeatable results.

### **Precautions Regarding Spoil Boards:**

The spoil board is porous and will absorb moisture. As moisture is absorbed, the dimensions of the board will change. In general, this will not be a problem, as the changes from day to day are not that excessive and will typically be over the complete board.

Thoro ara	howover	exceptions:
mere are.	HOWEVEL.	exceptions.

- 1) It is a good practice to keep material on the top surface of the spoil board overnight to prevent warpage due to uneven moisture absorption by the material.
- 2) Once a spoil board has been used and has kerf cuts that resulted from machining parts, it is a good idea to fly cut the surface again. This time it should only be necessary to remove 0.015" of material since the only purpose is to produce a smooth, flat surface, and that amount should remove the machining marks.
- 3) The spoil board must cover the complete table and sit on the flats around the table. If the spoil board does not cover all the vacuum slots, the vacuum may be lost or not exist and the panel material will not be pulled down onto the spoil board effectively.

### Manual Tool Release

The tool holder can be released from the spindle manually by pressing the "Green Manual Release Button" near the Electro-Spindle.

Note. When the "Green Manual Release Button" is pressed, the clamping is released and the tool will fall out.

Place your hand so that the tool holder (not the cutter) is supported.

To manually insert a **Tool Holder**, hold the tool holder in the spindle taper while holding the green manual release button.

Once the green manual release button is released, the tool holder will be pulled up into the spindle hole and clamped in position. \*\*\*Please note that a small amount of air escapes from the spindle nose. This is used to blow any dust out of the spindle taper and is normal.

Note: Keep the tool holders clean, lubricated with Teflon.

Note: The spindle taper is susceptible to rust and must be kept clean and lubricated with a Teflon lubricant.



# Tool Holder & Tool Holder Bracket



# "Green Manual Release Button"



**Straight Router Bits:**These are the standard router bits that are commonly used with handheld routers and are readily available at home centers. They will work but will generally not produce the edge finishes that are available with the spiral designed router bits.







**Up Shear Router Bits**: These bits have flutes that are spiraled upward (a standard twist drill is an example of this type of bit). This bit design removes the chips from the kerf but has a tendency to chip the top surface, especially on veneers or melamine surfaces.

**Ball Nose Router Bits:** are a variation of the up shear bit design but have radiuses on the ends. These bits are typically used for 3D surfacing applications.



Ball Nose End Mills

**Down Shear Router Bits:** These bits are similar to the up shear but with an opposite spiral that actually tends to pack the chips into the kerf. These bits prevent chipping the material surface, especially with veneers or melamine surfaces, and are an excellent choice for machining dadoes and other joinery that do not extend completely through the material.

**Combination (Compression) Router Bits:** These bits combine the advantages of both up shear and down shear designs. The top section of the tool is down shear to prevent chipping the top surface of the material, and the lower part of the bit is up shear to prevent chipping the bottom surface of the material.

**Compression Router Bits:** are the preferred configuration for machining veneered plywood as well as melamine-surfaced product. A variation of the bit is called the "Mortising Compression" router bit. With this bit, the Up Shear portion of the bit is less than  $\frac{1}{4}$ " in length so that the bit can be used on  $\frac{1}{4}$ " veneered plywood and for dados.

**Form Router Bits:** Form Router Bits typically are available in standard profiles such as round over, ogee, cove, etc. Router bits that have a shape associated with them would be classified with this group.



# Service, Maintenance, & Troubleshooting

# **Troubleshooting Syntec SS2:**

Alarm ID	OP-001	Alarm Title	Invalid axis board setting, IO will not work		
Description	When the controller does not detect the hardware interrupt signal, i send an alarm (old axis card: one interpolation time interval send signal. new axis card: 0.5ms sends one signal)				
Possible Cause	Controller parameters are set wrong     CPU BIOS sets wrong     Axis card error or jump setting error     Axis card and ISA SLOT have poor contact or axis card represses ISA SLOT				
Solution	Check whether setting parameter Pr1 of the controller is suitathe corresponding hardware specifications (see application handbook-parameter explanation)     Check whether IRQ11 setting of BIOS is Legacy ISA     Check jump of axis card     Check whether discontinuity signal ISR of the first card is disconnection (other axis cards must open).     Replacement the Axis card to avoid the poor contact between card and ISA slot				

Alarm ID	OP-002	Alarm Title	Parameter storage access failure, system halt
Description	card with PARAM.I booting, if damaged,	file path C:\C LKN, saved in controller car system will	I parameter is PARAM.DAT, saved in the first CF NC\APP. The backup file of system parameter is the first CF card with file path C:\CNC\LKN. As not find out two above files or two above files are rebuild those files. However, if system cannot it will send alarm to user
Possible Cause	The first C	CF card error	
Solution	PC ar C:\Cl	nd repair CF on NC\APP(file race the first C	ard out, insert into CF card reader, connect to the card on PC, after that recopy backup parameters to name of backup parameter is PARAM.LKN)  F card. (Please note that the first CF card needs and CNC kernel software)

Alarm ID	OP-003	Alarm Title	Parameter storage access failure, system halt
Description	C:\CNC\U REGISTE file of r C:\CNC\M three abo	JSER. The RYLKN, save machining da MIR. As booti we files are	ining data is REGISTRY.DAT, saved with file path first backup file of machining data is dwith file path C:\CNC\LKN. The second backup ta is REGISTRY.MIR, saved with file path ng, if controller cannot find out three above files or damaged, system will rebuild those three files, not rebuild those three files, it will send alarm to
Possible Cause	The secon	nd CF card err	or
- 6	Once this	case hannens	s, back up the machining data of user to a new CF

Alarm ID	OP-004	Alarm Title	Machining data loss, re-calibrate before machining		
Description	Once booted, controller will re-load the system registry file of the I shutdown into memory. After loading, if controller discovers the I shutdown state is busy or if the register file and the first backup file damaged, one alarm will be sent to the user.  The name of registry file is REGISTRY.DAT, saved with file path D:\CNC\USER. The first backup registry file is REGISTRY. MIR, save with file path D:\CNC\ MIR. The second backup file of registry is REGISTRY. LKN, saved with file path D:\CNC\ LKN				
Possible Cause	Shut down controller or power when controller state is busy     The second CF card error     File REGISTRY.DAT is damaged				
Solution		case happens, eplace the sec	back up the machining data of user to new CF card cond CF card		

Alarm ID	OP-005	Alarm Title	I/O transmission error	
Description	When PIO	5 of Watch D	log fails, the system will display warning	
Possible Cause	1. Moth 2. PIO5	erboard is too error	o hot	
	Motherboard error     Ground wire of controller is interfered			
Solution	1.	ck whether the	e fan turns correctly	
Solution	Change the motherboard     Check whether the machine touches the ground properly.			

Alarm ID	OP-006	Alarm Title	Permanent storage data CRC check failure re-calibrate before machining
Description	When the	hardware of	PIO5 has errors, alarm will appear
Possible cause	PIO5 error     Fram CRC error     Fram doesn't initialize		
solution	For the first and the second reason, change PIO5     For the third reason, using software version which is from 10.112.95 or 10.114.29 on		

Alarm ID	OP-007	Alarm title	Low memory, memory space is less than 1M	
Description	If capacity	y of system m	nemory is less than 1M, alarm will appear	
Possible cause			texts and pictures when they design CE human- make the capacity of system memory less than 1M	
Solution	Human-machine interface of controller should simplify components, only design effective variables and scripts to avoid the low memory phenomenon.			

Alarm ID	OP-008	Alarm title	Fatal low memory, memory space is less than 100K			
Description	System n	System memory is less than 100k.				
Possible cause		Users design too many texts and pictures when they design CE human-machine interface, and make the capacity of system memory less than 100k.				
Solution	Human-machine interface of controller should simplify components, only design effective variables and scripts to avoid the low memory phenomenon.					

Alarm ID	OP-009	Alarm title	The number of interpolation loss times is bigger than 100
Description	Interpolation	tion delay: Ax polation time,	54 (Interpolation delay times) more than 100. is card doesn't send the command calculated by the system will ignore the interpolation value to and amount which causes outflow command
Possible cause	Axis card is damaged.     System resource is exhausted.     The setting of interpolation time interval (Pr3203) is too small.		
Solution	Replace the hardware of axis card.     Replace a better motherboard.     Set longer interpolation time interval.		

Alarm ID	OP-010	Alarm title	Axis Group setting error		
Description	When parameters of axis group in CNC are not set correctly, cowill send alarm.				
Possible cause	Parameter setting error  Ex: Assume that the machine exists XYZ axes, each associated axis group is set as follows:  Pr701 = Pr702 = Pr703 = 5(XYZ axes belong to the 1 <sup>st</sup> group + 3 <sup>rd</sup> group)  Suppose that Pr731 = 3(axis groups in CNC are the 1 <sup>st</sup> spindle group, the 2 <sup>nd</sup> spindle group, and the 3 <sup>rd</sup> spindle group). It means that the 2 <sup>nd</sup> axis group is not covered by any axes, and one alarm will appear.				
Solution	Please check the matching between Pr701 ~ Pr716 and Pr731.				

Alarm ID	OP-012	Alarm title	CF card set by Pr3219 is error, check CF card or system setting value
Description	second C		if we set Pr3219 equal to 3 and do not insert the ata), controller will send alarm to avoid error of cistry.dat.
Possible cause	CF card.		sn't have the 2 <sup>nd</sup> CF card or cannot read the 2 <sup>nd</sup> two CF cards, but only one CF card is partition
Solution	reading e	rror.	the 2 <sup>nd</sup> CF card exists or there is CF card  d to the default state, have two partition states.  qual to 0 to use C: all

Alarm ID	OP-013	Alarm title	Software version and model can't driver hardware, call your vender!	
Description	(ex: 10.1	15.x etc.). V	10A) does not support the software version When axis card cannot send command to the t machining, this alarm will appear.	
Possible cause	The hardware doesn't support software version set on the controller, ex: EZ milling setups 10.114 software version.     In the controller, the motherboard, or IO card and CF card are replaced, and software version doesn't support new hardware.			
Solution	"EZ2/3 2. Ask S' proble	ses 9.242 softv 3/4 upgrade 10 YNTEC for the m.	version that supports the machine model, ex: EZ ware version. Or open the option, ex: option1  OA software function".  e password to solve the incompatible hardware  sn't have this error.	

Alarm ID	OP-014	Alarm title	WinCE option not enabled, call your vender!	
Description			rrsion of controller, WinCE options are not not send command from controller to machine	
Possible cause	The Option 2 of controller "Controller upgrades WinCE system" is no opened.			
0.40.00000-0.0000	E301 1000	stall Dos vers sk SYNTEC f	ion. for the password, and open Option 2 "Controller	
Solution	upgrades	WinCE system	m".	
	3. S	uper controlle	r doesn't have this error.	

Alarm ID	OP-020	Alarm title	NC file name is different with backup name, re- calibrate before machining	
Description	file name	also is availa ent, this alarm	f controller is saved in registry.dat, one backup ble at Fram. After booting, if these two data are will appear and machining file name will be	
Possible			hat writing registry.dat and registry.mir are leads to two file names inconsistent.	
cause	Install or replace registry.dat file.     Rename file name when downloading file			
	10.000	F card disk.		
Solution	Reselect machining file name.     Check whether machining data setting is correct.			
	4. Reboot.			

Alarm ID	OP-021	Alarm title	Use last known data, re-calibrate before machining	
Description	Machining data of controller is stored in registry.dat, and has two backup files: registry.mir and registry.lkn. If both registry.dat and registry.mir have errors. When system uses registry.lkn, an alarm appear and remove machining file name.			
Possible cause	CF card is damaged, so registry.dat and registry.mir files are also damaged.			
Solution	Scan CF card disk.     Try setting again or check whether machining data setting is correct     Reboot.			

Alarm ID	OP-022	Alarm title	Machine data rebuild, re-calibrate before machining
Description			't have registry.dat, backup files registry.mir and o rebuild file, an alarm will appear.
Possible cause	1. Replace	e CF card.	
Solution	1. Reset r	nachining data	a. 2. Reboot

Alarm ID	OP-023	Alarm title	Power break in machining, re-calibrate before machining
Description	and it wil	l be removed	Throller will set up machining flag in registry.dat when machining comebacks to ready status. chining flag is not removed, this alarm will
Possible cause	Discontir	nue power in n	machining process.
Solution	Scan CF card disk.     Check whether machining data setting is correct.     Reboot.		

Alarm ID	OP-024	Alarm title	Machine data file write fail, re-calibrate before machining
Description			ontroller, if the last writing registry.dat or ccessful, this alarm will appear.
Possible cause	2. Re	stem file can	nged. registry.mir files are set read-only. not handle system resource, lead to writing file
Solution	Scan CF card.     Check whether machining setting is correct.     Reboot.		

Alarm ID	OP-025	Alarm title	Machine data file write fail many times, re-calibrate
			before machining
Description	our house are selected		controller, if the total times of writing registry.dat accessfully exceed 100 times, this alarm will
Possible cause	processed 2. R 3. S	d soon. egistry.dat or	e damaged seriously, and CF card should be registry.mir file is set to read-only.
Solution	1. Scan C 2. Check 3. Reboo	whether mach	nining setting is correct.

Alarm ID	OP-026	Alarm title	Machine data file fault error, re-calibrate before machining and do scandisk
Description			controller, if the total times of writing registry.dat accessfully exceed 100 times, this alarm will
Possible cause	processed 2. R 3. S	d soon. egistry.dat or	e damaged seriously, and CF card should be registry.mir file is set to read-only. not handle system resource well, lead to writing
Solution	1. Scan C 2. Check 3. Reboo	whether mach	nining setting is correct.

Alarm ID	MOT-027	Alarm Title	program error in PLC axis	
Description	Grammar o	of PLC axis p	rogram error	
Possible cause	Grammar o	of PLC axis p	rogram error	
Solution	Check gran	nmar of PLC	axis program	

Alarm ID	MOT-028	Alarm Title	System memory too low
Description			LC axis switch, free memory of system is too low, an alert warning
Possible Cause	The machi	ning progran	n switches to PLC axis
Solution	Contact ma	achinery mar	nufacturers

MOT-029	Alarm Title	Miss index in homing			
	When searching home, if motor does not find out motor index signal a leaving home DOG more than 5 pitches, controller will send this alarm				
<ol> <li>Can't read the index signal.</li> <li>The setting of homing 2<sup>nd</sup> travel feedrate is too fast.</li> <li>The setting of motor reduction ratio is too big</li> <li>The distance between index signal and HomeDog is more than 5 pitches</li> </ol>					
Check motor index wire connecting; observe diagnostic screen 48(X), 49(Y), 50(Z) to check whether index signal is read. If no, please check whether connecting wire is correct.      Reduce setting value of the homing 2 <sup>nd</sup> travel federate (Parameter 841–843)					
When searching home, machine will use the velocity setting value of first stage to move to home DOG, and stop. After that machine more backward with velocity of the second stage. After leaving home DOG move backward, it start to search the nearest motor index signal. In second stage, controller will calculate according to resolution of encode if controller leaves home DOG more than 5 pitches and can not find the index signal. Controller will send alarm.					
	When sear leaving ho  1. Can't leaving ho  2. The s  3. The s  4. The c pitche  1. Chec 48(X pleas  2. Redu 841~  When sear first stage backward move backs and move backs at If controll If controll If	When searching home, leaving home DOG mo  1. Can't read the inde 2. The setting of hon 3. The setting of mot 4. The distance between pitches  1. Check motor indeed 48(X), 49(Y), 50(2) please check whet 2. Reduce setting value 841–843)  When searching home, first stage to move to backward with velocity move backward, it stars second stage, controller If controller leaves home.			

Alarm ID	MOT-030	Alarm Title	Zero speed timeout in homing
Description	When mot this alarm.		omeDog, if motor cannot stop, controller will send
Possible Cause			in is not good, so it makes motor vibrating causes resonance phenomenon.
Solution	2. Start	the resonance	a loop gain and velocity loop gain setting of driver e frequency inhibition ability of driver or manufacturers for help.
More description	first stage: that mach leaving ho index sign velocity to 9(Y), 10(2)	to move to he ine moves be ome DOG to a al. At the first o stop. After Z)-error regis	machine will use the velocity setting value of the me DOG, and stop once it meets home DOG. After ackward with velocity of the second stage. After nove backward, it start to search the nearest motor t stage to find the home DOG, motor will decrease 0.1 second command stops, if system data 8(X) ter receives values bigger than zero speed check controller will send alarm.

Alarm ID	MOT-031	Alarm Title	Static dual feedback error exceed	
Description	After the controller stops sending the motion command, during the time set by parameter Pr3805, the system will check whether dual feedback error exceeds allowed limit set by parameter Pr1421–1440. If yes, controller will send alarm.			
	1. Moto	r encoder is i	nterfered	
	<ol> <li>2<sup>nd</sup> er</li> </ol>	ncoder loop is	sinterfered	
Possible	3. Servo	controller is	disconnected.	
Cause	Mechanism has problem			
	5. Serve	is damaged		
	6. The 2	end resolution	loop is set wrong	

	5. Contact machinery manufacturers for help
Solution	Check whether the connection between the motor and encoder is firm     Remove high-power electromagnetic devices     Check whether the machine table can move smoothly     Replace the servo driver

Alarm ID	MOT-032	Alarm Title	(Z axis) Following spindle error exceed
Description	cause spin	dle reversal v nmand. If Z a	ng diagram of spindle feedback is inverted, it will when tapping is started. This phenomenon will raise xis command is raised more than 1 pitch, controller
Possible Cause	Wiring dia	agram of spin	dle feedback is inverted
Solution	trans	former sends	tion feedback value A+ and A- which frequency to the controller s related to frequency transformer

Alarm ID	MOT-033	Alarm Title	Absolute encoder read error
Description			coder, if the communication between the controller controller will send this alarm immediately.
Possible Cause	2. The c	d off	power on on line between the controller and driver come is fer board is damaged
Solution	2. Chec	k the connect	supply of driver ing wire olute transfer board

Alarm ID	MOT-034	Alarm Title	not set home position, Absolute encoder will not work		
Description			encoder, if the initial value of encoder set in controller will send this alarm immediately.		
Possible Cause	Do not use	e C25–to set i	the home of machine		
'Solution	Use C25~	to set home n	nachine		
More	Absolute encoder to search home				
description	Step 1: Move axes to the desired origin.				
	Step 2: Trigger C25 ~ (fill R38 value with X-axis mechanical coordinate)				
	controller automatically records the initial value A of encoder from				
	driver.				
	Step 3: Next time when controller is rebooted and communicates successfully with encoder, regardless of positions of axes, controller will compare present encoder motor position with record value A to find the difference value. Therefore, the correct motor position can be reached.				

Alarm ID	MOT-035	Alarm Title	absolute position battery failure
Description	and driver		icoder, if the communication between the controller, but the motor encoder position value is 0, then the m message.
Possible Cause	The battery of absolute encoder has no power		
Solution	Change th	e battery	

Alarm ID	MOT-036	Alarm Title	Can't leave home dog
Description			if motor can't leave HomeDog after moving over 5 vill send this alarm message.
Possible Cause	HomeDog	is damaged	
Solution	Use the electrical multimeter to check whether the sensor of HomeDog damaged or wiring connection is missing.		
More description	first stage backward move back second sta If controll	to move to with velocity ward, it star ge, controller er leaves hor	machine will use the velocity setting value of the home DOG, and stop. After that machine moves of the second stage. After leaving home DOG to t to search the nearest motor index signal. In the rwill calculate according to resolution of encoder. me DOG more than 5 pitches and cannot find out ller will send alarm.

larm ID	MOT-037	Alarm Title	Second Positive software limit exceed
Description			int of servo motor exceeds setting value in ive software limit
Possible Cause	The motion	of machine	table exceeds setting value
Solution	Remove ala software.	arm. Move ax	is in negative direction out of stroke protection

Alarm ID	MOT-038	Alarm Title	Second Negative software limit exceed
Description			pint of servo motor exceeds setting value in tive software limit
Possible Cause	The motion	n of machine	table exceeds setting value
Solution	Remove al software.	arm. Move a	xis in positive direction out of stroke protection

Alarm ID	MOT-051	Alarm Title	Inhibit cycle start in moving	
Description	Before all manual commands are sent, prohibit starting machining to prevent operation error.			
Possible Cause	Manual command (JOG, INJOG, and MPGJOG) cannot be sent successfully.			
Solution	Remove al	arm. Wait un	til machine stops, then start machining	

## **Service and Mainteance**

## **CAUTION**

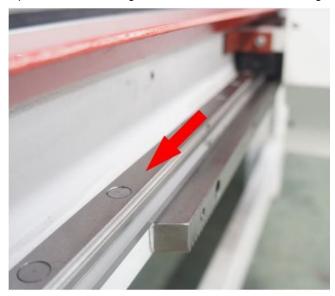
- 1.) Maintenance must be performed by qualified personnel.
- 2.) Switch off the main power supply before servicing.

If power supply is needed, have a qualified Electrician install main power Outlet.

3.) The changed or replaced parts and components must be of same type, specification & quality.

### **Drive System:**

Wipe clean the linear guides after use. Make sure the guides stay clean and lubricated.



Lubricate the rack and pinion and the ball screw drive once every week. This ensures longer service life.

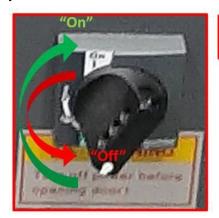


When lubricating the spindle screw, please use the manual oil gun provided by the manufacturer.



## **Electric Cabinet**

Attention! Switch off the main power supply before servicing. If power supply needed, have a qualified Electrician install an Electrical Outlet.



Main "On/Off" Power Switch

1.) Clean the cabinet with once every week. Keep the electronics clean.





2.) Inspect the fans every month. Keep them clean.



- 3.) Regularly inspect if the emergency stop button is functional. If machine belongs to Company/Facility that is ISO/QS 9000 Quality System Certified, make sure to place
- & document the stated Service & Maintenance Protocols into the facilities General Preventive Maintenance Section of the Quality System.



# **Servicing Vacuum Pumps**

## **Maintenance for Vacuum Pumps:**

- 1.) The entry filter net on the vacuum pump needs to be cleaned daily to keep dust from entering the pump.
- 2.) The exit filter net needs to be cleaned weekly.
- 3.) Inspect the pump grease every 2 months. Change, if the grease becomes dark and thick.
- 4.) Lubricate every three months. Only use the appointed grease.

# **Motion Troubleshooting**

Motion,	MOT
001	A,B feedback signal error
002	Error counter overflow
003	Encoder modulo error
004	No index signal
005	DDA command overflow
006	Can't clear index latch state
008	Loss Pulse
009	Servo Driver Alarm
010	Servo position command comm. error
011	Drive communication error
012	Driver failed to Homing
017	First Positive software limit exceed
018	First Negative software limit exceed
019	Following error exceed
020	Cannot back control mode when move
021	Must re-homing
022	Home position inaccurate
023	Fatal following error exceed
024	Dual feedback position error exceed
025	Positive hardware limit exceed
026	Negative hardware limit exceed
027	Program error in PLC axis
028	System memory too low
029	Miss index in homing
030	Zero speed timeout in homing
031	Static dual feedback error exceed
032	Following spindle error exceed
033	Absolute encoder read error
034	It is not set home position, Absolute encoder will not work
035	absolute position battery failure
036	Can't leave home dog
037	Second Positive software limit exceed
038	Second Negative software limit exceed
051	Inhibit cycle start in moving
131	minon cycle start in moving

Alarm ID	MOT-001	Alarm Title	A,B feedback signal error		
Description	Only occurs when the Pr9 – servo type is set 0 (EMP2), axis card detects A/B encoder feedback error				
Possible Cause	the A, B e	When servo type is set EMP2, internal axis card will automatically detect the A, B encoder signals, if signal error or have A-phase signal, but no B-phase signal, this alarm will appear.			
Solution	Check the	Check the servo cable or replace the axis card			

Alarm ID	MOT-002	Alarm Title	Error counter overflow		
	Only occur	rs when the F	Pr9-servo type is set to 0 (EMP2), 4(PMC4),		
Description			detects overflow encoder feedback		
Possible Cause	When serv	o type is set (	0(EMP2), 4(PMC4), 6(SERVO6), internal axis detect the A, B encoder signals, if signal error or counter overflow will appear.		
Solution	Check the servo cable or replace the axis card				
Alarm ID	MOT-005 Alarm Title DDA command overflow				
Description			nany commands. In the one interpolation time ulates that the number of commands to be sent is alarm will appear		
Possible Cause	2. Motion 3. Servo 4. Backli	parameter Pr3203) is too long 2. Motion velocity is too fast 3. Servo resolution is set too high 4. Backlash compensation or pitch compensation is too large			
Solutions	3. Redu high 3. Redu Pr61- 4. If m 1401 and f	Recommend that low interpolation time interval setting (parameter 3203) is not less than 2000     Reduce the velocity to do the test if max rapid travel federate is to high (Pr461-Pr480)     Reduce the servo resolution setting to do test (encoder and CNC Pr61-Pr80)     If mechanical compensation time constant is set (parameter 1401-1420), cancel the mechanical compensation setting to do test and find the best setting.			
More description	Please contact staff of machinery manufacturer to solve problem     In order to achieve the multi-axis coordinated control, SYNTEC's controller uses DDA (Digital Differential Analyzer), Cycle Time of DDA is set by parameter Pr 3203. In one Cycle time of DDA, every axial is allowed to send maximum 2047 pulses. Once exceeding this value, controller will send alarm				
Alarm ID	MOT-008	Alarm Title	Loss Pulse		
Alarm ID  Description	One secon	nd after send eedback com	Loss Pulse  ing command, controller will check whether the mand and sending command is in predetermined toller will send alarm.		
	One secon error of fe error range	nd after send bedback comme. If no, contr	ing command, controller will check whether the mand and sending command is in predetermined oller will send alarm.		
	One secon error of fe error range 1. Kiner 2. Serve	nd after send eedback comme. If no, contr matic occurs	ing command, controller will check whether the mand and sending command is in predetermined oller will send alarm.  obstruction phenomenon sunexpected Servo ON / OFF		
Description	One secon error of fe error range 1. Kines 2. Serve 3. CPU	and after send seedback comme. If no, contr matic occurs of drive occurs board send the	ing command, controller will check whether the mand and sending command is in predetermined oller will send alarm.  obstruction phenomenon is unexpected Servo ON / OFF the data to axis card unsuccessfully (CPU board or		
	One seconderror of feerror range  1. Kines 2. Serve 3. CPU axis composed 4. The composed	and after send seedback comme. If no, control matic occurs to drive occurs board send the card has problem and has problem as the card has problem as	ing command, controller will check whether the mand and sending command is in predetermined coller will send alarm.  obstruction phenomenon is unexpected Servo ON / OFF the data to axis card unsuccessfully (CPU board or lem, the contact between CPU and axis card is not discommand from controller to servo driver has		
<b>Description</b> Possible	One seconderror of feerror range  1. Kiner 2. Serve 3. CPU axis of good 4. The of poor of the seconderror range  4. The of poor of the seconderror range  1. Kiner 2. Serve 3. CPU axis of good 4. The of poor of the seconderror range  4. The of the seconderror r	ad after send sedback comme. If no, control matic occurs to drive occurs board send the eard has problem as a board send the eard has problem as a board send the eard has problem as a board send that send quality or is o	ing command, controller will check whether the mand and sending command is in predetermined oller will send alarm.  obstruction phenomenon is unexpected Servo ON / OFF the data to axis card unsuccessfully (CPU board or lem, the contact between CPU and axis card is not discommand from controller to servo driver has disconnected.		
<b>Description</b> Possible	One seconderror of feerror range  1. Kiner 2. Serve 3. CPU axis of good 4. The of poor of 5. Contri	ad after send eedback comme. If no, control end occurs to drive occurs board send the eard has proble eable that send quality or is coller doesn't	ing command, controller will check whether the mand and sending command is in predetermined coller will send alarm.  obstruction phenomenon is unexpected Servo ON / OFF the data to axis card unsuccessfully (CPU board or lem, the contact between CPU and axis card is not discommand from controller to servo driver has		

Alarm ID	MOT-008	Alarm Title	Loss Pulse		
Solution	<ol> <li>Do not shut down the controller when alarm occurs. Please check whether the value of No 8, 9, 10 in diagnose function is zero</li> <li>Check whether the mechanical lubrication system is good.</li> <li>Open the cover of axial to check whether foreign matter blocks the motion of axial.</li> <li>Rotate screw to check whether machine is stuck (loading of driver)</li> <li>Check the drive servo-on and the servo-off of power or cable signal of the setting value of No 8, 9, 10 in diagnostic function do not change please take home search action (don't need to reboot), after that check whether parameters 24, 25, 26, 40, 41, 42 are equal to zero, if the parameters 24, 25, 26 are not equal to zero, the feedback loop has problems</li> <li>If the parameters 40, 41, 42 are not equal to zero, commanter transmission from controller to the motor has been lost pulse.</li> <li>If all parameters 24, 25, 40, 41, 42 are not zero, then the interference signal is relatively large, specifically in the machining process, the setting value of parameters 8, 9, 10 gradually become large. The reason is the contact point between CPU board and axis card is not good. Try to replace CPU board and axis card</li> </ol>				
More description	Set parameters 561~580 to check the range of loss pulse 8[X axis following error value] 9[Y axis following error value] 10[Z axis following error value] 24[X axis absolute position feedback value] 25[Y axis absolute position feedback value] 26[Z axis absolute position feedback value] 40[X axis absolute position command value] 41[Y axis absolute position command value] 42[Z axis absolute position command value]		g error value] g error value] g error value] e position feedback value] e position feedback value] e position feedback value] e position command value] e position command value]		

Alarm ID	MOT-009	Alarm Title	Servo Driver Alarm
Description	Drive send	ls out warnin	g signal
Possible Cause	Drive alarm mostly is because of external causes. Ex: High temperature connecting wire error, internal parameters is set wrong, servo motor is unsuitable, driver is error, etc.		
Solution	Follow the steps in driver's application manual to solve alarm		ver's application manual to solve alarm

Alarm ID	MOT-010	Alarm Title	Servo position command comm. error
Description	(F)	vill check wh	tion between Kernel and axis card has errors, tether the queue value in internal IC of axis control
Possible Cause	There is only one axis card, but parameter sets two axis cards, and servo axis points to the second axis card     One axis card has errors in case controller has two more axis cards     Two or more axis cards, IRQ11 Jump is plugged. In diagnosis function, number 23 is not equal to 100		
Solution	Check whether the parameter setting Pr11, Pr13 are consistent with the hardware feature     Check jump axis card setting     Change axis card to do test		
More description	whether th	e QUEUE va value, alarm	ne interval, Kernel (core) software will check alue FLAG is correct. After one FILTER, if it reads will appear and diagnose function number 68 will

Alarm ID	MOT-011	Alarm title	Drive communication error
Description	Abnormal d	river commun	ication
Possible Reason	External rea	son like wire	problem or noise interference
Solution			of drive and checking whether controller is rrectly or noise interference.

Alarm ID	MOT-012	Alarm title	Driver homing error	
Description	If Driver sea	arches home u	nsuccessfully, this alarm will appear	
Reason	Home search method is set incorrectly (Pr961) or driver doesn't support home search function			
solution	Check whet search funct		ch method is correct or driver supports home	

Alarm ID	MOT-017	Alarm Title	First Positive software limit exceed	
Description	The end po	oint in moven	nent of servo motor exceeds positive software limit	
Possible Cause	Stroke movement of machine table exceeds the setting value			
Solution	Remove a		axis moves to negative movement out of the stroke	

Alarm ID	MOT-018	Alarm Title	First Negative software limit exceed			
Description	The end point in movement of servo motor exceeds negative software limit					
Possible Cause	Stroke movement of machine table exceeds the setting value					
Solution		Remove alarm, and let axis move to positive movement out of the stroke protection software				
Alarm ID	MOT-019	Alarm Title	Following error exceed			
Description	way to re	Because of the characteristics of servo, servo motor location, there is no way to respond the command of controller immediately, so a slow phenomenon appears, when this latency is not in allowed range, controller will send out the alarm.				
Possible Cause	Movement mechanism is not smooth     Contact wire has poor quality     Setting values of acceleration and deceleration time are too small     Servo on off Relay is interfered					
	5. Inner	loop gain of	driver is set too small			
	6. Enco	der solution	and electric gear ratio is set wrong			
	7. Drive or motor is damaged					
	Encoder or line between encoder and controller is abnormal					
	9. On diagnosis screen, number 23 is not equal to100					
	Add lubricating oil to machine					
	Use electric meter to check whether wire connecting is correct. V     controller runs dry run mode, open case to check whether serv off of relay pulses abnormally.					
Solution	Increase acceleration and deceleration time (parameter 401)     Inner loop gain of driver is set too small. For Mitsubishi driver, check Pr37					
	6. Cont	act to machin	nery manufacturers for helping			

Alarm ID	MOT-019	Alarm Title	Following error exceed
More description	setting par of control Reasonab loop gain Alarm all process), For examp Ferr = 100 32[X axis 33[Y axis	rameter divid ler. le following lowed value: velocity G00 ple: Speed 10 00*1000÷60+ reasonable f	following error] following error] 34[Z

MOT-020	Alarm Title	Cannot back control mode when move
Interpolati	on time inter	or monitor mode (C31 ~) is canceled, in one val (No 3203) if the motor movement exceeds zero 01), controller will send alarm.
000000		ovement of machine by hand adly. Therefore, when cancelling instantly, motor
will	be trembled	
1. Avo		movement position loop gain and speed loop gain setting
	When emilinterpolatic speed check.  1. Cancer 2. Drive will	When emergency stop Interpolation time inter speed check window (9 1. Cancel instantly m 2. Drive gain is set b will be trembled

Alarm ID	MOT-021	Alarm Title	Must re-homing		
Description	When MO	T-0020 and !	MOT-0022 appear, the controller will send alarm		
Possible Cause	MOT -0020[Cannot back control mode when move] or MOT -0022[Home position inaccurate] is triggered				
Solution	See MOT	See MOT -0020 or MOT -0022-alarm			

Alarm ID	MOT-022	Alarm Title	Home position inaccurate		
Description	After booting, at the N(N>1) times of searching home, home grid will be compared to the result of the first time searching home, if the error is over 0.1 turn of motor, the controller will send alarm.				
Possible Cause	Homing signal of motor is abnormal     Stopper, coupling or bearings is not locked tightly				
Solution	Move motor in the same direction and observe to check whether position counter index changes normally.     Check whether the mechanism components are fixed properly				

Alarm ID	MOT-023	Alarm Title	Fatal following error exceed		
Description	Because of the characteristics of servo, servo motor location, controller cannot respond immediately command, a delay phenomenon will appear, when this delay phenomenon is not in allowed limit, the controller will send a				
Possible Cause	Servo motor doesn't receive control due to external force     Parameter of drive - inner loop gain is too small     Parameters of acceleration and deceleration time is set too short     Encoder is abnormal or connecting encoder to controller is abnormal				
Solution	Check the external motion of machine table     Check the setting parameter of drive     Check the acceleration and deceleration setting of each axis, parameters 401, 541-560     Maintain the connection between encoder and servo drives.				
More description	Maximum velocity value of G00 and home search is equal to setting parameter divided by Kp. This value multiplied by 4 is setting range of controller.  Reasonable following error: Ferr= speech in command/ loop gain Alarm allowed values= {max[(velocity of first stage in home search process), velocity G00 of each axis]/Kp}*4  32[X axis reasonable following error]  33[Y axis reasonable following error]				

# **Compiler Troubleshooting**

Compile	er, COM					
001	EOF in comment					
002	No end of string character					
003	Syntax error					
004	Illegal variable					
005	xpression too complex					
006	EXIT statement outside loop statement					
007	Repeat loop too deep					
008	absent end of statement character ';'					
009	wrong assignment character ':='					
010	absent right ')'					
011	absent right ']'					
012	absent 'FOR' keyword in FOR statement					
013	absent 'DO' keyword in FOR statement					
014	absent 'END_FOR' keyword in FOR statement					
015	absent 'UNTIL' keyword in REPEAT statement					
016	absent 'END_REPEAT' keyword in REPEAT statement					
017	absent 'DO' keyword in WHILE statement					
018	absent 'END_WHILE' keyword in WHILE statement					
019	absent 'THEN' keyword in IF statement					
020	absent 'END_IF' or 'ELSE' keyword in IF statement					
021	absent 'END_IF' keyword in IF statement					
022	absent 'OF' keyword in CASE statement					
023	absent 'END_CASE' or 'ELSE' keyword in CASE statement					
024	absent 'END_CASE' keyword in CASE statement					
025	absent ':' or ',' delimiter in CASE statement					

Alarm ID	COM-001	Alarm Title	EOF in comment	
Description	as the begi		)" must be used in pairs, if the program uses "(*" comment, but doesn't use "*)" at the end of the send alarm	
Possible Cause	Programming error			
Solution	Using sym	ibol "(*" befo	re command and symbol "*)" after command	

Alarm ID	COM-002	Alarm Title	No end of string character
Description	Character s	string in brack	kets of PRINT command in MACRO has no
Possible Cause	Programming error		
Solution	Check PRI	NT command	d of program

Alarm ID	COM-003	Alarm Title	Syntax error
Description MACRO program has syntax error when controller interprets it			
Possible Cause	Programming error		
Solution	Check pro	gram syntax a	according to symbol appears on the screen

Alarm ID	COM-004	Alarm Title	Illegal variable	
Description	System cannot access variable, this alarm will appear.			
Possible Cause	Change error variable			
Solution	Check pro	gram variable	and confirm whether system uses that variable	

Alarm ID	COM-005	Alarm Title	expression too complex	
Description	MACRO is	s too complic	ated,	
Possible Cause	Programming error			
Solution	Check whe	ther logic is	clear and correct	

Alarm ID	COM-006	Alarm Title	EXIT statement outside loop statement			
Description	The purpose of EXIT command is to jump out loop. If EXIT command					
	cannot go to next loop, system will send alarm					
Possible Cause Programming error						
Solution	Check whe	ther EXIT co	mmand in program is used correctly			

Alarm ID	COM-007 Alarm Title Repeat loop too deep	
Description	IF Loop command in MACRO such as REPEAT loop, REPEAT lo WHILE loop, FOR loop repeats more than 10 times, system will se this alarm.	
Possible Cause	Programming error	
Solution	Change MACRO program to avoid too many loop commands.	

Alarm ID	COM-008	Alarm Title	absent end of statement character ';'		
Description	Program de finishes.	pesn't have to	erminal symbol when MACRO command		
Possible Cause	Programmi	Programming error			
Solution	Check MA	CRO prograi	m to confirm whether it has the terminal symbol		

Alarm ID	COM-009	Alarm Title	wrong assignment character ':='	
Description			g value to symbolic variable doesn't use the system will send alarm	
Possible Cause	Programming error			
Check MACRO program to see whether assigning value to variable is correct		n to see whether assigning value to symbolic		

Alarm ID	COM-010	Alarm Title	absent right')'
Description		, notation "(" l send alarm	and ")" must be used in pairs, if "(" lacks ")",
Possible Cause	Programmi	ng error	
Solution	Check MA	CRO program	n to confirm whether using "(" and ")" is correc

Alarm ID	COM-011	Alarm Title	absent right']'
Description		, notation "[" I send alarm	and "]" must be used in pairs, if "[" lacks "]",
Possible Cause	Programm	ing error	
Solution	Check MA	CRO prograr	m to confirm whether using "[" and "]" is correct

Alarm ID	COM-012	Alarm Title	absent 'FOR' keyword in FOR statement	
Description		p in MACRO will appear.	D uses TO to define loop condition incorrectly,	
Possible Cause	Programming error			
Cause  Check MACRO program to confirm whether FOR loop  Solution		n to confirm whether FOR loop uses TO correctly		

Alarm ID	COM-013	Alarm Title	absent 'DO' keyword in FOR statement	
Description		p in MACRO , this alarm w	Duses DO to define Implement task in loop rill appear.	
Possible Cause	Programming error			
Check MACRO program to confirm whether FOR loop uses DO correctly				

Alarm ID	COM-014	Alarm Title	absent 'END_FOR' keyword in FOR statement	
Description	If FOR loo will appear		O doesn't use END_FOR to finish loop, this alarm	
Possible Cause	Programming error			
	Check MACRO program to confirm whether FOR loop uses END_FOR			

Alarm ID	COM-015	Alarm Title	absent 'UNTIL' keyword in REPEAT statement	
Description		loop in MA , this alarm w	CRO uses UNTIL to define loop condition vill appear.	
Possible Cause	Programming error			
Check MACRO program to confirm whether using UNTIL in loop is correct		n to confirm whether using UNTIL in REPEAT		

Alarm ID	COM-016	Alarm Title	absent 'END_REPEAT' keyword in REPEAT statement
Description	If REPEAT loop doesn't have END_REPEAT to finish loop, this alarm will be sent		
Possible Cause	Programming error		
Solution	Check MACRO program to confirm whether REPEAT loop has END_REPEAT		

Alarm ID	COM-017	Alarm Title	absent 'DO' keyword in WHILE statement	
Description	If WHILE will appear		to define implement task incorrectly, this alarm	
Possible Cause	Programming error			
Solution	Check MACRO program to confirm whether WHILE loop uses DO correctly		n to confirm whether WHILE loop uses DO	

Alarm ID	COM-018	Alarm Title	absent 'END_WHILE' keyword in WHILE statement	
Description	If WHILE	loop doesn't	have END_WHILE to finish loop	
Possible	Programmi	Programming error		
Cause				
Solution	check MAG		n to confirm whether WHILE loop has	

Alarm ID	COM-019	Alarm Title	absent 'THEN' keyword in IF statement	
Description	If IF uses 7 this alarm	THEN to defin	ne implement task incorrectly, system will send	
Possible Cause	Programmi	Programming error		
Solution	Check MACRO program to confirm whether IF loop use END correctl			

Alarm ID	COM-020	Alarm Title	absent 'END_IF' or 'ELSE' keyword in IF statement		
Description	If IF loop doesn't have ELSE or END_IF, this alarm will appear				
Possible Cause	Programming error				
Solution	check whether IF loop uses ELSE or END_IF				

Alarm ID	COM-021	Alarm Title	absent 'END_IF' keyword in IF statement		
Description	If IF loop uses END_IF to finish loop incorrectly, this alarm will appear				
Possible Cause	Programm	Programming error			
Solution	Check whe	ther IF loop	uses END_IF correctly		

Alarm ID	COM-022	Alarm Title	absent 'OF' keyword in CASE statement	
Description	If CASE command uses OF incorrectly, this alarm will appear			
Possible Cause	Programming error			
Solution	Check whether CASE command uses OF correctly			

Alarm ID	COM-023	Alarm Title	absent 'END CASE' or 'ELSE' keyword in CASE statement
Description	If CASE command doesn't use ELSE or END_CASE		
Possible Cause	Programming error		
Solution	Check whe	Check whether CASE loop uses ELSE or END_CASE correctly	

Alarm ID	COM-024	Alarm Title	absent 'END_CASE' keyword in CASE statement		
Description	If CASE co	ommand does	sn't have END_CASE keyword		
Possible Cause	Programming error				
Ensure that END_CASE keyword is used before finishing CASE command					

Alarm ID	COM-025	Alarm Title	absent ':' or ',' delimiter in CASE statement			
Description	If CASE co	ommand in M	ACRO uses '; 'or ', ', this alarm will appear.			
Possible Cause	Programming error					
Solution	Check MACRO program. In CASE statement, '; 'or ', ' is correct.  However, you should use'; 'when finishing CASE command.					

# **Program Error Troubleshooting**

Alarm ID	COR-001	Alarm title	Array Index must be Integer				
Description			not an integer, the system will send this alarm mmand is not positive integral, this alarm will				
Reason	Programmin	Programming error.					
Solution	Please check the machining program, the index in MACRO command has to be rounded Ex: @[ROUND(#1)+1]						
	Ex : @[RO	UND(#1)+1]					
Alarm ID	Ex : @[RO	UND(#1)+1]  Alarm title	File not found				
Alarm ID  Description	COR-002  If the file th	Alarm title					
	COR-002  If the file th	Alarm title nat the system 98 (or G65.G	File not found wants to read does not exist				

Alarm ID	COR-003	Alarm title	Devide by zero		
Description			n of MACRO is equal to 0 #3) command is equal to 0.		
Reason	Programming error				
Solution	Check the machining program to ensure that the denominator is not equal to 0.				

Alarm ID	COR-004	Alarm title	Operand domain error	
Description				
Reason	Programmii	ng error		
Solution	Please chec	k the machini	ng program.	

Alarm ID	COR-005	Alarm title	Program loading failure		
Description	MACRO sy	ntax error.			
Reason	Programmi	ng error			
Solution	Please chec	k the machini	ing program.		
Alarm ID	COR-006	Alarm title	Arc not on work plane		
Description	In G02 and G03 syntax, if vector from center to starting point is not on the arc of working plane, this alarm will appear.  Ex: G17 G02 I50. K10.; if it implements the left program, this alarm will appear.				
Reason	Programming error				
Solution	Check the n correctly.	nachining pro	gram to ensure that G02 and G03 are used		

Alarm ID	COR-007	Alarm title	Arc radius too short		
Description			if Arc radius is smaller than 10 to the power of m will send this alarm		
Reason	Programming error				
Solution	200	Check the machining program to ensure that the Arc radius of G02 at G03 are used correctly			

Alarm ID	COR-008	Alarm title	Arc destination not on arc	
Description	In G02 and G03 syntax, if the Arc end point coordinate is not on the circle, system will send this alarm.  From V8.31 version, parameter 3807- destination not on arc check window is added. It allows error set in parameter 3807.  When error of Arc end point coordinate is smaller than setting value Pr3807, system will automatically correct center coordinate, so the point can be on arc correctly.  If error of Arc end point coordinate is bigger than setting value in Pr3807, system will send alarm.			
Reason	Programming error			
Solution	Programming error  Check the machining program to ensure that the Arc radius of G02 a G03 are used correctly			

Alarm ID	COR-009	Alarm title	Macro call too deep	
Description	Use G65 to	call MACRO	subprogram that has more than 12 layers	
Reason	Programming error			
Solution		Check machining program to ensure that G65 calls MACRO subprogram that has less than 12 layers		

Alarm ID	COR-010	Alarm title	Modal macro call too deep	
Description	Use G66 to	call MACRO	subprogram that has more than 4 layers	
Reason	Programming error			
Solution		Check machining program to ensure that G66 calls MACRO subprogram that has less than 4 layers		

Alarm ID	COR-011	Alarm title	Subprogram call too deep	
Description	Use M98 to	call subprog	ram that has more than 16 layers	
Reason	Programming error			
Solution	Check machining program to ensure that M98 calls subprogram that has less than 16 layers			

Alarm ID	COR-012	Alarm title	Too many modal macro canel,G67		
Description	G66 and G67 need to be used in pairs. When number of G67 is than G66 in one machining program, this alarm will appear.				
Reason	Programming error				
Solution	Check progra	nm to ensure t	hat G66 and G67 are used in pairs		

Alarm ID	COR-013	Alarm title	G65,G66 must be the last one in G code list
Description	G65 and G66 please put of	6 will have pr her G code in de of G65 and	O, so in single block the right hand side of rocessing arguments. So in single block, a the left hand side of G65 and G66. If the d G66 has G code or M code, system will
Reason	Programmin	g error	
Solution	Please check	the machinir	ng program.

Alarm ID	COR-014	Alarm title	Absent program number		
Description	The right hand side of G65 and G66 doesn't have parameter P to specify program number, system will send this alarm.				
Reason	Programming error				
Solution	Please check	the machinin	g program to ensure the use of G65 and G66.		

Alarm ID	COR-015	Alarm title	Too many M code			
Description	There are me	ore than 3 M	codes in a single block.			
Reason	Programmin	Programming error				
Solution	Please check the machining program to ensure that there are equal or less than 3 M codes in a single block					
Alarm ID	COR-016	Alarm title	Illegal variable access			
Description	Accessing v	Accessing variables do not exist.				
Reason	Programming error					

Alarm ID	COR-017	Alarm title	Label not found	
Description	Cannot find out corresponding line number N in GOTO command			
Reason	Programmii	ng error		
Solution	Please chec	k the machini	ng program.	

Alarm ID	COR-018	Alarm title	Line number not found			
Description	Input of line	input of line number is incorrect when implementing MDI				
Reason	Programmii	Programming error				
Solution	Enter the co	ter the correct MDI line number				

Alarm ID	COR-019	Alarm title	sub program no M99			
Description	Subprogran	Subprogram has no M99 to return main program				
Reason	Programmin	Programming error				
Solution	Write M99	Write M99 at the end of subprogram				

Alarm ID	COR-020	Alarm title	Too many G code			
Description	There are m	There are more than 10 G codes in a single block.				
Reason	Programmii	Programming error				
Solution	Dividing the	Dividing that single block into others single block that has less than				

Alarm ID	COR-021	Alarm title	Too many (I,J,K) triples		
Description	Repeat to much IJK command in the same single block.				
Reason	Programmii	Programming error			
Solution	Please chec	Please check the machining program.			

Alarm ID	COR-022	Alarm title	Use undefined workpiece coordinate			
Description	Do not inpu	Do not input G17, G18, G19				
Reason	Programmin	Programming error				
Solution	Decide the	Decide the working plane, and input G17, G18, or G19				

Alarm ID	COR-024	Alarm title	Invalid arc radius value		
Description	When implementing G02, G03, appointing Arc end point and given radius is contradicted, given radius cannot meet appointing Arc end point.  Ex: G03X1500Y4000R2000				
Reason	Programmi	ng error			
Solution	Check the program and recalculate.				
Alarm ID	COR-025	Alarm title	macro stack is full or access fail		
Description	STACK can store maximum value up to 4095(PUSH). If this value is exceeded, controller will send alarm.     in STKTOP[n], n is started from 0, if the value of n is bigger than  (value storing in stack-1), controller will send alarm				
Reason	Storing value in STACK (PUSH) is to much.     Arguments in STKTOP[]exceeds the value storing in STACK				
Solution	AND 100 100		oush command ment in STKTOP[].		

Alarm ID	COR-026	Alarm title	macro stack is empty			
Description	Empty stack still has value pop()					
Reason	The number	The numbers of Push commands and Pop commands are not the same.				
Solution	Check the program to ensure that the number of Push commands is to same with that of Pop commands.					

Alarm ID	COR-027	Alarm title	Invalid macro arguments				
Description	Macro Alar	Macro Alarm.					
Reason	Once Macro finds out the unreasonable situation, machining program will be stopped and alarm will appear						
Solution	According to display content of alarm to find out where error is						
Alarm ID	COR-028	Alarm title	macro program error				

Alarm ID	COR-028	Alarm title	macro program error
Description	Cannot quit	Quiet Mode	although Quiet Mode already finish.
Reason	Programmin	ng error	
Solution	Please chec	k the machini	ing program.

Alarm ID	COR-029	Alarm title	Tool length offset change at arc
Description	G43, G44, G single block		vive linear interpolation command in the next
Reason	Programmii	ng error	
Solution	Please chec	k the machini	ng program.

Alarm ID	COR-031	Alarm title	Radius compensation cancel at arc
Description	G40 only re block	ceives linear	interpolation command in the next single
Reason	Programmin	ng error	
Solution	Please chec	k the machini	ing program.

Reason

Program error

Alarm ID	COR-032	Alarm title	Radius compensation startup at arc			
Description	G41,G42 or block	G41,G42 only receive linear interpolation command in the next single block				
Reason	Programming error					
Solution	Please check	the machini	ng program.			
Alarm ID	COR-033	Alarm title	Wrong direct draw command usage			
Description	Using A, R,	or C commar	d is not suitable for specification			
Reason	Programmin	g error				
Solution			n to confirm that whether before and after r specifications			
Alarm ID	COR-035	Alarm title	Zero movement at corner in direct draw			
Description	Before and after single block, inserted value of rounding or chamfer is too small and cause system calculates wrong					
Reason	Programming error					
Solution	Check machining program to confirm that whether inserted value of rounding or chamfer is suitable for specifications     Check to confirm whether working plane and round plane are the same.					
Alarm ID	COR-036	Alarm title	Invalid angle amount , A, in direct draw			
Alarm ID  Description			Invalid angle amount, A, in direct draw nterpolation of single block.			
110000000000000000000000000000000000000		nly in linear i	-			
Description	A is valid of Programmin	l nly in linear i ng error	nterpolation of single block.  In to confirm that whether angle amount A is			
Description Reason	A is valid of Programmin	l nly in linear i ng error nining prograi	nterpolation of single block.  In to confirm that whether angle amount A is			
Description Reason Solution Alarm ID	A is valid of Programmin Check mack suitable for COR-037	nly in linear i ng error nining prograt specifications  Alarm title	nterpolation of single block.  In to confirm that whether angle amount A is s  Dot chamfer amount bigger than displacement			
Description Reason Solution	A is valid of Programmin Check mack suitable for COR-037	nly in linear i ng error nining prograt specification:  Alarm title ofter single bl d cause system	Interpolation of single block.  In to confirm that whether angle amount A is a Dot chamfer amount bigger than displacement ock, inserted value of rounding or chamfer is			
Description Reason Solution Alarm ID Description	A is valid of Programmin Check mack suitable for COR-037  Before and a too small an Programmin 1. Check to of roun	nly in linear ing error nining programspecifications  Alarm title offer single blid cause system g errors.  machining proding or cham	m to confirm that whether angle amount A is  Dot chamfer amount bigger than displacement ock, inserted value of rounding or chamfer is m calculates wrong  ogram to confirm that whether inserted value fer is suitable for specifications.			
Description Reason Solution Alarm ID Description Reason	A is valid of Programmin Check mach suitable for COR-037  Before and a too small an Programmin 1. Check to of roun 2. Check to Ch	nly in linear ing error nining programspecifications  Alarm title offer single blid cause system g errors.  machining proding or cham	nterpolation of single block.  In to confirm that whether angle amount A is s  Dot chamfer amount bigger than displacement ock, inserted value of rounding or chamfer is mealculates wrong			

Check the machining program, and correct coordinate position

Alarm ID	COR-041	Alarm title	GOTO label must be integer	
Description	The input G Ex: GOTO GOTO 1. W N1; Correct N1.; Wrong	l Correct rong	not an integer.	
Reason	Program error			
Solution	Check the n	nachining pro	gram, and input integer in GOTO label.	

Alarm ID	COR-043	Alarm title	ASIN()/ACOS() operand must between -1.0 and 1.0
Description	ASIN()/A	COS() Opera	nd is not between -1.0 and 1.0.
Reason	Programm	ing error	
Solution	Check the	machining p	rogram.

Alarm ID	COR-044	Alarm title	SQRT() operand should not be negative
Description		root of a negative root of a neg	ative value will be imaginary, but the controller ction.
Reason	Programmii	ng error	
Solution	Check the p	rogram; ente	r a positive value in SQRT operand.

Alarm ID	COR-045	Alarm title	L address should be integer
Description	The L addre	ess is not an i	nteger.
Reason	Programmi	ng error	
Solution	Check the p	rogram, and	use L address in integer.

Alarm ID	COR-046	Alarm title	O address should be integer	
Description	The O addr	ess is not an i	nteger.	
Reason	Programmin	ng error		
Solution	Check the p	rogram, and	use O address in integer.	

Alarm ID	COR-047	Alarm title	M address should be integer	
Description	M address i	s not an integ	er.	
Reason	Programmi	ng error		
Solution	Check the p	orogram, and	use M address in integer.	

Alarm ID	COR-048	Alarm title	Spindle speed, S, should be integer			
Description	The speed S	he speed S of spindle is not an integer.				
Reason	Programmin	ng error				
Solution	Check the p	rogram, and	use the speed S of spindle in integer.			

Alarm ID	COR-049	Alarm title	Tool length number, H, should be integer	
Description	If tool lengt alarm.	h number, H,	is not an integer, controller will send this	
Reason	Programming error			
Solution	Please chec	k the progran	n, and use tool length number H in integer	

Alarm ID	COR-050	Alarm title	Tool radius number, D, should be integer	
Description	If tool radius number, D, is not an integer, controller will send this alarm.			
Reason	Programming error			
Solution	Please chec	k the progran	n, and use the tool radius number D in integer	

Alarm ID	COR-051	Alarm title	Tool selection number, T, should be integer
Description	If the tool n	umber, T is n	ot an integer, this alarm will appear.
Reason	Programming error		
Solution	Please check the program, and use the tool number T in integer.		

Alarm ID	COR-052	Alarm title	Sub-program number, P, should be integer	
Description	If the sub-program number P is not an integer, controller will send alarm.			
Reason	Programming error			
	Please check the program, and use the sub-program number P in integer.			

Alarm ID	COR-053	Alarm title	Repeat count, L, should be integer	
Description	If the repeat times L is not an integer, this alarm will appear.			
Reason	Programming error			
Solution	Please check the program, and use the repetitive times L in integer.			

Alarm ID	COR-054	Alarm title	Imcompatible data type	
Description	When the data format doesn't meet the requirements set by control controller will send this alarm.			
Reason	Machining program is not compatible with the SYNTEC controller.			
Solution	Make sure t	Make sure that the data format is suitable for controller.		

Alarm ID	COR-055	Alarm title	Tool length number, H, over range	
Description	The tool len	gth number I	I exceeds the range of tool number.	
Reason	Programming error			
Solution	Make sure that the tool length number, H, is in the range of tool number.			

Alarm ID	COR-056	Alarm title	G10 table index, P, over range		
Description	correspondi	ing P value, E 1000, and the	0 L P R ; different L value has different x: L10 has the corresponding tool No. P. If tool No. P1000 doesn't exist, controller will		
Reason	Program error				
Solution	Use reasona	able value P is	n G01 table index		

Alarm ID	COR-057	Alarm title	Tool radius number, D, over range		
Description	The tool radius number D exceeds the range of tool number.				
Reason	Program error				
Solution	Make sure t	Make sure that the tool radius number D is in the range of tool number			

Alarm ID	COR-058	Alarm title	Tool nose number over range				
Description	If the tool n will send th		exceeds the range of tool number, the controller				
Reason	Program err	Program error					
Solution	Make sure that the tool radius number D is in the range of tool number						
Alarm ID	COR-059	Alarm title	Subprogram call sequence num., H, must integer				
Description	Number H called in subprogram is not an integer						
Reason	Program error						
Solution	Change the	Change the number H of subprogram into an integer.					

Alarm ID	COR-060	Alarm title	M99 return sequence number, P, must integer	
Description	The return sequence number P of M99 is not an integer.			
Reason	Program error			
Solution	Change the return sequence number P of M99 into an integer.			

Alarm ID	COR-061	Alarm title	Workpiece number over range	
Description	The number controller.	r of work piec	ees exceeds the allowable range of the	
Reason	Program error.			
Solution	Make sure the number of work pieces in the allowed range of the controller.			

Alarm ID	COR-062	Alarm title	Dwell skip source, Q, must be integer				
Description	If dwell skip	If dwell skip source Q is not an integer, controller will send this alarm.					
Reason	Program err	Program error					
Solution	Change the	Change the dwell skip source Q into an integer.					
Alarm ID	COR-063	Alarm title	Dwell skip source Q, over range				
Description	Dwell skip source Q exceeds the allowed range						
Reason	Program error.						
Solution	Make sure ti	Make sure the dwell skip source Q in the allowed range.					

Alarm ID	COR-064	Alarm title	P address must be integer		
Description	If P address	If P address is not an integer, this alarm will be sent.			
Reason	Programmin	Programming error			
Solution	Change P ad	Change P address into an integer.			

Alarm ID	COR-065	Alarm title	Dot angle and axis command conflict	
Description	The end poin	t of single blo	ock is in the specified angular direction.	
Reason	Programming error			
Solution	Check the ma	achining prog	ram.	

Alarm ID	COR-066	Alarm title	Inc. axis command and abs. axis command conflict		
Description	Both G91 a	nd G90 are in	n the same line.		
Reason	Programmin	Programming error			
Solution	Decide to use incremental or absolute command, and enter the correct command.				

Alarm ID	COR-067	Alarm title	Arc center vector and radius conflict		
Description	The arc end the specify		on the arc created by the arc starting point and		
Reason	Programming error				
Solution	Please chec	k the machin	ing program.		

Alarm ID	COR-068	Alarm title	Metric/Inch cmd. not available under quiet mode			
Description	The Quiet n		on of single block command cannot switch to			
Reason	Programmir	Programming error				
Solution	Please check the machining program.					
Alarm ID	COR-069	Alarm title	Corner round and chamfer cmd. conflict			
Description	Chamfer co	Chamfer command and fillet command are on the same line.				
Reason	Program error					
Solution	Do not let c	Do not let chamfer command and fillet command exist in the same line				

Alarm ID	COR-070	Alarm title	Invalid G Code			
Description	Enter incorr	Enter incorrect G code to controller.				
Reason	Program err	Program error				
Solution	Enter the va	alid G-code.				

Alarm ID	COR-071	Alarm title	No main program assignment		
Description	The name of	The name of main program is not specified.			
Reason	The program	The program is not loaded.			
Solution	Specify the	Specify the name of main program.			

Alarm ID	COR-074	Alarm title	Overcut by tool radius too big		
Description	radius 2. During	of tool, this a	ototh, if notch width is smaller than twice larm will appear. rapezoidal, if the height of trapezoidal is less tool, this alarm will be sent.		
Reason	Tool compensation causes overcut				
Solution			ing program to decide whether this part of the compensation.		

Alarm ID	COR-075	Alarm title	Exact stop wait timeout
Description		etween feedb	act stop (G09/G61) command, If the ack and command exceeds allowable value,
Reason	Servo vibrati	on	
Solution	Servo tur     Change p	ning parameters	

Alarm ID	COR-076	Alarm title	G04 dwell time cannot be negative			
Description	When input	value of dwel	time G04 is negative, this alarm will appear.			
Reason	Program erro	Program error				
Solution	Check the ma	achining prog	ram, and enter a positive value to G04			

Alarm ID	COR-201	Alarm title	Part program file not exist
Description	When speci	fied program	does not exist, this alarm will appear.
Reason			
Solution	Ensure that	program file	exists

Alarm ID	COR-202	Alarm title	Communication link failure
Description	When com	nunication lin	nk is dropped, controller will send this alarm.
Reason	00		
Solution	Reconnect a	good comm	unication link

Alarm ID	COR-203	Alarm title	Loading page size too small
Description	System assi new program		age to small, and can't meet the demands of
Reason			
Solution	Please conta	act with the n	nachinery manufacturer.

Alarm ID	COR-204	Alarm title	File size too large
Description	When progr	am file is too	large, controller will send this alarm
Reason	Program em	or	
Solution	Reduce the	program size,	or split program into two subprograms.

Alarm ID	COR-205	Alarm title	File content is empty
Description	After contro	oller loads the	e program, it finds out that the file content is
Reason	Loading pro	ogram error o	r CF card damaged
Solution	Reload prog	gram or replac	ce CF card

Alarm ID	COR-206	Alarm title	Loading page lock failure
Description	New machin unsuccessfu		requires the system to distribute loading page
Reason			
Solution	Please conta	ct machinery	manufacturers

Alarm ID	COR-207	Alarm title	Sequence number not found
Description	When seque	ence number i	s not found, controller will send this alarm.
Reason	Program err	or	
Solution	Use sequence	ce number in	the program range.

Alarm ID	COR-208	Alarm title	Cannot use jump statement in sequential file
Description	Using jump	command to	execute sequential file.
Reason			
Solution	Do not use j	jump commar	nd to execute sequential file.

## **Spindle Safety Instructions**

- 1.) Use ISO 30 Tool Holder (HSD 9KW Spindle).
- 2.) It is suggested that you use original tool holders.
- 3.) The tool holder must be in the upright position when changing tools.
- 4.) Empty the filter every day (preferably every 8 hours) to prevent from rusting.
- 5.) Air Pressure needs to be 6kg-7kg during tool change.
- 6.) Clear the dust in the spindle regularly. Do not blow to clean. Shut the red cover plate when the spindle is not in use to prevent dust from falling in.
- 7.) Keep the tools sharp and clean. The workpiece needs to be fixed tightly on the table or the spindle will vibrate during a job.
- 8.) Change the filter in the oil-water separator on a monthly basis. Empty the water every 8 hours. Blow air into the middle hole and make sure there is no oil, or else the bearing might be damaged.
- 9.) The air needs to be filtered to be free of moist, oil mist and dust before entering the spindle.

#### **Other Maintenance Protocols**

NOTICE

The coolant filter net needs to be cleaned daily.

NOTICE

Clean the tool magazine regularly.

To have a longer service life, perform regular maintenance on the following parts and components:

- 1.) Keep the machine lubricated. Regularly inspect and clean the lubrication system. Keep the ball screw, linear guide and rack and pinion lubricated at all times.
- 2.)Regularly inspect the vacuum system. The filter nets need to be cleaned and changed regularly. Remember to empty the filter in time. When the system gives out low pressure alarm, check if the pressure is enough.
- 3.) Inspect the over travel limit switches (both software limit switch and mechanical stopper regularly. Do not let rust accumulate on the limit switches as it seriously affects their sensitiveness and may fail to give alarm when the machine over travels, which could lead to mechanical crash and damage to the machine. The way to inspect is to press the switch with hand to see if it gives off alarm. You can also check if the I/O port input signal changes.
- 4.) Regularly inspect the electronics. Make sure all plug-in devices, cables and cords are well-connected. Keep the cabinet door closed when possible.

Opening the cabinet door will not help it cool down. Regularly inspect and clean the fans and filter nets to ensure better cooling effect.

5.) You are encouraged to utilize the machine and do not let it stay idle for long, especially in the first year. The more you use the machine, the more likely the machine will be in good condition in the future. If the machine stays idle for too long, the electronics are exposed to moist, heat, etc., thus reducing the service life of the machine. Make sure to power up the machine from time to time (at least once in a month) even you do not use it. Perform regular check and maintenance. Run the machine for one hour each time and the heat generated will help reduce the humidity.

This will also help you to discover problems with the machine in advance.

#### **More Maintenance Tasks:**

- 1.) Sweep and clean the table every day. Keep the machine clean and free of other objects.
- 2.) Check and clean all the limit switches every day.
- 3.) Check the lubricator every day and make timely refill.
- 4.) Check every day to ensure there is enough water in the water tank used for spindle cooling and whether that water tank is functioning.
- 5.) Check each of the tools is in correct position.
- 6.) Make sure the air compressor has the right air pressure.
- 7.) Make sure the filter cup of the water separator and dryer is dry.
- 8.) Wipe clean the linear guides and check if they have any scratches or damages.
- 9.) Make sure the protective covers on the machines are all intact.
- 10.) Make sure the fan in the electrical cabinet is working and there is no clogging in the air filter net. Clean the filter regularly.
- 11.) Make sure all the signal lights are functioning, all axes are in zero position and that tool holders and other accessories are in working order.
- 12.) Regularly check the oil bowl and water tank to see if they need refilling. Replace the liquid when necessary. Clean the oil bowl and water tank regularly.
- 13.) Sweep clean the electrical cabinet when necessary.

- 14.) Clean the filter net regularly, replace with new one when necessary.
- 15.) Make sure the wirings and connections are alright.
- 16.) Make sure all the valves and switches are functioning.
- 17.) Check all the cables, cords and terminals are in correct working order.
- 18.) Perform monthly check of the controller.
- 19.) Check if the electrical parts are making strange noises. If they do, replace them.
- 20.) Measure the backlash on all axes every half year. If you find any deviation, make sure to adjust or make compensation.
- 21.) Inspect all the electronics and relays to make sure they are working.
- 22.) Make sure the whole machine is still properly balanced after 6 months of service. If not, adjust the iron pads and tighten the screws.

# **Automatic Tool Change (ATC) Maintenance**

Protocol	Interval	Completed B
	interval.	<u>completed b</u>
Fully clean and inspect bearing rails for wear on all 3-Axis.	Quarterly	
Fill Oil Reservoir with 30W Oil.	Weekly	
Pump the Oil System once for every 8 hours of		
run time.	Every 8 Hours.	
Inspect all Oil Lines and verify every device is		
receiving oil. Bleed lines with large air bubbles.	Monthly	
Drop drive pinions, and verify motion is smooth	Yearly	
the length of travel in Y and X-Axis.	rearry	
Re-install pinion box's or Planetary gear box		
drive mechanisms. Set proper mesh and verify	Yearly	
with holding current present.		
For belt drive pinion box or Z-Axis drive belt, check drive belt condition. Replace if worn or	Overted	
degraded. Verify pulley alignment.	Quarterly	
For belt drive pinion box, or Z-Axis drive belt		
check belt tension. Verify with holding current	12	
present, and with it released that there is no	Quarterly	
slack in the belts.		
For Z-Axis with planetary gear box, verify		
coupler condition. Make sure alignment is	Quarterly	
correct and all fasteners are properly	Quarterly	
tightened.		
Inspect all tool holders for wear. Tighten all	Weekly, or	
pull studs. Replace any components with visual	when tooling	
wear.	is changed out.	
Wipe down all toolholders with oil saturated	Weekly, or	
cloth. Wipe off the excess oil completely.	when tooling	
	is changed out.	
In a second seco		
Inspect all tool holder clips. Replace any that are deformed or are loosely holding the tool	Quarterly	
holder.	Quarterly	
For liquid cooled spindles, inspect all water	Weekly	
lines and	WEERIY	
For liquid cooled spindles, Verify reservoir is		
always full of clean water and return water is a	Daily	
constant flow.  Verify all tool locations. Adjust any that have		
excessive motion during a tool change. Back up		
machine settings after tool location	Yearly	
adjustments.		
Check the spindles internal taper for		
imperfections, or rust. Clean completely and	Weekly	
lightly lubricate with oil saturated rag. Never	WEEKIY	
use compressed air on any spindle.		
For HSK style spindles. Lubricate monthly with		
MetaFlux Moly Spray. Never use compressed		
air for cleaning. Compressed air will destroy	Monthly	
any spindle by pushing debris into the precise		1

4.)	With power locked out, clean electrical cabinet, and tighten all connections on both sides of the panel.	Yearly
	With power locked out, tighten the electrical connections on the vacuum pump, and it's contactor/overload or the VFD that powers	Quarterly
	With power restored, carefully inspect that the cooling fans are fully functional.	Monthly
	Inspect and clean if needed, the filters on the electrical cabinets cooling system. Keep all foam inserts cleaned or cooling will be effected.	Monthly
	Test all Emergency stop's to insure they are fully functional. Verify recovery after E-stop is easily achieved.	Monthly
5.)	Clean Vacuum Pump Filters.	Inspect Weekly.
		Fully Clean Monthly.
	Check all vacuum pump connections. Do this over the entire plumbing to the table and it's manifold.	
	over the entire plumbing to the table and it's	Clean Monthly.

Inspect all pneumatic lines for wear, and or pinched/creased conditions.	Quarterly	
Check for air leaks at all fittings, Valves and regulators.	Quarterly	
Drain all water separators or service filters.	Weekly	
Inspect all air controlled pistons are moving at full travel and at the proper speed.	Quarterly	

# **Parts List**

Name	Part No.	Qty.
Cable	30402032	6
Cable	30402046	12
Inverter	3010302043	1
Brake resistor	3010601023	1
USB Cable	30317550	1
Transformer	30107041	1
Power supply	30114008	1
Driver	3010200007	4
Key switch	30109067 30109035	1
E-stop switch Self-recover switch	30109009	1
Self-recover switch	30109006	1
Self-locking switch	30109025	2
Breaker	30108137	1
Fuse core	30113042	2
Fuse core	30113037	2
Fuse core	30113030	1
Fuse core base	30113058	5
Breaker	30108095	2
AC contactor AC contactor	30110022 30110020	1 2
AL contactor	30110020	2
Name	Part No.	Qty.
Thermal relay	30112026	2
Breaker	30108047	1
Relay	30111007	3
Line adapter board	3010105002	1
Fan on the electric box	30115210	2
Dust screen	30115081	4
Ground strip	30115102	1
Ground strip	30115101	1
Electric box Handheld book	20220226 3010104018	1
Handheld hook Rotation handheld bracket	3010104018 20120147	1
Hand wheel cover plate	20202001	2
Aviation plugs	30405027	1
Self-recover button	30109024	1
	30402046 30402037	13.7 42.8
Ground Cable: From control box to machine, 54.5mm Dia. x 4M L (3010404026)	30402033	11.2
	30402032	2.5
	30402030	17.8
Proximity sensor	30404092	3
limit sudteb supporter		
Limit switch supporter	30404059	,
Limit switch supporter Name	30404059 Part No.	Qty.
Name	Part No.	Qty.
Name Dring cháin	Part No. 30403043	Qty.
Name Drag chain Drag chain	Part No. 30403043 30403210	Qty.
Name Drog chain Drog chain Proeumatic schematic diagram	Part No. 30403043 30403210 3040101519	Qty. 1 1 1
Name Drog chain Drog chain Drog chain Trog chain Terminal junction box	Part No. 30403043 30403210 3040101519 20221059	Qty.  1  1  1  1
Name Drag chain Drag chain Procurate schematic diagram Terminal Junction box Terminal cover plate	Part No. 30403043 30403210 3040101519 20221059 20221058	Qty.  1  1  1  1
Name  Drag chain  Drag chain  Pneumatis schematit diagram  Terminal junction box  Terminal cover plate  Tool sensor	Part No. 30403043 30403210 3040101519 20221059	Qty.  1  1  1  1
Name Drag chain Drag chain Procurate schematic diagram Terminal Junction box Terminal cover plate	Part No. 30403043 30403210 3040101519 20221059 20221058	Qty.  1  1  1  1
Name  Drag chain  Drag chain  Pneumatis schematit diagram  Terminal junction box  Terminal cover plate  Tool sensor	Part No. 30403043 30403210 304031519 20221099 20221058 30406014	Qty.  1  1  1  1  1  1
Name Drag chain Drag chain Preumatic schematic diagram Terminal junction box Terminal over plate Tool sensor	Part No. 30403043 30403210 3040101519 20221059 20221058 30406014 30406036	Qty.  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Drag chain  Proweumatic schematic diagram  Terminal junction box  Terminal cover plate Tool sensor Speed control valve  Hose joint	Part No. 30403043 30403210 3040101519 20221059 20221058 304060614 304060636 30401096	Qty.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Pneumatic schematic diagram  Terminal junction box  Terminal cover plate  Tool sensor Speed control valve  Mose joint  Mose joint  Mose joint	Part No. 30403043 30403210 3040101519 20221059 20221058 30406014 3040106 30401066 30401090	Qty.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Drag chain  Premunata schematic diagram  Terminal junction box  Terminal cover plate  Tool sensor  Speed control valve  Nose pinit  Nose pinit  Tool sensor supporter	Part No. 30403343 30403210 3040101519 20221099 20221058 30406014 30406036 30401906 30401127	Qty.  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain slot  Drag chain slot	Part No. 30403043 30403210 3040101519 20221058 30406014 30406016 30401096 30401990 30401177 20103117	Qey.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Dring chain  Dring chain  Progunates schematic diagram  Terminal junction box  Terminal cover plate  Tool sensor  Speed control valve  Mose joint  Mose joint  Mose joint  Mose joint  Mose joint  Xa ads Drag chain slot  X ads Drag chain slot	Part No. 30403043 30403210 3040101519 20221058 30406014 30401056 30401090 30401177 20202411 20202748	Clty.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Preventatic schematic diagram  Ferminal junction box  Terminal cover plate  Tool sensor  Speed control valve  Nose joint  Nose joint  Nose joint  Nose joint  Tool sensor supporter  Drag chain slot  Drag chain slot bracket	Part No. 30403043 304031210 3040101519 20221058 30406014 30406036 30401090 30401127 20103117 20103117 20202748 20202748	Chy.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Drag chain  Drag chain  Drag chain  Terminal junction box  Terminal cover plate Tool sensor Speed control valve  Mose joint  Mose joint  Tool sensor Speed control valve  Tool sensor Speed control valve  Mose joint  Tool sensor Speed control valve  Tool sensor Speed control valve  Tool sensor Supporter  Drag Chain slot Drag Chain slot Drag Chain slot bracket  Drag Chain for bracket	Part No. 30403943 30403210 30403210 20221059 20221058 30460014 30401096 30401090 30401127 20103117 20202411 202020485 20201045	1 1 1 1 1 1 1 1 1 1 1 2
Name  Drag chain  Drag chain  Preventatic schematic diagram  Ferminal junction box  Terminal cover plate  Tool sensor  Speed control valve  Nose joint  Nose joint  Nose joint  Nose joint  Tool sensor supporter  Drag chain slot  Drag chain slot bracket	Part No. 30403043 304031210 3040101519 20221058 30406014 30406036 30401090 30401127 20103117 20103117 20202748 20202748	Chy.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Dring chain  Dring chain  Dring chain  Dring chain  Terminal junction box  Terminal junction box  Terminal cover plate Tool sensor Speed control valve  Nose joint  Nose joint  Tool sensor supporter Dring chain slot bracket  Dring chain slot bracket  Button bracket	Part No. 30403043 30403210 3040101519 20221059 20221058 30406034 30406036 30401090 30401090 30401177 20202411 20202411 20202482 20201055 20204307 20206004	9 (h).
Name  Drag chain  Drag chain  Drag chain  Drag chain  Drag chain  Terminal junction box  Terminal cover plate Tool sensor Speed control valve  Mose joint  Mose joint  Tool sensor Speed control valve  Tool sensor Speed control valve  Mose joint  Tool sensor Speed control valve  Tool sensor Speed control valve  Tool sensor Supporter  Drag Chain slot Drag Chain slot Drag Chain slot bracket  Drag Chain for bracket	Part No. 304035043 30403510 3040101519 20221059 20221058 304060014 30406006 30401090 30401090 30401177 20100117 20202748 202021055 20202407 20206004 Part No.	1 1 1 1 1 1 1 1 1 1 1 2
Name  Dring chain  Dring chain  Dring chain  Dring chain  Terminal junction box  Terminal junction box  Terminal cover plate Tool sensor Speed control valve  Nose joint  Nose joint  Tool sensor supporter Dring chain slot bracket  Dring chain slot bracket  Button bracket	Part No. 30403043 30403210 3040101519 20221059 20221058 30406034 30406036 30401090 30401090 30401177 20202411 20202411 20202482 20201055 20204307 20206004	9 (h).
Name  Dring chain  Dring chain  Dring chain  Dring chain  Terminal junction box  Terminal cover plate  Tool sensor  Speed control valve  Hose joint  Hose joint  Hose joint  Tool sensor supporter  Dring chain slot bracket  Dring chain slot bracket  Dring chain slot bracket  Button bracket  Name	Part No. 304035043 30403510 3040101519 20221059 20221058 304060014 30406006 30401090 30401090 30401177 20100117 20202748 202021055 20202407 20206004 Part No.	0 ky.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name Drag chain Drag chain Drag chain Drag chain Drag chain Terminal junction box Terminal cover plate Tool sensor Speed control valve Mose joint Mose joint Mose joint Tool sensor supporter Drag chain slot Drag chain slot Drag chain slot bracket Drag chain plate of limited block United block	Part No. 30403943 30403210 30403210 20221059 20221058 30400014 30401096 30401090 304011090 30401127 20103117 20202411 20202748 20201045 20201045 20204087 20206004 Part No. 20220100	Qsy.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Drag chain  Drag chain  Terminal praction box  Tool sensor  Tool sensor supporter  Drag chain slot  X axis Toog chain slot  Drag chain slot bracket  Button bracket  Button bracket  Name  Transition plate of limited block	Part No. 30403943 30403210 3040101519 20221058 30400014 30401096 30401090 30401090 30401177 20003411 20002748 20001485 20004877 20206004 Part No.	Qty.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drig chain  Drig chain  Drig chain  Drig chain  Drig chain  Terminal Junction box  Terminal Cover plate  Tool sensor Speed control valve  Nose joint  Nose joint  Tool sensor supporter  Drig chain slot  Xia charge schai slot  Drig chain slot  Xia charge schai slot  Drig chain slot Xia  Ratio Drig chain slot  Xia charge schai slot  Drig chain slot Xia  Ratio Drig chain slot  Xia charge schai slot  Drig chain slot Xia  Lia charge schai slot  Drig chain slot Xia  D	Part No. 30403943 30403210 30403210 20221059 20221058 30400014 30401096 30401090 304011090 30401127 20103117 20202411 20202748 20201045 20201045 20204087 20206004 Part No. 20220100	Qsy.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Drag chain  Drag chain  Terminal purction box  Terminal purction box  Terminal cover plate Tool sensor Speed control valve  Mose joint  Mose joint  Mose joint  Tool sensor supporter  Drag chain slot  Zwas Drag chain slot  Drag chain slot  Drag chain slot bracket  Button bracket  Button bracket  Name  Tannition plate of limited block  Lunited block	Part No. 30403943 30403210 30403210 20221059 20221058 30400014 30401096 30401090 304011090 30401127 20103117 20202411 20202748 20201045 20201045 20204087 20206004 Part No. 20220100	Qsy.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Drag chain  Drag chain  Drag chain  Terminal praction box  Terminal cover plate  Tool sensor  Tool sensor  Soed control valve  Hose joint  Hose joint  Tool sensor  Drag chain slot  X axis Drag chain slot  Drag chain slot  Drag chain slot  Tarnstition plate of limited block  Limited block  Drag chain  Tarnstition plate of limited block  Limited block  Drag chain	Part No. 30403043 30403210 30401051519 20221058 304060614 30401090 30401177 20013117 20013117 2002248 20010055 20020407 200206004 Part No. 20220100 20120143 30403049	Qty.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Drag chain  Drag chain  Terminal junction box  Terminal cover plate Tool senoor Speed control valve  Nose piont  Nose piont  Nose piont  Tool sensor supporter  Drag chain slot  X axis Drag chain slot  Drag chain slot  Tong chain slot bracket  Drag chain bracket  Sustron bracket  Sustron bracket  Sustron bracket  Sustron bracket on  Zusak slog chain  Lover bracket on  Zusak slog chain  Lover bracket on	Part No. 30403043 30403210 30401051519 20221058 304060614 30401090 30401177 20013117 20013117 2002248 20010055 20020407 200206004 Part No. 20220100 20120143 30403049	Qty.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Drag chain  Drag chain  Drag chain  Terminal junction box  Terminal cover plate  Tool sensor  Tool sensor	Part No. 30403043 30403210 3040101519 20221059 20221058 30406014 30401096 30401090 30401107 2003117 2003241 20032748 20201045 20201045 20201045 20201041 20202104 20201041 20202104 20201040 2020100 20120143	Qty.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Drag chain  Drag chain  Terminal junction box  Terminal cover plate Tool senoor Speed control valve  Nose piont  Nose piont  Nose piont  Tool sensor supporter  Drag chain slot  X axis Drag chain slot  Drag chain slot  Tong chain slot bracket  Drag chain bracket  Sustron bracket  Sustron bracket  Sustron bracket  Sustron bracket on  Zusak slog chain  Lover bracket on  Zusak slog chain  Lover bracket on	Part No. 30403043 30403210 3040101519 20221059 20221058 30406014 30401096 30401090 30401107 2003117 2003241 20032748 20201045 20201045 20201045 20201041 20202104 20201041 20202104 20201040 2020100 20120143	Qty.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Drag chain  Drag chain  Terminal purction box  Terminal cover plate Tool sensor Speed control valve  Mose joint  Mose joint  Mose joint  Tool sensor supporter  Drag chain slot  Tool sensor supporter  Drag chain slot bracket  Drag chain bracket  Drag chain slot bracket  Drag chain slot bracket  Drag chain slot of limited block  Limited block  Drag chain  Lipper bracket on  Z auds drag chain  Lower bracket on  Z auds drag chain	Part No. 30403043 30403210 30403210 20221059 20221058 30406014 30401096 30401096 30401097 20021017 2003117 20020411 20020748 20201045 20201045 20201045 20201045 20201049 20120143 30403049 201006008	Qsy.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name Drag chain Drag chain Drag chain Drag chain Drag chain Drag chain Terminal punction box Terminal cover plate Tool sensor Speed control valve Hose joint Hose joint Hose joint Drag chain slot X axis Torg chain slot Drag chain slot Drag chain slot Trag chain slot Drag chain	Part No. 30403043 30403210 304010519 20221058 304010514 30401096 30401090 30401177 20203411 20202748 20203417 20202412 20202418 20202418 20204099 Part No. 20220100 20120143 30403049 20106008	Qty.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name Drig chain Terminal Junction box Terminal cover plate Tool sensor Speed control valve Note piont Note piont Tool sensor supporter Drig chain slot X axis Drig chain slot Drig chain slot Drig chain slot bracket Drig chain Dri	Part No.  30403043  30403210  304010519  20221058  304060614  30401096  30401090  30401177  200103117  2002248  20010457  20020407  20020407  20020407  200206004  Part No.  20220100  20120143  30403049  20160608  2001068  2001068  2001068	Qty.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name  Drag chain  Drag chain  Drag chain  Drag chain  Drag chain  Terminal purction box  Terminal cover plate Tool sensor Speed control valve  Mose joint  Mose joint  Mose joint  Mose joint  Mose joint  Dool sensor supporter  Drag chain slot  Transition plate of limited block  Limited sheet	Part No.  30403510  30403510  30403510  20221059  20221058  30406014  30401096  30401090  30401090  30401127  20203117  20202411  20202411  20202748  20201045  20201045  Part No.  20220100  20120143  30403049  20100508  20101058  20201068  20201068  20201065  20201065  20201065  20201065	Qsy.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name Drag chain stee Drag chain Dr	Part No.  30403043  30403210  304010519  20221059  20221058  30401061  30401090  30401090  304011090  30401127  20103117  20202141  20202748  20201045  20201045  20201049  Part No.  2020100  20120143  30403049  20106008  20201068  20201068  20201065  20201067  2021106  20201067  2021106	Qty.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name Dring chain Dring chain Dring chain Dring chain Dring chain Dring chain Terminal junction box Terminal cover plate Tool sensor Speed control valve Mose joint Mose joint Mose joint Mose joint Mose joint Dool sensor supporter Dring chain slot Dring chain slot Dring chain slot bracket Dring chain slot slot slot slot slot slot slot slot	Part No.  30403510  30403510  30403510  20221059  20221058  30406014  30401096  30401090  30401090  30401127  20203117  20202411  20202411  20202748  20201045  20201045  Part No.  20220100  20120143  30403049  20100508  20101058  20201068  20201068  20201065  20201065  20201065  20201065	Qsy.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name Drag chain stee Drag chain Dr	Part No.  30403043  30403210  304010519  20221059  20221058  30401061  30401090  30401090  304011090  30401127  20103117  20202141  20202748  20201045  20201045  20201049  Part No.  2020100  20120143  30403049  20106008  20201068  20201068  20201065  20201067  2021106  20201067  2021106	Qty.  1  1  1  1  1  1  1  1  1  1  1  1  1
Name Drag chain solor Drag chain	Part No.  30403043  30403210  304010519  20221058  30400614  30401096  30401090  30401177  20203117  20203117  20203411  20203748  20203407  20204004  Part No.  20220100  20120143  30403049  20106008  20101058  20201068  20201065  20201065  20201067  20201066  20201066  20201067  20201066  20201066  20201066  20201067  20201066  20201066  20201066  20201066  20201066  20201066  20201066  20201066  20201066  20201066	Qty.  1  1  1  1  1  1  1  1  1  1  1  1  1

### **Warranties & Policies**

#### **Dealer Machinery Warranty**

New woodworking machines sold by Laguna Tools carry a two-year warranty effective from the date of dealer invoice to customer/end-user. Machines sold through dealers must be registered with Laguna Tools within 30 days of purchase to be covered by this warranty. Laguna Tools guarantees all new machine sold to be free of manufacturers' defective workmanship, parts and materials. We will repair or replace, without charge, any parts determined by Laguna Tools, Inc. to be a manufacturer's defect. We require that the defective item/part be returned to Laguna Tools with the complaint. The end-user must request an RMA (return material authorization) number from Customer Service and include the (RMA) number with any and all returned parts/components requesting warranty coverage.\* Any machines returned to Laguna Tools must be returned with packaging in the same manner in which it was received. If a part or blade is being returned it must have adequate packaging to ensure no damage is received during shipping. In the event the item/part is determined to be damaged due to lack of maintenance, cleaning or misuse/abuse, the customer will be responsible for the cost to replace the item/part, plus all related shipping charges. This limited warranty does not apply to natural disasters, acts of terrorism, normal wear and tear, product failure due to lack of maintenance or cleaning, damage caused by accident, neglect, lack of or inadequate dust collection, misuse/abuse or damage caused where repair or alterations have been made or attempted by others.

\*\*NOTE: Issuing an RMA number is for referencing materials and issues, it does NOT indicate warranty acceptance/conformity.

Laguna Tools is not responsible for errors or omissions. Specifications subject to change. Machines may be shown with optional accessories.

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### **CNC Limited Warranty**

#### **CNC Limited Warranty**

New CNC machines sold by Laguna Tools carry a one-year warranty effective from the date of shipping. Laguna Tools guarantees allnew machine sold to be free of manufacturers' defective workmanship, parts, and materials. We will repair or replace without charge, any parts determined by Laguna Tools, Inc. to be a manufacturer's defect. We require that the defective item/part is determined to be damaged due to lack of maintenance, cleaning or misuse/abuse, the customer will be responsible for the cost to replace the item/part, plus all related shipping charges. This limited warranty does not apply to natural disasters, acts of terrorism, normal wear andtear, product failure due to lack of maintenance or cleaning, damage caused by accident, neglect, lack of or inadequate dust collection, misuse/abuse or damage caused where repair or alterations have been made or attempted by others. Laguna Tools, Inc. is not responsible for additional tools or modifications sold or performed (other than from/by Laguna Tools, Inc.) on any Laguna Tools, Inc. woodworking machine. Warranty maybe wided upon the addition of such described tools and/or modifications, determined on a case-by-case basis. Software purchased through Laguna Tools, Inc., is not covered under this warranty and all technical support must be managed through the software provider. Normal user alignment, adjustment, tuning and machine settings are notcovered by this warranty. It is the responsibility of the user to understand basic woodworking machinery settings and procedures and to properly maintain the equipment in accordance with the standards provided by the manufacturer. Parts under warranty are shipped at Laguna Tools, Inc.'s cost either by common carrier, FEDEX ground service or a similar method. Technical support to install replacement parts is primarily provided by phone, fax, e-mail or Laguna Tools Customer Support Website. The labor required to install replacement parts is the responsibility of the user. Laguna Tools is not responsible for damage or loss caused by a freight company or other circumstances not in our control. All claims for loss or damaged goods must be notified to Laguna Toolswithin twenty-four hours of delivery.

\*\*\*\*Please contact our Customer Service Department for more information. Only NEW machines sold to the original owner are covered by this warranty. For warranty repair information, call 1-800-332-4094. Copyright 2013 Laguna Tools, Inc. \*\*Warning –no portion of these materials may be reproduced without written approval from Laguna Tools, Inc.



## **Modifications Policy**

#### No Modifications Allowed or Sold

Laguna Tools, Inc. is not responsible for additional tools or modifications sold or performed (other than from/by Laguna Tools, Inc.) on any Laguna Tools, Inc. woodworking machine. Warranty maybe voided upon the addition of such described tools and/or modifications, determined on a case-by-case basis. Normal user alignment, adjustment, tuning and machine settings are not covered by this warranty. It is the responsibility of the user to understand basic woodworking machinery settings and procedures and to properly maintain the equipment in accordance with the standards provided by the manufacturer. Parts, under warranty, are shipped at Laguna Tools, Inc.'s cost either by common carrier, FEDEX ground service or a similar method. Technical support to install replacement parts is primarily provided by phone, fax, e-mail or Laguna Tools Customer Support Website. The labor required to install replacement parts is the responsibility of the user. Laguna Tools is not responsible for damage or loss caused by a freight company or other circumstances not in our control. All claims for loss or damaged goods must be notified to Laguna Tools within twenty-four hours of delivery. Please contact our Customer Service Department for more information. Only new machines sold to the original owner are covered by this warranty.

For warranty repair information, call 1-800-332-4094. No Modifications Allowed or Sold.

# Return Materials Authorization (RMA) Procedure

#### Laguna Tools Packaging/RMA Example Procedure

\*\*Any machines returned to Laguna Tools must be returned with packaging in the same way it was received. If a part or blade is being returned it must have adequate packaging to ensure no damage is received during shipping. In the event the item/part is determined to be damaged due to lack of maintenance, cleaning or misuse/abuse, the customer will be responsible for the cost to replace the item/part, plus all related shipping charges.

We require that the defective item/part be returned to Laguna Tools with the complaint. The end-user must request an **RMA** (**Return Material Authorization**) **Number** from Customer Service and include the (RMA) number with all returned parts/components requesting warranty coverage.

#### (Return Material Authorization)



