# LAGUNA TOOLS

# Laguna Tools-Smartshop J8 Machine-

<u>Owner's Manual-</u> Overview of Machine, Start-Up Procedure, Control Software Introduction, Running a Program, Troubleshooting, Maintenance



Laguna Tools: 744 Refuge Way Grand Prairie, TX U.S.A. Service: +1 (800) 234-1976 or email: customerservice@lagunatools.com Swift Series CNC Machines © 2021 Laguna Tools 10/01/2021

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## **Features and Applications-**

The Smartshop J8 can precisely and consistently route several types of standard joints. From classic mortise and tenon joinery to lockset and hinge mortising, the J8 comes with a 4.5HP air-cooled spindle, Delta Servo Motors and Drivers, a central lubrication system, pneumatic positioning pop-up pins, and a DSP handheld control system.

#### Features:

Strengthened Steel Structure 4.5HP Air Cooling Spindle 5HP Delta Inverter DSP Control System 750w Delta Servo Motor & Driver Bakelite Table Lubrication System Pneumatic Pop-Up Pins UL Cable & Electric Components

#### Frame & Gantry:

- Welded once piece steel frame
- Helical Rack and pinion drive system X-Axis
- Precision ground ball screw on Y and Z-Axis
- Delta Servos
- Shipping Weight: 2500 lbs.
- Shipping Dimensions (W x L X H): 42.3" x 49" x 43"

## Features and Applications (Cont'd.)-

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## **Applications:**

- Classic Mortise and Tenon
- Floating Mortise and Tenon
- Finger Joints
- Louvered Grooves
- Lockset Mortising
- Hinge Mortising
- Drilling
- Doweling

## Features and Applications (Cont'd.)-

## **Additional Features:**

4ft. or 8ft. Capacity
2-Zone Workstation
6 in. of Z-Axis Travel
Max. Trenon 1.5 in.
4.5HP Air Cooled Spindle
DSP Handheld Controller
Delta Servo Motors
Pneumatic Hold Down
3-Axis Interpolation



4.5HP Air Cooled Spindle with Delta Servo Motors



DSP Handheld Controller for Quick Programming



4" Inch Material Thickness Capacity

## **Receiving New Machine-**

**Note:** It is probable that your machine will be delivered by a third party. Before you unpack your new machine, you will need to first inspect the packing, invoice and shipping documents supplied by the driver. Ensure that there is no visible damage to the packing or the machine. You need to do this prior to the driver leaving. All damage must be noted on the delivery documents and signed by you and the delivery driver. You must then contact the seller (Laguna Tools) as soon as practical. If damage is found after delivery, contact the seller as soon as is practical.

**Note:** It is probable that you will find sawdust within your machine. This is because the machine has been tested prior to shipment from the factory and / or Laguna Tools. Laguna Tools endeavors to test machines prior to shipping to customers as movement can take place during transportation. It must be noted that additional machine movement can take place between Laguna Tools and the end user, and some adjustments may have to be undertaken by the customer. These adjustments are covered in the various sections of this manual.

## **Unpacking your Machine-**

To unpack your machine, you will need tin snips, a knife, and a wrench.

1.) Using the tin snips, cut the banding that is securing the machine to the Pallet [if fitted]. WARNING: EXTREME CAUTION MUST BE USED BECAUSE THE BANDING WILL SPRING AND COULD CAUSE INJURY.

2.) Remove the box from the CNC machine if fitted and any other packaging material. The parts ordered with the machine will be packed on or inside the machine. Note. The machine is heavy, and if you have any doubt about the described procedure, seek professional assistance. Do not attempt any procedure that you feel is unsafe, or that you do not have the physical capability of achieving.

3.) Use a forklift with sufficient lifting capacity and forks that are long enough to extend the complete width of the machine.

4.) Remove the securing bolts that attach the machine to the pallet [if fitted].

5.) Approaching the machine from the side, lift the machine on the frame taking care that there are no cables or pipes around the forks.

6.) Move the machine to the required position and lower gently to the floor.

## **Unloading Requirements-**

1.) When the Crate containing your newly purchased Smartshop<sup>®</sup> Laser/CBX is delivered, it will be delivered "Curbside", in other words the Machine will be delivered in front of the Driveway of one's Garage/Shop or Workspace. (\*\*\*\*It is the Purchasers responsibility of moving the Machine into His or Hers Garage/Shop or Workspace. \*\*\*\*)

2.) One should obtain a Crane: Hydraulic crane / crane (10T or above, 4 groups of 10T rings, 2 10M long, 10T straps).

3.) One should obtain a Forklift: The forklift can fork items weighing 10T or more.

4.) To Open Crate-Acquire some standard tools for taking apart the Crate.

a.) Hammer.



b.) Pry Bar.

## **Unloading Requirements-**

## c.) Wire Cutters.



d.) Cordless Drill.



5.) Cut all straps only on the Crate.



6.) Unscrew a series of Screws at the Base of Crate using a Cordless Drill.



7.) Unscrew and Remove Side Panels of Crate.







## Where to locate your Machine-

Before you unpack your machine, select the area where you will use your machine. There are no hard and fast rules for its location, but below are a few guidelines.

1.) There should be an area around the machine suitable for the length of material that you will be machining.

2.) **Adequate Lighting:** The better the lighting, the more accurately and safely you will be able to work.

3.) Solid Floor: You should select a solid flat floor, preferably concrete or something similar.

4.) Close to a Power Source (220V-Volt Capacity) and Dust Collection, (Proper created Ventilation Holes Suggested).

## **Smartshop J8 Standard Damage Notification-**

1.) The Machines are thoroughly tested before leaving any or our Laguna Tools Facilities, but that does not mean the Machines would not experience any damage in transit.

2.) Before one Signs the Bill of Lading (See Example Below) when the Trucking Company drops off the Machine, visually inspect the entire crate and check for any damage.

SHIP FROM Laguna Tools 744 Retuge Way Suite #200 Grand Prainie, TX 75050 SID No.:								Bill of Lading Number:					
								BAR CODE SPACE					
SHIP TO								Carrier Name:					
Name] [Street Address] [City, <u>ST_ZIP</u> Code] [CI No.:								Trailer number: Serial number(s):					
THIRD PARTY FREIGHT CHARGES BILL TO								SCAC:					
Name] [Street Adross] [City, <u>ST_ZIP</u> Code] Special Instructions:								Pro Number: BAR CODE SPACE					
								Freight Charge Terms (#reight charges are prepaid unless marked otherwise): Prepaid Collect 3rd Party					
								Maste	r bill of l	lading wit	th attached underlying b	vills of lading.	
						CUSTOM	ER ORDER	INFOR	MATIO	N			
Custom	ner Order	No.				# of Pa	ckages   W	veight	Paire (circl	st/Slip le one)	Additional Shipper In	nformation	
									Y	Ν			
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									Y	N			
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## Safety Protocols-

## Safety Rules

As with all machinery there are certain hazards involved with the operation and use of this machine. Using it with caution will considerably lessen the possibility of personal injury. However, if normal safety precautions are overlooked or ignored, personal injury to the operator may result. If you have any questions relative to the about its installation and operation, do not use the equipment until you have contacted your supplying distributor.

## Read items stated below carefully before operating the machine:

1.) Keep the working area clean and be sure adequate lighting is available.

2.) Do not wear loose clothing, gloves, bracelets, necklaces, or ornaments.

3.) Wear face, eye, respiratory and body protection devices as indicated for the operation or environment.

4.) Be sure that the power is disconnected from the machine before tools are serviced or an attachment is to be fitted or removed.

- 5.) Never leave the machine with the power on.
- 6.) Do not use dull, gummy, or cracked cutting tools.

7.) Be sure that the keys and adjusting wrenches have been removed and all the nuts and bolts are secured.

### **Specification Sheet of the Smartshop J8-**





## {MCNC SS-J8} 3 AXIS HORIZONTAL CNC

SPECIFICATION:			
	DRAWN,S.B8/21/2020_REV,1		
POWER REQUIREMENTS.	220V,30A,1 PH.		
FOOTPRINT.	132" W X 56" L X 51.5" TALL		
WORKING AREA.	4" Y * 96" X * 3" Z, TRAVEL		
GANTRY CLEARANCE.	4" MATERIAL THICKNESS		
SPINDLE.	4HP MT, AIR COOLED SPINDLE		
SPINDLE RPM.	6,000-24,000		
RAPID TRAVEL.	600 IPM		
CENTRALIZED OIL SYSTEM.	YES		
DUST PORT DIAMETER.	4"		
PRECISION HELICAL RACK & PINION.	20MM HEAVY DUTY LINEAR		
DRIVE SYSTEM FOR X AND Y AXES	BEARING,ALL AXES		
CONTROLLER.	LAGUNA HAND HELD DSP CONTROLLER		
MDF TABLE TOP WITH TEE SLOTS.	NO, PNUEMATIC CLAMPING		
SOLID STATE HOME SWITCH'S.	YES		
HEAVY DUTY WELDMENT TUBULAR			
STEEL FRAME.	1200 POUNDS		
DRIVE SYSTEM	DELTA SERVO SYSTEM		

## Parts of the J8 Machine-

The CNC machine consists of a few major parts, which are discussed in this manual. Take the time to read this section and become familiar with the machine.



## Parts of the J8 Machine (Cont'd.)-



The <u>"Emergency</u> <u>Stop</u>", One can Release or Disengage Button by twisting clockwise, and it will pop out.



Press the <u>"Start Button"</u> that will turn power on to the machine.



Turn the Main Power Isolation Switch Clockwise to the <u>"On"</u> Position. Turn Counterclockwise to the <u>"Off"</u> Position.



Hand-Held Controller

## Parts of the J8 Machine (Cont'd.)-



## How to Power Up & Turn "On" & "Off" the Smartshop J8 CNC Machine-

No cable is supplied as this will depend on the local wiring codes and your electrical supply. Ensure that when installing the electrical supply to the machine that 220v (220 Volts) single phase is supplied.

It is recommended that you use a 30-amp Breaker.

Wire to Terminal L1 & L2. Terminal L3 is not used.

**Note:** When wiring the machine to your electrical system, keep your cable as short as possible and the cable should not be allowed to run along the floor, as this will cause a trip hazard. There is a cable that has a female electrical socket for connection to the water pump. **Note:** A qualified electrician must carry out the electrical installation.



### How to Install Power & Turn "On" & "Off" the Smartshop J8 CNC Machine (Cont'd.)-

- After installing cable for the 220v (220 Volts) Outlet.
   <u>Note</u>: A qualified electrician must carry out the electrical installation.
- 2.) Turn the Main Power Isolation Switch Clockwise to the <u>"On"</u> Position.



Turn the Main Power Isolation Switch Clockwise to the <u>"On"</u> Position. Turn Counterclockwise to the <u>"Off"</u> Position.

### How to Install Power & Turn "On" & "Off" the Smartshop J8 CNC Machine (Cont'd.)-

- 3.) Make sure <u>"Emergency Stop</u>" is disengaged, one can Release or Disengage Button\_by twisting clockwise, and it will pop out.
- 4.) Press the "Start Button" that will turn the power <u>"On"</u> to the machine & HHC Controller.



## How to Install Power & Turn "On" & "Off" the Smartshop J8 CNC Machine-

1.) Pull the "Start Button" out, that will turn the power <u>"Off"</u> to the machine & HHC

Controller.



2.) Turn the Main Power Isolation Switch Counterclockwise to the <u>"Off"</u> Position.



#### How to engage the "Emergency Shut Off "on the Smartshop J8 CNC Machine-

**Emergency Stop Cord** 



In case an Emergency Stop needs to be performed, one can pull the <u>"Emergency Stop Cord"</u>.



The <u>"Emergency Stop Button</u>" can be pushed in case an Emergency Stop needs to be performed. To release or Disengage Button twist button clockwise, and it will pop out & disengage.

### How to align Projects on the Bed of the Smartshop J8 CNC Machine-



## How to align Projects on the Bed of the Smartshop J8 CNC Machine (Cont'd.)-

## Parts of the J8 Machine (Cont'd.)-





#### How to Zero Out the Electrical Spindle Router of the Smartshop J8 CNC Machine-

1.) Press the "Start Button" that will turn the power <u>"On"</u> to the machine & HHC Controller.



2.) On the HHC-Handheld Controller Press the <u>"Green"</u> Button that states <u>"Origin OK"</u>, Press Button and release and the Spindle Assy. will go to the <u>"Home Position"</u>.





#### How to Control the Electrical Spindle Router of the Smartshop J8 CNC Machine-

(\*\*\*Picture may not represent current produced Machine.) To move the Spindle in either X, Y & Z Directions, one can



push appropriate Buttons on the HHC-Handheld Controller.

+/- Z-Axis



For the <u>"Z" Axis</u> Press the <u>Z+ or Z-</u> <u>Buttons</u> on the HHC.

For the <u>"X" Axis</u> Press the <u>X+ or X-</u> <u>Buttons</u> on the HHC.



For the <u>"Y" Axis</u> Press the <u>Y+ or Y-</u> <u>Buttons</u> on the HHC.

## <u>J8 CNC Machine-Set Up the Machine: Different Modes & How to change of the CNC Machine</u> <u>Modes-</u>



When one continues to Press on any of the Buttons, the Spindle will continue to move in that direction. That is called " <u>Continuous Mode</u>".





When presses the "<u>MODE</u>" Button, the mode will change . That is called "<u>Step Mode</u>"- This Mode will allow the Spindle to move a certain distance in any direction.



#### J8 CNC Machine-Set Up the Machine: How to Control the Step Distances.-



The Step Distances are controlled by the "HIGH/LOW" Button. Press the "HIGH/LOW" Button, one can switch the mode distances.











If one presses any of the directional buttons in "High" Mode, the Spindle will move a 1/2mm or .020 in.

If one presses any of the directional buttons in "Low" Mode, the Spindle will move a 1/10 mm or .004 in.

### J8 CNC Machine-Set Up the Machine: Moving the Spindle at a Specific Distance-

"Press the High/ Low Button Twice or 2 Times"



"Press he Mode" Button one more time.





The Distance shows up will be 100 or 100.00 mm.





2.) Press the OK Button that will **Lock-In** the 100 mm distance.



3.) Press any of the directional buttons and the Spindle will move 100 mm.

### J8 CNC Machine- Set Up the Machine: Tool Set up & Changing.-



On the HHC-Handheld Press the "<u>Green</u>" Button that states <u>"Origin OK"</u> to go to the Home Position.



To Turn the Spindle "ON" & "OFF", Press the "ON" & "OFF" Button.

## <u>J8 CNC Machine-Set Up the Machine: Programming "Touching Off"-</u> <u>Setting Origin-</u>



1.) Press the Y- & 6 Button continuously until Router Tool almost touches the Top of the Project.



2.) Press #8 Button (Z Arrow-0) to Set the "Z" Origin.



3.) "Z" Origin is now set to "0".

## Type of Routers that can be used of the Smartshop J8 CNC Machine-

Examples:

5-Pack SC Spiral O Single Flute, Aluminum Cutting 1/8 D x 1/2 CH x 1/4 SHK x 2 Inch Long Up-Cut

**Router Bits with Mirror Finish-**



5-Pack SC Spiral Plunge 1/4 D x 3/4 CH x 1/4 SHK x 2-1/2 Inch Long 2 Flute Up-Cut Router Bits



## How to use the HHC Controller/Rich Auto Programming of the Smartshop J8 CNC Machine-

## **Rich Auto System Introduction:**

Rich Auto is CNC motion control system independently developed and it can be widely applied to machinery, advertisement, woodworking, mold engraving machine, laser, flame, plasma cutting machine, and so on in the machine control field.

Rich Auto make DSP as the core control system High-speed processing operation is the microcontroller, PLC systems can't match Use embedded structure, high degree of integration, strong stability easy to installation and operation disk support Removable storage card reader With USB Interface High speed transfer, Plug and play the full realization of all work offline.

## **Characteristics:**

1.) System deploys standard X, Y, Z axis motion control method, Support the rotation axis control. This enables to switch the processing of surface and processing of rotation; up extended to X, Y, Z, C four-axis motion control, Implementation four axis interlocking Control.

2.) Multi I / O Point Control there is eight input and output signals in every basic I / O signal node Expansion I / O node can be expanded to 32 input and output signals $_{\circ}$ 

3.) Support the standard G-Code, PLT format instructions; support domestic and international mainstream CAM software, such as: Type3, Art cam, UG, Pro / E, Master CAM, Cimatron, Wentai etc.

# How to use the HHC Controller/Rich Auto Programming of the Smartshop J8 CNC Machine-

## Characteristics (Cont'd.):

4.) Provide with power-down protection. Instantaneous power processing system to automatically save the current processing of information (file name, current line number processing, processing speed, spindle threshold), when power again machine moves back, the system automatically prompts the user to restore the processing before power down, the processing operations become more humanity.

5.) Support breakpoint memory, file selection, processing. Save 8 different breakpoint processing information.

6.) Multi-coordinate memory function. Provide nine working coordinate system, the user can switch among the 9-coordinates, each coordinate system can save a process origin information.

7.) Support online to adjust spindle operating frequency. The spindle frequency from 0 to maximum frequency is divided into 8 thresholds; 1 - 8 threshold can be processed directly adjust up and down without suspend processing.

8.) Support and adjust speed ratio online. Users can adjust the speed ratio, to adjust the processing speed and empty running speed, speed ratio values from 0.1-1, Ascending or descending per 0.1 numerical.

# How to use the HHC Controller/Rich Auto Programming of the Smartshop J8 CNC Machine-

## Characteristics (Cont'd.):

9.) Simply manual operate mode. In manual mode, the system provides three kinds of sports concluding continuous, step (crawl), distance, manual operation becomes simpler and more convenient.

10.) Identifies M-Code, F-Code, and other development commands can open a special code based on user needs.

11.) Built-in 512 M memory.

12.) Unique handheld form factor with one hand to hold. Own liquid crystal display and 16 button buttonboard, operate intuitive and flexible, no longer dependent on the computer, the full realization of full offline operation

13.) Comes with USB communications port, file transfer efficiency can be directly read U disk, card reader file, Plug and Play.

14.) Self-test function, the system comes with I / O port signal detection capabilities, ease of remote maintenance.

15.) Processing with high-speed and smooth, support high subdivides, make sure processing with high accuracy and high speed.
# Characteristics (Cont'd.):

16.) Unique in Chinese English to show double interface, can be realized in switching Chinese and English show online.

17.) multi-language display. Support for Simplified Chinese, Traditional Chinese, English, Russian, French, and other languages, can be customized according to user needs.

18.) System can support automatic dynamic upgrades, convenient to remote operation, remote maintenance.

# System Composition-

<u>**Rich Auto Control System</u>** contains the following parts: A hand-held motion controller(handle), a line adapter board (interface board), a 50-pin data transmission cable, an USB communication cable.</u>



Hand-Held Motion Controller

# **Rich Auto Accessories Schematic Diagram**



**Rich Auto Interface Board** 

**Rich Auto Accessories Schematic Diagram** 



50-Pin Data Transmission Cable



USB Communication Cable

# How to use the HHC Controller/Rich Auto Programming of the Smartshop J8 CNC Machine Description of Each Component

# 1.) Handheld Controller (Handle)-6 Components:

**a.)** <u>LCD Screen</u>: 128 \* 64 resolution LCD display, to display the machine motion, system settings and other information.

**b.)** <u>Keyboard</u>: Contains 16 buttons to input system parameter information and operate the machine.

c.) <u>U-Disk Interface</u>: The port of U-Disk (FAT16/32) and the memory card.

**d.)** <u>50-pin Data Cable Port</u>: The port of 50-pin data cable it connects the handle with the interface board to realize controlling the machine.

e.) <u>USB Communication Port</u>: The port of USB communication cable. It is used to connect the handle with your computer.



# **Description of Each Component**-

2.) Interface Board: Includes 5 Parts-



- a.) **<u>50-Pin Data Cable Port</u>**: Connect Handle with Interface Board.
- b.) J7-Output Control Terminal: Including spindle on/Off Signal, Work & Alarm LED Signal etc.

c.) **J8-Input Control Terminal:** Including machine origin detection switch, Tool Setting, Driver Alarm, Hard Limit Switch, and E-Stop Signal.

- d.) Input Control Terminal: DC24V, 3A.
- e.) Motor Driver Control Terminal X-Axis, Y-Axis, Z-Axis, C-Axis.

Description of Each Component (Cont'd.)-



50-Pin Data Transmission Cable

4.)

3.)



**USB** Communication Cable

# **Controller Button Introduction & Functions-**

**<u>Note</u>**: There is a comprehensive manual for the hand-held controller. Below is a list of the main key functions. The controller may vary from that shown.

**<u>Rich Auto Motion Control System</u>**: Defines 16-Buttons according to functional requirements. Each button has one or more functions under different work status.



<u>X+/1</u> = Moves the gantry in the X direction away from the home end of the bed. <u>Y+/2</u> = Moves the gantry in the Y direction away from the home end of the bed. <u>Z+/3</u> = Moves the router head in the Z [Up direction] away from the table surface. XY-0/4 = Set's Machine "Origin".

# **Controller Button Functions (Cont'd.)-**



<u>X-/5</u> = Moves the gantry in the X direction towards the home end of the bed.

<u>Y-/6</u> = Moves the router head in the Y direction towards the home end of the bed.

- Z / 7 = Moves the router head in the Z (Down Direction) towards the table surface.
- **<u>Z-0 / 8</u>** = Used set the tool to the "Zero" surface (Tool "Touch-Off".)

Controller Button Functions (Cont'd.)-



**HOME / 9** = Causes the machine to move to the "Home" position, first in the Z-Axis, followed by X and then Y. (Home is a mechanically determined position using mechanical switches/sensors.)

**<u>HIGH/LOW / 0</u>** = Toggles jogging speeds between High and Low ranges.

**<u>ONOFF/</u>**. = Turns the Router Spindle on and off.

**MENU** / \_ = Provides access to various setup features.

**Controller Button Functions (Cont'd.)-**



**ORIGIN /OK** = Use to accept commands ("On".) Origin causes machine to the machines "Origin".

**MODE** = Toggles between the three jogging modes: Continuous, Step or Distance.

"RUN/ PAUSE / DELETE" = Used to load a program from either the USB drive or internal memory. While the program is running, causes the operation to <u>"Pause"</u>.

**<u>STOP / CANCEL</u>** = Stops a running program. Also used to cancel commands.

### **Assembling the Controller:**

Fit the Cable to the controller and ensure that the screws are finger tight.



**<u>Note</u>**: When using a memory stick, it fits into a slot on the top of the hand-held controller and must not exceed 8G in capacity.





**USB** Communication Cable



# Interface Board Shell Size-

Scale: 1:1, Unit: mm

### **Usage Mode of Controller-**

Rich Auto motion control system provide two modes of buttons' operations, including one-touch button & Combination button.

**One-Touch Button:** Press one button on handle.

<u>Combination Button</u>: Press two buttons at the same time to achieve the operation. <u>The Operation Step</u>: Press one main function button and meanwhile press a second accessibility button, and then release the two buttons at the same time to realize the combination button operation.

# List of Combination Buttons:

	<b>Combination Button</b>	Function
1	MENU "	Switch the coordinate system (0 for the mechanical coordinate system , 1 - 9 for the work coordinate system).
2	MENU ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	Start Z-Axis Automatic Tool Setting.
3	RUNPAUSE DELETE "+"1-8" Number Buttons	Start the Breakpoints Processing, (Support Number 1 - 8).

How to use the HHC Controller/Rich Auto Programming of the Smartshop J8 CNC Machine-List of Combination Buttons (Cont'd.):

	Combination Button	Function
4	RUN/PAUSE DELETE ,+**	Start Advanced Processing.
5	$\begin{bmatrix} ON/OFF \\ \cdot \\$	To switch gear shaft under manual mode.
6	RUNPAUSE DELETE ,+ 9,,	Repeat last time processing.
7	"(MODE)" +"(Z+0 8)"	Set Stop Position.
8	MENU - ,,+« ORIGIN OK ,,	System Upgrade.
9	MENU - ,,, MODE,,	Operate Machine by Entering Coordinates Parameters.
10	ORIGIN OK ,+ CANCEL,	Quit Buttons Check.

# **Detail Information for Buttons Function:**

Name	Function
X + 1 ▲	Positive movement of X-Axis, menu upward , Figure 1 Inputting.
Y + 2 ^	Positive movement of Y-Axis, speed-up processing speed, Figure 2 inputting.
Z + 3	Positive movement of Z-Axis, Figure 3 inputting, Increase Spindle Speed during Processing.
XY→0 4	Set X-Axis and Y-Axis Work Origin, Figure 4 inputting.
X- 5▼	Negative movement of X-Axis, Menu Downward, Figure 5 Inputting.
Y − 6∨	Negative movement of Y-Axis, Slow Down Processing Speed, Figure 6 inputting different property selecting in Menu.

# **Detail Information for Buttons Function (Cont'd.):**

Name	Function
X+ 1▲	Positive movement of X-Axis, menu upward , Figure 1 Inputting.
Y + 2 ^	Positive movement of Y-Axis, speed-up processing speed, Figure 2 inputting.
Z+ 3	Positive movement of Z-Axis, Figure 3 inputting, Increase Spindle Speed during Processing.
XY→0 4	Set X-Axis and Y-Axis Work Origin, Figure 4 inputting.
X - 5 ▼	Negative movement of X-Axis, Menu Downward, Figure 5 Inputting.
Y - 6∨	Negative movement of Y-Axis, Slow Down Processing Speed, Figure 6 inputting different property selecting in Menu.

# **Detail Information for Buttons Function (Cont'd.):**

Name	Function
Z – 7	Negative movement of Z-Axis, Figure 7 inputting, reduce Spindle Speed during Processing.
Z+0 8	Set Z-Axis Work Origin, Figure 8 Inputting.
HOME 9	Machine back home, Figure 9 Inputting, check information during Processing.
HIGH/LOW	High or Low Speed selection under Manual Mode, Figure 0 inputting, Change Work Coordinate & Mechanical coordinate during processing.

# **Detail Information for Buttons Function (Cont'd.):**

Name	Function
ON/OFF	Spindle Start/Stop, Decimal Point Inputting.
MENU -	Enter Menu Setting, Negative Sign Inputting ,Check Information during Processing.
ORIGIN OK	Back to Work Origin, Confirm Motions /Inputting/Operating.
MODE	Manual Mode, Continue/Step/Distance to Select.
RUN/PAUSE DELETE	Run or Pause Processing, Delete Inputting Data, Different Property Selecting in Menu.
STOP CANCEL	High/Low Speed Parameter Adjust under Manual Mode, Quit Process Stop/Selections, Inputting and Operating Cancel.

# Wiring Instructions-

**Rich Auto Interface Board Description-**

Interface Board Schematic Diagram:



**Rich Auto Interface Board** 



# Interface board I/O Description-

Port Label	Port Definition	Pin Definition	Pin Functions & Parameters	<u>Notes</u>
J10	System Main Power	System Main Power Supply Port	System Main Power Supply Terminal, Interface Board give DC 5V for System.	Power Area: DC10V~D C24V/3A~40V
J2		5V Signal Output Port	X-Axis Drive Common Anode Power Supply Terminal 5V Output	Do not impose Voltage on this Pin.
	X-Axis Pulse	Pulse Signal Output Port	X-Axis direction of the Drive Signal Output Port Output Voltage ≧ 3V Drive Current≦ 8mA	
Shield	Output Port	Direction Signal Output Port	X-Axis direction of the Drive Signal Output Port Output Voltage ≧ 3V Drive Current≦ 8mA	
		Shield Connection Port	X-Axis Drive Signal Output Voltage Line Terminal Shield	Do not impose Voltage on this Pin.
J3		5V Signal Output Port	Y-Axis Drive Common Anode Power Supply Terminal 5V Output	Do not impose Voltage on this Pin.
SU+ PULSE D	Y-Axis Pulse	Pulse Signal Output Port	Y-Axis direction of the Drive Signal Output Port Output Voltage ≧ 3V Drive Current≦ 8mA	
R Shield	Output Port	Direction Signal Output Port	Y-Axis direction of the Drive Signal Output Port Output Voltage ≧ 3V Drive Current≦ 8mA	
		Shield Connection Port	Y-Axis Drive Signal Output Voltage Line Terminal Shield	Do not impose Voltage on this Pin.

# Interface board I/O Description (Cont'd.)-

Port Label	Port Definition	Pin Definition	Pin Functions &NotesZ-Axis Drive CommonDo not imposeAnode Power SupplyVoltage on thisTerminal 5V OutputPin.	
J4		5V Signal Output Port	Z-Axis Drive Common Anode Power Supply Terminal 5V Output	Do not impose Voltage on this Pin.
		Pulse Signal Output Port	Z-Axis direction of the Drive Signal Output Port Output Voltage ≧ 3V Drive Current≦ 8mA	
C DIR Shield	Z-Axis pulse Output port	Direction Signal Output Port	Z-Axis direction of the Drive Signal Output Port Output Voltage ≧ 3V Drive Current≦ 8mA	
		Shield Connection Port	Z-Axis Drive Signal Output Voltage Line Terminal Shield	Do not impose Voltage on this Pin.
J5		5V Signal Output Port	C-Axis Drive Common Anode Power Supply Terminal 5V Output	Do not impose Voltage on this Pin.
5U+ PULSE	C-Axis Pulse	Pulse Signal Output Port	C-Axis direction of the Drive Signal Output Port Output Voltage ≧ 3V Drive Current≦ 8mA	
	Output Port	Direction Signal Output Port	C-Axis direction of the Drive Signal Output Port Output Voltage ≧ 3V Drive Current≦ 8mA	
		Shield Connection Port	C-Axis Drive Signal Output Voltage Line Terminal Shield	Do not impose Voltage on this Pin.

# Interface board I/O Description (Cont'd.)-

Port Label	Port Definition	Pin Definition	Pin Functions &	Notes
J7		Y1(S0): Spindle ON/OFF	Connect to FWD of Inverter	Output Low Level Signal
		Y2(S1): Speed 1	Connect to Inverter to Control Speed	Output Low Level Signal
Y 1 (50)		Y3(S2): Speed 2	Connect to Inverter to Control Speed	Output Low Level Signal
Y 3 (52) Y 4. (53)		Y4(S3): Speed 3	Connect to Inverter to Control Speed	Output Low Level Signal
<ul> <li>Y 5 (\$4)</li> <li>Y 6 (\$5)</li> <li>H 3 (\$6)</li> </ul>	Output Signal Control Terminal	Y5(S4): Alarm LED	Lignt will appear when there is something wrong with System	Output Low Level Signal
• 7 7 (56) • Y 8 (\$?) • GHD		Y6(S5) : Work LED	Lignt will appear when System works	Output Low Level Signal
		Y7(S6): Definable	User-Defined Signal	Output Low Level Signal
		Y8(S7): Definable	User-Defined Signal	Output Low Level Signal
		GND: Output GND		GND Connect to this Terminal in Control Inverter Speed Mode

# Interface board I/O Description (Cont'd.)-

D19         Power LED         Interface Board SV Indicator Indicates the Interface and Internal Power Supply Status Moderators         Lights after Power           D11         Status Indicator         X origin status indicator         Lights after Power           D12         Status Indicator         X origin status indicator         Lights after Power           D12         Status Indicator         Y origin status indicator	Port Label	Port Definition	Pin Definition	Pin Functions &	Notes
D19     Power LED     Indicator indicates the interface and internal Power Supply Status Moderators     Lights after Power       D11     Status Indicator     X origin status indicator     Lights after Power       D12     Status Indicator     X origin status indicator     Light after power       D13     Status Indicator     Z origin status indicator     Light after power       D14     Status Indicator     Tool-Setting Status Indicator     Light after power. Input Iow, level signal, the lights       D15     Status Indicator     Driver Alarm Status Indicator     Light after power. Input Iow, level signal, the lights       D16     Status Indicator     Driver Alarm Indicator     Light after power. Input Iow, level signal, the lights       D16     Status Indicator     Driver Alarm Indicator     Light after power. Input Iow, level signal, the lights will be bright again       D16     Status Indicator     Definable Signal Status Indicator     Output Terminal Y1 Status Indicator       D1     Status Indicator     Output Terminal Y2 Status Indicator     Output Low Level signal Werks       D2     Status Indicator     Output Terminal Y3 Status Indicator     Votput Low Level signal Werks       D4     Status Indicator     Output Terminal Y5 Status Indicator     Works       D5     Status Indicator     Output Terminal Y5 Status Indicator     Works       D6     Status Indicator<				Interface Board 5V	
D19     Power LED     the Interface and internal Power Supply Status Moderators     Lights after Power       D11     Status Indicator     X origin status indicator     Lights after Power       D12     Status Indicator     X origin status indicator     Lights after Power       D13     Status Indicator     Y origin status indicator     Light after power. Input Iow, Ievel Signal, the lights       D14     Status Indicator     Tool-Setting Status Indicator     Light after power. Input Iow, Ievel Signal, the lights       D15     Status Indicator     Driver Alarm Status Indicator     Release the signal, the lights will be bright again       D16     Status Indicator     Definable Signal Status Indicator     Status Indicator       D18     Status Indicator     Output Terminal Y1 Status Indicator     Output Terminal Y2 Status Indicator       D2     Status Indicator     Output Terminal Y4 Status Indicator     Output Low Level Signal Status Indicator       D3     Status Indicator     Output Terminal Y5 Status Indicator     Output Low Level Signal Went the System       D5     Status Indicator     Output Terminal Y5 Status Indicator     Went the System       D6     Status Indicator     Output Terminal Y6 Status Indicator       D7     Status Indicator     Output Terminal Y7 Status Indicator       D8     Status Indicator     Output Terminal Y8 Status Indicator				Indicator Indicates	
D19         Power LED         and Internal Power Supply Status Moderators         Power           D11         Status Indicator         X origin status indicator         Power           D12         Status Indicator         Y origin status indicator         Indicator           D13         Status Indicator         Y origin status indicator         Indicator           D14         Status Indicator         Indicator         Indicator           D15         Status Indicator         Driver Alarm         Relights           D16         Status Indicator         Indicator         Indicator           D17         Status Indicator         Indicator         Relights           D18         Status Indicator         Difticator         Difticator           D1         Status Indicator         Output Terminal Y1 Status Indicator         Vuput Terminal Y2 Status Indicator           D2         Status Indicator         Output Terminal Y2 Status Indicator         Output Low Level Signal When the System           D3         Status Indicator         Output Terminal Y3 Status Indicator         Vuput Low           D4         Status Indicator         Output Terminal Y3 Status Indicator         Votput Low           D6         Status Indicator         Output Terminal Y5 Status Indicator         Votput Terminal Y6 Status	5	D10	Dowor LED	the Interface	Lights after
D11       Status Indicator indicator       X origin status indicator         D12       Status Indicator       Y origin status indicator         D13       Status Indicator       Y origin status indicator         D14       Status Indicator       Tool-Setting Status Indicator         D15       Status Indicator       Driver Alarm Status Indicator         D16       Status Indicator       Brite Status Indicator         D17       Status Indicator       Hard Limit Status Indicator         D18       Status Indicator       Definable Signal Status Indicator         D1       Status Indicator       Output Terminal Y2 Status Indicator         D2       Status Indicator       Output Terminal Y3 Status Indicator         D3       Status Indicator       Output Terminal Y5 Status Indicator         D4       Status Indicator       Output Terminal Y5 Status Indicator         D5       Status Indicator       Output Terminal Y5 Status Indicator         D6       Status Indicator       Output Terminal Y5 Status Indicator         D7       Status Indicator       Output Terminal Y5 Status Indicator         D6       Status Indicator       Output Terminal Y5 Status Indicator         D7       Status Indicator       Output Terminal Y5 Status Indicator         D8       Stat	contraction of the second seco	019	POWERLED	and Internal Power	Power
D11         Status Indicator         X origin status indicator           D12         Status Indicator         Y origin status indicator           D13         Status Indicator         Y origin status indicator           D14         Status Indicator         Indicator           D15         Status Indicator         Driver Alarm Status Indicator         Light after power. Input low, level signal, the lights           D16         Status Indicator         Driver Alarm Status Indicator         Release the signal, the lights will be bright again           D17         Status Indicator         Hard Limit Status Indicator         Release the signal, the lights           D18         Status Indicator         Definable Signal Status Indicator         Output Terminal Y1 Status Indicator           D1         Status Indicator         Output Terminal Y2 Status Indicator         Output Low Level signal status Indicator           D2         Status Indicator         Output Terminal Y2 Status Indicator         Output Low Level signal when the System           D4         Status Indicator         Output Terminal Y6 Status Indicator         System Works           D6         Status Indicator         Output Terminal Y6 Status Indicator         System Works				Supply Status	
D11         Status Indicator         X origin status indicator         Indicator           D12         Status Indicator         Y origin status indicator         Indicator           D13         Status Indicator         Z origin status indicator         Indicator           D14         Status Indicator         Tool-Setting Status Indicator         Light after power. Input Iow, level signal, tel lights           D15         Status Indicator         Driver Alarm Status Indicator         Light after power. Input Iow, level signal, the lights           D16         Status Indicator         Driver Alarm Status Indicator         Release the signal, the lights will be put out. Release the signal, the lights will be bright again           D17         Status Indicator         Definable Signal Status Indicator         Status Indicator           D18         Status Indicator         Output Terminal Y1 Status Indicator         Output Terminal Y2 Status Indicator           D2         Status Indicator         Output Terminal Y2 Status Indicator         Output Low Level signal when the System           D5         Status Indicator         Output Terminal Y5 Status Indicator         System Works           D6         Status Indicator         Output Terminal Y7 Status Indicator         System Works				Moderators	
U11         Status Indicator         indicator           D12         Status Indicator         Y origin status indicator         Indicator           D13         Status Indicator         Z origin status indicator         Indicator           D14         Status Indicator         Tool-Setting Status Indicator         Indicator           D15         Status Indicator         Driver Alarm Status Indicator         Indicator           D16         Status Indicator         Hard Limit Status Indicator         Will be put out. Release the signal, the lights will be bright again           D17         Status Indicator         Definable Signal Status Indicator         Definable Signal Status Indicator           D18         Status Indicator         Output Terminal Y1 Status Indicator         Output Terminal Y2 Status Indicator           D2         Status Indicator         Output Terminal Y2 Status Indicator         Output Terminal Y3 Status Indicator           D4         Status Indicator         Output Terminal Y5 Status Indicator         System Works           D5         Status Indicator         Output Terminal Y5 Status Indicator         System Works           D6         Status Indicator         Output Terminal Y5 Status Indicator         System Works	12	244	Charles Indiana	X origin status	
D12       Status Indicator       Y origin status indicator       Light after power. Input Iow, ievel signal, the lights         D14       Status Indicator       Tool-Setting Status Indicator       Light after power. Input Iow, ievel signal, the lights         D15       Status Indicator       Driver Alarm Status Indicator       Light after power. Input Iow, ievel signal, the lights         D16       Status Indicator       Driver Alarm Status Indicator       Light swill be put out. Release the signal, the lights will be bright again         D16       Status Indicator       E-stop Status Indicator       Indicator         D17       Status Indicator       Definable Signal Status Indicator       Status Indicator         D18       Status Indicator       Output Terminal Y1 Status Indicator       Output Terminal Y2 Status Indicator         D2       Status Indicator       Output Terminal Y3 Status Indicator       Output Low Level signal when the System Works         D5       Status Indicator       Output Terminal Y5 Status Indicator       System Works         D6       Status Indicator       Output Terminal Y5 Status Indicator       System Works         D7       Status Indicator       Output Terminal Y5 Status Indicator       System Works		DII	Status Indicator	indicator	
D12       Status Indicator       indicator         D13       Status Indicator       Z origin status indicator       indicator         D14       Status Indicator       Tool-Setting Status Indicator       level signal, the lights         D15       Status Indicator       Driver Alarm Status Indicator       Release the signal, the lights will be put out.         D16       Status Indicator       Hard Limit Status Indicator       Release the signal, the lights will be bright again         D17       Status Indicator       E-stop Status Indicator       Definable Signal Status Indicator         D18       Status Indicator       Output Terminal Y1 Status Indicator       Output Terminal Y2 Status Indicator         D2       Status Indicator       Output Terminal Y3 Status Indicator       Output Terminal Y3 Status Indicator         D4       Status Indicator       Output Terminal Y5 Status Indicator       Output Low Level signal Works         D5       Status Indicator       Output Terminal Y5 Status Indicator       Works         D6       Status Indicator       Output Terminal Y6 Status Indicator       Works         D7       Status Indicator       Output Terminal Y6 Status Indicator       Works		D12	Status Indicator	Y origin status	]
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D14     Status Indicator     indicator       D14     Status Indicator     Tool-Setting Status Indicator     power. Input Iow, Ievel signal, the lights       D15     Status Indicator     Driver Alarm       D16     Status Indicator     Status Indicator       D17     Status Indicator     Hard Limit Status Indicator       D18     Status Indicator     Definable Signal Status Indicator       D1     Status Indicator     Output Terminal Y2 Status Indicator       D2     Status Indicator     Output Terminal Y2 Status Indicator       D3     Status Indicator     Output Terminal Y2 Status Indicator       D4     Status Indicator     Output Terminal Y2 Status Indicator       D4     Status Indicator     Output Terminal Y2 Status Indicator       D4     Status Indicator     Output Terminal Y5 Status Indicator       D5     Status Indicator     Output Terminal Y6 Status Indicator       D6     Status Indicator     Output Terminal Y6 Status Indicator       D7     Status Indicator     Output Terminal Y6 Status Indicator       D8     Status Indicator     Output Terminal Y7 Status Indicator		D13	Status Indicator	Z origin status	Light after
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D14     Status Indicator     Indicator     Indicator       D15     Status Indicator     Driver Alarm Status Indicator     Will be put out. Release the signal, the lights will be bright again       D16     Status Indicator     Hard Limit Status Indicator     Indicator       D16     Status Indicator     Hard Limit Status Indicator     Release the signal, the lights will be bright again       D17     Status Indicator     Definable Signal Status Indicator     Status Indicator       D18     Status Indicator     Output Terminal Y1 Status Indicator     Output Terminal Y2 Status Indicator       D2     Status Indicator     Output Terminal Y3 Status Indicator     Output Low Level signal When the System       D4     Status Indicator     Output Terminal Y4 Status Indicator     Output Low Uput Terminal Y5 Status Indicator       D5     Status Indicator     Output Terminal Y5 Status Indicator     System Works       D6     Status Indicator     Output Terminal Y5 Status Indicator       D7     Status Indicator     Output Terminal Y6 Status Indicator       D8     Status Indicator     Output Terminal Y8 Status Indicator		D14	Canadian Intelligence	Tool-Setting Status	level signal
D15       Status Indicator       Driver Alarm Status Indicator       will be put out. Release the signal, the lights will be bright again         D16       Status Indicator       Hard Limit Status Indicator       Indicator       Hereinsbe Bright         D16       Status Indicator       E-stop Status Indicator       Indicator       Hereinsbe Bright       Indicator         D17       Status Indicator       Definable Signal Status Indicator       Definable Signal Status Indicator       Indicator         D18       Status Indicator       Output Terminal Y1 Status Indicator       Output Terminal Y2 Status Indicator       Indicator         D2       Status Indicator       Output Terminal Y3 Status Indicator       Output Terminal Y4 Status Indicator       Output Low Level Signal when the System         D5       Status Indicator       Output Terminal Y5 Status Indicator       System Works         D6       Status Indicator       Output Terminal Y7 Status Indicator       Works         D7       Status Indicator       Output Terminal Y7 Status Indicator       B         D8       Status Indicator       Output Terminal Y8 Status Indicator       B		D14	Status Indicator	Indicator	the lights
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D16       Status Indicator       Hard Limit Status Indicator       Ilights will be bright again         D17       Status Indicator       E-stop Status Indicator       Indicator         D18       Status Indicator       Definable Signal Status Indicator       Status Indicator         D1       Status Indicator       Output Terminal Y1 Status Indicator       Output Terminal Y2 Status Indicator         D2       Status Indicator       Output Terminal Y3 Status Indicator       Output Terminal Y2 Status Indicator         D3       Status Indicator       Output Terminal Y3 Status Indicator       Output Low Level signal When the System         D5       Status Indicator       Output Terminal Y6 Status Indicator       Works         D6       Status Indicator       Output Terminal Y6 Status Indicator       Works         D7       Status Indicator       Output Terminal Y7 Status Indicator       Works         D8       Status Indicator       Output Terminal Y6 Status Indicator       Works		D15	Status Indicator	Status Indicator	Release the signal the
D16       Status Indicator       Indicator       Indicator         D17       Status Indicator       E-stop Status Indicator       bright again         D18       Status Indicator       Definable Signal Status Indicator       bright again         D1       Status Indicator       Definable Signal Status Indicator       bright again         D1       Status Indicator       Output Terminal Y1 Status Indicator       bright again         D2       Status Indicator       Output Terminal Y2 Status Indicator       bright again         D3       Status Indicator       Output Terminal Y3 Status Indicator       Output Low Level signal when the System         D4       Status Indicator       Output Terminal Y5 Status Indicator       System Works         D6       Status Indicator       Output Terminal Y6 Status Indicator       Works         D7       Status Indicator       Output Terminal Y7 Status Indicator       Works				Hard Limit Status	lights will be
D17     Status Indicator     E-stop Status Indicator     Origin egon       D18     Status Indicator     Definable Signal Status Indicator     Definable Signal Status Indicator       D1     Status Indicator     Output Terminal Y1 Status Indicator       D2     Status Indicator     Output Terminal Y2 Status Indicator       D3     Status Indicator     Output Terminal Y3 Status Indicator       D4     Status Indicator     Output Terminal Y4 Status Indicator       D5     Status Indicator     Output Terminal Y5 Status Indicator       D6     Status Indicator     Output Terminal Y6 Status Indicator       D7     Status Indicator     Output Terminal Y7 Status Indicator       D8     Status Indicator     Usuput Terminal Y7 Status Indicator		D16	Status Indicator	Indicator	bright again
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D18Status IndicatorDefinable Signal Status IndicatorD1Status IndicatorOutput Terminal Y1 Status IndicatorD2Status IndicatorOutput Terminal Y2 Status IndicatorD3Status IndicatorOutput Terminal Y3 Status IndicatorD4Status IndicatorOutput Terminal Y4 Status IndicatorD5Status IndicatorOutput Terminal Y4 Status IndicatorD6Status IndicatorOutput Terminal Y6 Status IndicatorD7Status IndicatorOutput Terminal Y7 Status IndicatorD8Status IndicatorOutput Terminal Y6 Status Indicator		D17	Status Indicator	Indicator	
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D2Status IndicatorOutput Terminal Y2 Status IndicatorD3Status IndicatorOutput Terminal Y3 Status IndicatorD4Status IndicatorOutput Terminal Y4 Status IndicatorD5Status IndicatorOutput Terminal Y5 Status IndicatorD6Status IndicatorOutput Terminal Y6 Status IndicatorD7Status IndicatorOutput Terminal Y7 Status IndicatorD8Status IndicatorOutput Terminal Y8 Status Indicator	100000000				
D2       Status Indicator       Y2 Status Indicator         D3       Status Indicator       Output Terminal         Y3 Status Indicator       Output Terminal         Y4 Status Indicator       Output Terminal         Y5 Status Indicator       Output Terminal         Y5 Status Indicator       Output Terminal         Y5 Status Indicator       Output Terminal         Y6 Status Indicator       Works         D6       Status Indicator         D7       Status Indicator         D8       Status Indicator	2			Output Terminal	
D3       Status Indicator       Output Terminal Y3 Status Indicator       Output Low Level signal when the System         D4       Status Indicator       Output Terminal Y4 Status Indicator       Output Terminal Were Status Indicator         D5       Status Indicator       Output Terminal Y5 Status Indicator       Output Terminal Works         D6       Status Indicator       Output Terminal Y6 Status Indicator       Works         D7       Status Indicator       Output Terminal Y7 Status Indicator         D8       Status Indicator       Output Terminal Y8 Status Indicator		D2	Status Indicator Y2 Sta	cator Output Terminal Y2 Status Indicator Cator Output Terminal Y3 Status Indicator Output Low Cator Output Terminal Y4 Status Indicator when the	
D3       Status Indicator       Output Terminal Y3 Status Indicator       Output Low Level signal when the System         D4       Status Indicator       Output Terminal Y4 Status Indicator       Output Terminal Y5 Status Indicator       Output Low Level signal when the System         D5       Status Indicator       Output Terminal Y5 Status Indicator       Works         D6       Status Indicator       Output Terminal Y6 Status Indicator       Works         D7       Status Indicator       Output Terminal Y6 Status Indicator       Works         D8       Status Indicator       Output Terminal Y8 Status Indicator       Works	N				-
D4     Status Indicator     Output Terminal Y4 Status Indicator     Output Low Level signal when the System       D5     Status Indicator     Output Terminal Y5 Status Indicator     Works       D6     Status Indicator     Output Terminal Y5 Status Indicator     Works       D6     Status Indicator     Output Terminal Y6 Status Indicator     Works       D7     Status Indicator     Output Terminal Y6 Status Indicator     Output Terminal Y7 Status Indicator       D8     Status Indicator     Output Terminal Y8 Status Indicator     Y8 Status Indicator	R	D3	Status Indicator		
D4     Status Indicator     Output Terminal Y4 Status Indicator     Level signal when the System       D5     Status Indicator     Output Terminal Y5 Status Indicator     Works       D6     Status Indicator     Output Terminal Y6 Status Indicator     Works       D7     Status Indicator     Output Terminal Y6 Status Indicator     Output Terminal Y7 Status Indicator       D8     Status Indicator     Output Terminal Y8 Status Indicator					Output Low
D4     Status Indicator     Output Terminal Y4 Status Indicator     When the System       D5     Status Indicator     Output Terminal Y5 Status Indicator     Works       D6     Status Indicator     Output Terminal Y6 Status Indicator     Works       D7     Status Indicator     Output Terminal Y6 Status Indicator     Output Terminal Y7 Status Indicator       D8     Status Indicator     Output Terminal Y8 Status Indicator	4			Output Terminal	Level signal
D5     Status Indicator     Output Terminal Y5 Status Indicator     System Works       D6     Status Indicator     Output Terminal Y6 Status Indicator     Works       D7     Status Indicator     Output Terminal Y6 Status Indicator     Works       D8     Status Indicator     Output Terminal Y8 Status Indicator		D4	Status Indicator	Y4 Status Indicator	when the
D5     Status Indicator     Output Terminal Y5 Status Indicator     Overall System       D6     Status Indicator     Output Terminal Y6 Status Indicator     Works       D7     Status Indicator     Output Terminal Y6 Status Indicator     Works       D8     Status Indicator     Output Terminal Y8 Status Indicator	C1			0	System
D6     Status Indicator     Output Terminal Y6 Status Indicator       D7     Status Indicator     Output Terminal Y7 Status Indicator       D8     Status Indicator     Output Terminal Y8 Status Indicator	2	D5	Status Indicator	Output Terminal	Works
D6     Status Indicator     Output Terminal Y6 Status Indicator       D7     Status Indicator     Output Terminal Y7 Status Indicator       D8     Status Indicator     Output Terminal Y7 Status Indicator				Y5 Status Indicator	, works
D0         Status Indicator         Y6 Status Indicator           D7         Status Indicator         Output Terminal Y7 Status Indicator           D8         Status Indicator         Output Terminal Y8 Status Indicator		DS	Status Indicator	Output Terminal	
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D7 Status Indicator Y7 Status Indicator D8 Status Indicator Output Terminal Y8 Status Indicator				Output Terminal	
D8 Status Indicator V8 Status Indicator		D7	Status Indicator	Y7 Status Indicator	
D8 Status Indicator V8 Status Indicator				Output Terminal	1
		D8	Status Indicator	Y8 Status Indicator	

Installation Requirements: Power (24V, 3A), it is better to add a filter to prevent the electric field interference. If origin detecting switch are different power supply type, the special testing switching power is needed, (24V Origin Detecting Switch is the best choice).

<u>Rich Auto Motion Control System</u> realizes its control through the connection between the Interface Board and CNC Machine. Interface Board Terminal can be divided into Input Terminal and Output Terminal:

# **Input Terminal:**

J8 (Input Control Terminal)

J10 (Main Power Terminal)

# **Output terminal:**

J2 (X-Axis Pulse Signal Output Terminal)

J3 (Y-Axis Pulse Signal Output Terminal)

J4 (Z-Axis Pulse Signal Output Terminal)

J5 (C -Axis Pulse Signal Output Terminal)

J7 (Output Control Terminal)

# **Input Signal Terminal:**

# <u>J8</u>

- 1.) Sensor Input:
- a.) Mechanical: Y and Z are the same as X.



b) NPN(NO): Y and Z are the same as X.



# **Input Signal Terminal:**

# J8 (Cont'd.)





1-4

View

2.) Tool-Setting Input: Tool-Setting Detecting Wiring:



3.) X5-X8 Driver Alarm, Hard Limit, E-Stop Signal:



### J10-Main Power Wiring:



### **Output Terminal**

### J2 X-Pulse Signal Wiring: Y and Z are the same as X:





J2 X-Pulse Signal Wiring: Y and Z are the same as X (Cont'd.):

# J7 Spindle Output

# **<u>2 Status: Spindle Start/Stop</u>**:



# The corresponding Spindle Setting is:



<u>8 Status:</u> Spindle Start---S1—speed 1, S2—speed 2, Sn—speed n, when Spindle Stop, the Screen displays Fn—the Speed before Spindle Stop.

### 3 Lines, 8 Status-



<u>8 Status:</u> Spindle Start---S1—speed 1, S2—speed 2, Sn—speed n, when Spindle Stop, the Screen displays Fn—the Speed before Spindle Stop.

# 3 Lines, 8 Status- (Cont'd.):

The corresponding Spindle Setting is:

1 Shift	ŧ	ŧ	ŧ
2 shift	t	ŧ	ŧ
3 shift	ŧ	t	ŧ
4 shift	t	t	ŧ
5 shift	ŧ	ŧ	t
6 shift	t	ŧ	t
7 shift	ŧ	t	t
8 shift	t	t	t

**PS:** FWD and DCM has Connected in Parallel in some Inverters, please do not need to connect Y1 (S0) in such situations, you only need to connect DCM with GND of Interface Board, without having to reset the Spindle Gear.

J7 Output Port Y5-Alarm LED and Y6-WORK LED:



You can Connect the Machine with the Control System when the above setting is over.

### **Commissioning of the Machine and Control System-**

- 1.) After turning on the power, users can manually move each axis and confirm the direction. If the movement direction and definition direction are opposite, users can change the motor phase sequence.
- 2.) According to the original location of the machine coordinates, users can enter menu-machine setup-home setup- home direction to reset it.
- 3.) Double-Press "Menu"-Manual Voltage Setup (the Upper Arrows stand for Input Voltage) to check whether the Home Switch is working. The machine is in good connection, if all the above setting is "OK".

### Menu Descriptions-

### Menu Category-

According to Menu Function, Rich Auto System Menu divided into the following:

- MACHINE SETUP
- AUTO PRO SETUP
- SYSTEM SETUP
- OPERATE FILE
- VERSION VIEW

Every main menu has some submenus.

### Menu Details-

### Machine Setup-

Users can set the parameters about machine hardware under <u>"Machine Setup"</u>. It is set by machine producer according to device type. If machine hardware parameter is not changed, this parameter should also not change. If machine users need to change, please consult machine producer.

### Machine Setup (Cont'd.)-

### Machine Setup Chart



1.) **Pulse Equiv. (or Pulse Equivalent):** The number of pulses of the system needs to send when machine moves every 1mm. (Unit Pulse/mm.).
#### 1) Stepper Driver-

**Formula** = Pulses per Revolution / Distance per Revolution.

Pulses per revolution formula: (360 °/Stepper Angle) \* Driver Subdivision.

Some stepper drivers mark pulse number directly.

#### Distance/R Formula:

**Screw Drive Machine** = Screw Pitch \* Mechanical Transmission Ratio.

<u>**Rack Drive Machine**</u> = Rack Module \* Gear Teeth Number\* $\pi$  (Pie)\* Mechanical Transmission Ratio.

#### **Stepper Motor System Formula:**

Screw Drive:



**Formula Description:** Stepper Angle is the Angle of the Motor Parameters, Motor Rotation Step Walk.

Driver subdivision is the parameter set by the driver.





**Screw Pitch (See Above Pictures):** The distance that the nut moves when the ball screw makes one rotation.

**Transmission Ratio**: The speed ratio or angular velocity ratio of the capstan and the driven wheel.

**Rack Drive:** 



pulse =  $\frac{\frac{360 \circ}{\text{stepper angle}} * \text{ Driver subdivision}}{\text{rack module } * \text{ gear teeth number } * \Pi * \text{ transmission ratio}}$ 

**Formula Description:** step angle is the angle of the motor parameters, motor rotation step walk. **Driver Subdivision:** is the parameter set by the driver.

Rack Module and Gear Teeth Number are Gear Parameters:

Rack Module \* Gear Teeth Number \*  $\pi$  (Pie) = Equals the Perimeter of the Reference Circle. <u>Transmission Ratio</u>: The Speed Ratio or Angular Velocity Ratio of the capstan and the driven wheel.

Setting: Enter "Pulse Equiv", cursor is in the X-Axis Pulse Equivalent position,



#### Servo Driver-

The Pulse Equivalent factory default X, Y, Zare 400, and set the **Electronic Gear Ratio** in the **Servo Drive** according to the **Pulse Equivalent**.

The **Numerator of the Electronic Gear Ratio** represents **Encoder Pulse Number**, users can search it in **Servo Driver Manual**.

The **Denominator of the Electronic Gear Ratio**:

✓ <u>Screw Drive</u>: Handle Pulse Equivalent (400) \* Screw Pitch \* Mechanical Transmission Ratio.

 <u>Rack Drive</u>: Handle Pulse Equivalent (400) \* Rack Module \* Gear Teeth Number\*π (Pie)\* Mechanical Transmission Ratio.

#### Table Size:

<u>**Rich Auto System</u>** make the table size as the soft limit values, to prevent the machine to move over travel, machine size must be less than or equal to the value of the actual motion</u>



#### Spindle Setup:

**Spindle Delay:** Unit: ms; including start delay and stop delay.

**Spindle State:** Used to set system using multi-speed or only "On/Off" 2 status, the corresponding system parameters.

System default "3-line 8-state", if users need "1-line 2-state (On/Off)", users can change the number of lines is 1; See detailed settings at <u>J7</u> Spindle Output Wiring.

#### Home Setup:

**Home Speed:** Every axis movement speed when back home, System Default Speed X, Y: 3000 MM/Minute, Z: 1800 MM/Minute.

Home Order: Every Axis movement order when back home Including:

+	Z, X and Y	Z, X, Y	Z, Y, X	
+	Z Only	X and Y, Z	X, Y, Z	
+	Y, X, Z	X, Y Home	X, Y, Home	
+	Y, Z, Home	None Home	X Home Only	X, Z and Y

<u>Home Direction</u>: Every Axis movement direction when back home, this direction depends on the position where home switch is on the machine. If home switch installed in the positive direction, so home direction should be **"Positive"**, and vice versa.

**Setting:** Enter <u>"home dir"</u>, press " $\begin{bmatrix} X + \\ 1 & \end{bmatrix}$ /"  $\begin{bmatrix} X - \\ 5 & \end{bmatrix}$ " to move cursor to where users want to modify. Press " $\begin{bmatrix} RUNPAUSE \\ DELETE \end{bmatrix}$ , to change home direction, press " $\begin{bmatrix} ORIGIN \\ OK \end{bmatrix}$ " to save the change.

Accel (Acceleration): Unit-mm/s2, the maximum acceleration value during acceleration and deceleration movement, improve (including straight and curved motion) processing capabilities. If acceleration is too large, it may cause the motor losing steps, jitter and even whistle, if too small, it will lead to accelerated slowly and reduce the operating speed of the entire graph. System Default: linear acceleration is 800 mm/s2, curve acceleration is 1000 mm/s2, the proposed curve acceleration is 1-1.5 times the linear acceleration value.

<u>Start Speed:</u> Unit-mm/minute. The speed of axis started directly from standstill. Not starting from zero speed, but starting directly from a certain speed, so it can shorten the overall processing time, but do not set this speed too high. Set too high, it will cause the motor losing steps, jitter and even whistle; Set too small, it will reduce the operating speed of the entire graph. If the inertia of motion axes (axis heavier), users can set a smaller start speed, if the inertia of motion axes smaller (lighter shaft), users can set it bigger.

**Voltage Setup:** Set input and output signal terminal status, " $\downarrow$ " means normal open, " $\uparrow$ " means normal closed. Including two rows of arrow: The upper arrow indicates the input level: Set input voltage signal terminal status. The top four: 0, 1, 2, 3 positions correspond X-Axis back home, Y-Axis back home Z-axis back home, Tool Setting Signal, 5-7: 4, 5, 6 positions correspond Driver Alarm, Hard Limit E-Stop Signal.

The under arrow indicates the output level: Set output voltage signal terminal status. The Top Four: 0, 1, 2, 3 positions correspond spindle "On/Off", Multi-Speed 1, Multi-Speed 2, Multi-Speed 3 Signal, 5, 6:4, 5 Positions correspond Alarm LED, Work LED Signal.

#### Setting:

**Press** "
$$\begin{bmatrix} X + \\ 1 & \\ \end{bmatrix}$$
 "/" $\begin{bmatrix} X - \\ 5 & \\ \end{bmatrix}$ " to move around, **Press** " $\begin{bmatrix} Y + \\ 2 & \\ \end{bmatrix}$ ", " $\begin{bmatrix} Y - \\ 6 & \\ \end{bmatrix}$ " to move up and down, **Press** " $\begin{bmatrix} RUNPAUSE \\ DELETE \end{bmatrix}$ " to change the direction of the arrow.

#### C.A.D. Thickness (Unit-mm) :

This thickness should input by actual, if it is bigger than the actual thickness, Z-Axis may cut too much; if smaller, Z-Axis can't touch workpiece. This parameter can only take effect when user use auto tool setting function.

#### Max Spd Limit (Max Speed Limit): (Unit: mm/minute):

Set machine top speed, it only takes effect during processing, system default max speed X, Y is "60000000 mm/minute", "Z+" is "1800 mm/minute", "Z-" is "3000 mm/minute".

#### DistTime Limit:(Unit: second):

Users select distance mode, and if the machine does not move in a certain period (System Default is 30 seconds), the system will go back to Continuous Mode to prevent Z-Axis collision risk because of the customer forgot to switch back to Continuous Mode and set a large distance value.

#### InputConfi (Input Port Configuration):

To open or prohibit input signal, if the interface board does not connect X5-X8 signals, users can prohibit X5-X8 signals.

#### Auto Pro Setup-

Users can set processing parameters, G-Code attributes etc. under this menu.

## AUTO PRO SETUP Work Speed Safe Height Auto Scale Fall Scale Stop Statue G Code Setup Pro Attribute Work Array

#### Auto Pro Setup Chart

Machine Setup (Cont'd.)-	AUTO PRO SETUP	
	Work Speed	
<u>Auto Pro Setup (Cont'd.)-</u>	Safe Height	
	Auto Scale	
	Fall Scale	
	Stop Statue	
	G Code Setup	
	Pro Attribute	
	Work Array	

1.) <u>Work Speed:</u> Unit: mm/minute, including work speed and fast speed, System Default is 3000 mm/minute.

2.) <u>Safe Height:</u> Unit: mm, the height of Z-Axis rises during processing.System Default is 40.000 mm.

3.) <u>Auto Scale</u>: Actual Processing Speed= Work Speed\*Auto Scale, system default auto scale does not affect the fast speed.

4.) Fall Scale: Fall Scale, System Default is 0.200, Fall Speed=fast speed\*fall scale,

the maximum fall speed is Z axis negative limit speed\*fall scale. Fall height, System Default is 5.000mm, fall down scale takes effect when the spindle falls to the fall height.

#### Auto Pro Setup (Cont'd.)-

5.) **Stop Statue:** Setup stop position after auto processing.







#### **G-Code Setup:**

Set Special G -Code attribute, according to the actual need to make changes.

Attribute Of	G Code
F Read	Ign F/Read F
AbsCntr	Off/On
T Read	Ign T/ Read T
Spindle	NTLLG/FORCE/INSTR
FilterJD	None/ Adj Z Filter
S Read	Ign S/ Read S
Read G54	Ign G54/ Read G54
Read G49	Ign G49/ Read G49
Read G40	Ign G40/ Read G40
CodeHead	Skip/NoSkip
Input TO	-1

(Ign=Ignore, Adj=Adjt=Adjust, AbsCntr= Absolute Center) PS: Blue Parts indicate System Default Attributes. Setting: Press " $\begin{bmatrix} X + \\ 1 & \\ \end{bmatrix}$ " (" $\begin{bmatrix} X - \\ 5 & \\ \end{bmatrix}$ " move cursor to where users want to modify,

#### Work Array:

Set array parameter, including Columncount, Rowcount, Columnspace, Rowspace, Interval, (Unit : ms)

**<u>Columnspace</u>**: File spacing of X direction.

**Rowspace:** File spacing of Y direction.

**<u>Total Processing Times</u>** = Columncount\* Rowcount.

Interval: System Default 0, it means no wait.

During processing, if users need to change processing materials after completion of each processing, you need set time interval a negative number. When the first-time processing is completed, the screen prompt: waiting for the next array processing, press any key to start the next array processing at this time, if not press, system keep waiting.

SYSTEM SETU	Р
	Languages
	Data Initial
	Inner Format
	Wipe Cache
	Fucntion Confi
	Probation Pas
	Backup Pas
	Input Port
	Output Port
	Buttons Check
	Backup Data
	Restore Data
	Trail Setting
	Auto Upgrade

#### System Setup Chart

- 1.) Languages: Change system display language users can choose Chinese and English.
- 2.) Data Initial: After data initial system parameters will restore to factory setting.
- 3.) Inner Format: Wipe the internal files, it will not damage the system parameters.

#### System Setup Chart (Cont'd.)

4.) <u>Wipe Cache</u>: Users need to do this after functional upgrade, such as change four-axis program to three-axis program, users must do this operation. After this operation, users need to restart the system.

5.) **Function Confi (Function Configuration):** Set whether the system retain a function or not, change it according to the actual application in accordance with the practical application of changes. After the operation, users need to restart the system.

n ni	
PausePkup	NoPick/Pickup
ScaleFast	None/Affect
Manual	Step/Trad
Pretrt	Parse/None
QuryPara	Query/None
StrtHome	Query/Auto/ZOnly/None
CopyWork	Off/On
RetOrgPZ	Pick Z/Z Stop
TolstAct	Pickup/Origin
PauseRstr	All/only Z

PS: **<u>Blue Parts</u>** indicate system default function.

#### System Setup Chart (Cont'd.)

Setting: Press " $\begin{bmatrix} X + \\ 1 & \\ \end{bmatrix}$ "  $\begin{bmatrix} X - \\ 5 & \\ \end{bmatrix}$ " move cursor to where users want to modify, Press" $\begin{bmatrix} RUNPAUSE \\ DELETE \end{bmatrix}$ ", and then select the function users want, Press " $\begin{bmatrix} ORIGIN \\ OK \end{bmatrix}$ " to save.

6.) **Probation Pas (Probation Password):** If engraving machine manufacturers setting some kinds of passwords before shipment (including probation password and backup password, etc.), if you forget the original password, you can connect our company and tell us 20-digit here, our company will provide you a new 20-digit password, you need enter the new 20-digit password, and then all the passwords will be cracked.



#### System Setup Chart (Cont'd.)

7.) Backup Pas (Backup Password): Prevent users overwritten the original correct parameters in the parameter backup disorder or misuse case. To cancel, you do not input any number when you

8.) Input Port (Input Port List): 1-3:X, Y, Z Home Signal, 4: Tool Setting Input Signal,

5-7: Driver Alarm, Hard Limit, E-Stop Signal.

9.) Output Port (Output Port List): 1: Spindle On/Off Signal, 2-4: Spindle Speed Signal,

5: Driver Alarm Signal, 6: Work LED Signal.

10.) Buttons Check: Users can check buttons are valid or not under this menu.

Enter "Buttons Check", Press every button if it is valid, the screen will highlight.



11.) Backup Data: Backup system parameters to U-Disk or Inner, format system can't affect this. File Format: data.bak.

#### System Setup Chart (Cont'd.)

12.) Restore Data: Restore backup data from U-Disk or Inner to System.

13.) Trial Setting: Including Four levels password, password and using time can be set in every level respectively. Password can be set to be 1-8 digits; using time unit: hour, system default1. The password work according to top-down order, if you do not set trial 1 password, only set trial 2-4, it will work according to 2-4 order.

The operation of Data Initial, Inner Format, Wipe Cache should not crack the password.



There is a mark "\*" before every level password, if not, the password will not work normally.



Restart the handle, and system will work normally.

#### System Setup Chart (Cont'd.)

**NOTE:** If engraving machine manufacturers forgot all password, you can contact our company and tell us 20-digit original password under **"SYSTEM SETUP-Probation pas"**, we will provide the new

20-digit password entered the new number, and Press "

"to confirm.

After Cracking Password, restart the handle, and then you can work normally.

14.) Auto Upgrade: If the system has new function, our company will provide upgrade file (extension \*\*\*\*\*. PKG & shown as rz-xxxx), users can upgrade through the U-Disk, specific steps in Appendix 1. It will not damage the original parameters.

File fomat: P1\_1025(普通三轴雕刻[3寸单色屏][USB1]).pkg

#### **Operate File:**



#### Machine Setup (Cont'd.)-Operate File:



- 1.) **Copy File:** Copy files from U-Disk to Inner.
- 2.) Del File (Delete File): Delete files of Inner.
- 3.) View File: View the files and G-Codes of U-Disk or inner.

4.) **Pro Info (Processing Information):** System Power On, it will statistical the times of successful processing by File Name, if System power Off, the Data will disappear.

5.) <u>Check Pro Time (Check Processing Time)</u>: Calculate processing time by system work speed after reading G-Code, the screen will display the processing time, different work speed corresponding to different processing time.



### Machine Setup (Cont'd.)-Operation Method (Cont'd.): 2.) Win XP system after copying files, please Press" (", and then the display will show ("Safely remove USB Mass Storage Device - Drive(Ht) ", choose the device to be shut down. When the display show ("Safely Remove Hardware" ", the U-Disk pull out from computer

#### Version View-

successfully.

Users can view information about the system hardware and software, including:

- Update Version e.g. : P1.409/rz-xxxx/q10-82
- Product ID e.g.: A0020112
- Soft Version e.g.: A1.1936
- " Emergency Version e.g.: A1.1920 "
- "Soft Type: 3-Axis Carving"
- Hardware Type: Support 3-inch Screen Flash Disk Mode

#### **Machine Operation-**

#### **Return Home-**

It will display **"All Axis Home"**, **"Z Home Only"**, **"None Axis Home"** after starting up the DSP handle. Choose any one you want. Machine return home can correct the coordinate of system.

In some cases, such as after normal power off, reboot ad continues last operation, user no need to reset machine, just choose **"None Axis Home"**. That is because system auto save coordinate value when system quit.

#### **Import Processing Files-**

Before processing, generally we should import files. Rich Auto System has 2 ways for processing:

U-Disk file processing, inner file processing.

1. Directly import the processing file into U-Disk, then run the handle.

2. Copy the process file to inner memory space via U-Disk.

#### Machine Operation (Cont;'d.)-

#### **Manual Processing Operation-**

Manual Processing Operation refers to controlling of the machine tool though keyboard. User can change the operate speed and set the grid under manual processing operation. System will enter Manual Operation state after returned home, and the screen displays:

Manual control state initial interface :



#### Manual Operation Speed Switching and Adjusting-

1.) Speed Modes Switching-

There are 2-Two Speed Modes:

- High Speed.
- Low speed.
   We can change mode by press "
   We can change mode by press "
   Inightow
   Inightow<

#### Manual Operation Speed Switching and Adjusting (Cont'd.)-



To ensure the accuracy of processing and debugging, the system introduces the concept of grid which also called minimum feed. Its range is 0.05mm-1.0mm. When user change mode to **"Step"**, machine will move by grid distance.

High speed mode setting is the same as low-speed mode.

#### Manual Processing Mode-

To meet different situation of manual movement, the system provides 3 kinds of motion

modes: **Continue, Step, Distance.** We can change mode by Pressing " MODE "and the bottom of screen will display what the current manual mode is.

1.) Continuous Motion Mode: This mode has no value control. In continuous mode, machine will



Its motion speed is decided by current speed mode.

**Note:** If user's release the button immediately after pressing the button(shorter than 0.5s), machine will automatically move to the nearest grid point. It always stops on grid point when the motion mode is over. Continuous mode suitable for crude regulation of machine coordinate situation.

2.) Step Motion Mode: This mode is always move in low speed, move 1 grid per 0.5 second. The grid distance is decided by current speed mode. This motion mode is suitable for tool adjusting or precise adjustment of the location of the mechanical coordinates.

3.) Distance Motion Mode: In this mode, it runs according to the setting of distance. Machine will move by the set distance when user press direction button  $\begin{bmatrix} x_+ \\ 1 & 5 \end{bmatrix} \begin{bmatrix} x_- \\ 2 & 6 \end{bmatrix} \begin{bmatrix} z_+ \\ 3 \end{bmatrix} \begin{bmatrix} z_- \\ 7 \end{bmatrix}$ .

#### Manual Processing Mode (Cont'd.)-

<u>Note</u>: Grid unable to affect the distance motion mode. Machine will move by set distance, can't move to grid point. If user wants to change distance, please change to distance mode, and reenter the distance value.

#### **Manual Testing Input and Output-**

In the initial boot interface, that is screen displays as follow:

1X	0.000	MAUN		
1Y	0.000	<b>F2</b>		
1 <b>Z</b>	0.000	L SP		
Continue				

MENU

Press " $\Box$ " twice, the screen will display two rows of arrows which are defaults to all arrows are downwards " $\downarrow$ ".

Upper arrows represent input signal: the former 4 numbers 0, 1, 2, 3 corresponding to X zero, Y zero, Z zero and tool setting gauge. 4,5,6 corresponding to driver alarm, hard limit and emergency stop input signal.

Manual trigger the corresponding signal switch by Pressing " \_\_\_\_\_\_ arrow flip so the signal is normal.

DELETE "and the corresponding

#### Manual Processing Mode (Cont'd.)-

Bottom rows represent output signal: the former 4 number 0,1,2,3 corresponding to spindle on/off, multistep rotational speed one, multistep rotational speed two, multistep rotational speed three output signal 4, 5 corresponding to alarm lamp, running lamp output signal.

Press " [DELETE]" button can change the arrow direction, so it can control the output of corresponding port. For example, press " [DELETE]" to flip the arrow upwards under 0, it is

equivalent to start the spindle. Press " [UNPAUSE DELETE]" again, the arrow flip downwards that is equivalent to stop the spindle.

#### **Manual Testing Input and Output-**

Including Machine Coordinate System and Work Coordinate System.

<u>Machine Coordinate System</u> is fixed, the origin of coordinates is always a fixed position relative to the machine; Its coordinates are called mechanical values, the origin of coordinates is the origin of the machine or reference point. so that at any time, one point of space can be confirmed by machine coordinate system. Because of reference point is the calculation basis of machine coordinates movement powered on or remove all abnormal states, you need back to zero.

#### **Manual Testing Input and Output-**

<u>Work Coordinate System</u> used more greatly than other coordinates system in processing. Usually in processing, we describe a processing position is always relative to a certain point on the workpiece, whereas the workpiece on the machine tool's position relative to the mechanical origin is often change, so it is necessary to introduce a set of more convenient coordinate system during processing, this is work coordinate system. The origin of work coordinate system is a fixed point relative to the workpiece, but relative to the origin of machine coordinate system is floating.

**<u>RichAuto-A11</u>** provide a machine coordinate system and eight work coordinates system,

Press "MENU "+" |MGH/LOW "can switch machine coordinate system and work coordinate system,

## MENU " + "Number Button 1-8" can switch machine coordinate system and eight work

coordinates system, Coordinates System (See Graph):

AX0.000MAUNAY0.000S2AZ0.000LSPContinous	1X         0.000         MAUN           1Y         0.000         S         2           1Z         0.000         L         SP           Continous
Machine coordinate system	Work coordinate system1
2X 0.000 MAUN	8X 0.000 MAUN
2Y 0.000 S 2	8Y 0.000 S 2
2Z 0.000 L SP	··· 8Z 0.000 L SP
Continous	Continous

Work coordinate system2

··· Work coordinate system8

**NOTE:** You cannot set work origin under machine coordinate system, switch to work coordinate system to set work origin.

#### **Automatic Processing Operation-**

Auto processing refers to the system runs the file in U disk or inner storage space according to the instruction, it also called file processing. Before auto processing, user must set the machine tool parameters and all the system parameters correctly.

#### **Auto Processing Steps:**

#### **Determine the Origin of the Workpiece-**

The origin coordinates of X, Y and Z in the processing program is the origin of the workpiece . Before operation, we should pay attention to this position as well as the real position. Operation is as follow:

Move X, Y and Z to the position which will start to process the file on workpiece. Afterwards, Press zero clearing " $\begin{bmatrix} XY \rightarrow 0 \\ 4 \end{bmatrix}$ " can set the origin of X,Y axis. Press zero clearing " $\begin{bmatrix} Z \rightarrow 0 \\ 8 \end{bmatrix}$ " to set the origin of Z axis. It should be noted that if user have already used the tool setting function which combination button is " $\begin{bmatrix} MENU \\ - \end{bmatrix}$ "+" $\begin{bmatrix} ONOFF \\ \cdot \end{bmatrix}$ ", will no need to Press the " $\begin{bmatrix} Z \rightarrow 0 \\ 8 \end{bmatrix}$ " button.

#### **Choose Processing Files-**

After determined the workpiece origin, Press " [UPPAUSE] " will appears a dialog frame: Press "  $\begin{bmatrix} X + \\ 1 ▲ \end{bmatrix}$ ", "  $\begin{bmatrix} X - \\ 5 ▼ \end{bmatrix}$ " to move the cursor and choose press "  $\begin{bmatrix} ORIGIN \\ OK \end{bmatrix}$ " to enter the list, the screen will display three file names, choose the file by pressing "  $\begin{bmatrix} X + \\ 1 ▲ \end{bmatrix}$ ", "  $\begin{bmatrix} X - \\ 5 ▼ \end{bmatrix}$ ". Press "  $\begin{bmatrix} Y + \\ 2 \land \end{bmatrix}$ ", "  $\begin{bmatrix} Y - \\ 6 \lor \end{bmatrix}$ " to turn to the next page. Press "  $\begin{bmatrix} STOP \\ CANCEL \end{bmatrix}$ " to exit.

#### **Processing Parameters Setting-**

After choosing the processing file, please Press " <sup>ORIGIN</sup> ", enter processing parameters setting, it includes Work Speed Travel speed (or Fast Speed), Speed Scale (Speed Ratio), Fall Down Speed (or Z Down Ratio).

1
3000.000
3000.000
1.000
0.200

#### Processing Parameters Setting (Cont'd.)-

Press " $\begin{bmatrix} X + \\ 1 \\ 1 \end{bmatrix}$ " and " $\begin{bmatrix} X - \\ 5 \\ \hline \end{bmatrix}$ " to move cursor, press " $\begin{bmatrix} \mathbb{R} \\ \mathbb{D} \\ \mathbb{$ 

System will remember the checking only when the previous checking is a complete and correct checking, so that the system will not check the same code again next time.

In the process of processing, the screen scrolling display real-time processing speed,

operation time, current line number. We can switch these options by Pressing " MODE ".

# MODE "

#### **During Processing Operations-**

#### Speed Ratio & Spindle Grade Adjusting-

1.) <u>Adjust Speed Ratio</u>: In-Process of processing, Press " $\begin{bmatrix} Y + \\ 2 \land \end{bmatrix}$ ", " $\begin{bmatrix} Y - \\ 6 \lor \end{bmatrix}$ " can directly change speed ratio, Current Speed = Set Speed \* Ratio, each push on " $\begin{bmatrix} Y + \\ 2 \land \end{bmatrix}$ " or " $\begin{bmatrix} Y - \\ 6 \lor \end{bmatrix}$ ", the Speed Ratio will go up or down drop 0.1. Speed Ratio: max 1.0, min 0.1, the displayed speed will be corresponding to the changing of speed ratio, but time will not change.

#### **During Processing Operations (Cont'd.)**-

#### Speed Ratio & Spindle Grade Adjusting (Cont'd.)-

2.) <u>Adjust Spindle Grade</u>: If user has set multistep speed, the DSP handle can change the Multistep Speed in process of processing. Press " $\begin{bmatrix} Z+\\ 3 \end{bmatrix}$ " and " $\begin{bmatrix} Z-\\ 7 \end{bmatrix}$ " to change Spindle Grade. Each Push of " $\begin{bmatrix} Z+\\ 3 \end{bmatrix}$ " and " $\begin{bmatrix} Z-\\ 7 \end{bmatrix}$ " will go up or down drop 1 grade till to S8 or S1.

#### Pause & Adjust Position-

Press " **RUNPAUSE** ]" pause processing. The right upwards of screen will change from

"MAUN" to "PAUZ" and machine paused processing except the rotating of spindle.

Shown Below:

1X	7.000	PA	US
1Y	8.000		<b>S2</b>
1 <b>Z</b>	-2.000	н	SP
User w	vill start		

#### Pause & Adjust Position (Cont'd.)-

At this moment, the user is allowed to adjust the position of X, Y and Z axis. The system <u>default Motion Mode is STEP</u>. So that user can fine adjust each axis distance. Machine moves one low or high-speed grid distance every step. Meanwhile, user can change the speed mode to high mode just Press "  $\begin{bmatrix} HIGHLOW \\ 0 \end{bmatrix}$ ".

When the adjustment is finished, Press " $\begin{bmatrix} RUNPAUSE \\ DELETE \end{bmatrix}$ " again, screen shows below:

1X	7.200	РА	US	
1¥	41.300	<u>S2</u>		
1Z	-0.200	н	SP	
Restore Position?				

The system asks the user whether save the modified position. Press " or " (" [UNPAUSE ]" the system will start processing in modified position, press " [STOP CANCEL ]", system will back to the position before modifying.
#### **Breakpoint Processing & Power Down Protection-**



#### Breakpoint Processing & Power Down Protection (Cont'd.)-

### Breakpoint Processing (Cont'd.)-



2.) Power off protection When there is a sudden power failure during processing, system will save current coordinate and parameters, while power restart, process continue. Before that, system must have a home motion. Shown as below:



#### **Advanced Processing-**

Advanced processing is designed for some special requests, it contains Array Work, Resume Work, Tool Changing, Part work, Calculate Bound, Mill Plane, Step Work File, Calculate Work Time, Find break No. The Combination Button is "[NUMPAUSE] "+ "[HIGHLOW] ", shown below:





Press "X+ 1A", "X- 5▼" to move cursor to the Array Work, Press "OK 7, Press "OK 7, Press "OK 7 or 7 to select different files list.
 Press "OK 7 to enter file list, then Press "X+ 1A", "X- 7 move the cursor to choose object file.

- 3.) Set processing parameters, also can modify the array parameters in this step, or you can go to **"AUTO PRO SETUP"**, choose **"Work Array"** and modify the array parameters. The rest steps are like the normal processing. System will start to work according to the user's setting.
- 4.) In the processing of array work, you can view current row number, volume number



2.) <u>**Resume Work-**</u> Steps are as follows:

## 3.) Tool Changing-

#### 4.) Park Work-

Park Work means user can select start line and stop line, so part of the processing file can be processed. The steps are as follows:



5.) Set processing parameters.

5.) **Calculate Bound-**Calculate bound means user can check the size of processing, to avoid unnecessary waste of materials and processing errors. The steps are as below:



### 6.) Mill Plane-

Include 2-two types: Scan Mill and Encircle Mill.

Steps are as follows:



1.) Press "<sup>x+</sup>/<sub>1</sub>" or "<sup>x-</sup>/<sub>5</sub>" to move cursor to choose the mill type.
2.) Press "<sup>origin</sup>/<sub>ok</sub>" to enter the Scan Mill Set, it includes Scan Type, Width, Height, Diameter, Depth, Z-Step, T-Ratio.
3.) Press "<sup>x+</sup>/<sub>1</sub>" and "<sup>x-</sup>/<sub>5</sub>" to move cursor on the option which need modify, Press "<sup>Puppuse</sup>/<sub>5</sub>" to choose mill type (X Scan or Y Scan), also press this button to modify the parameters. Press "<sup>origin</sup>/<sub>ok</sub>" after modified all the parameters to save them.



2.) Press " or enter the scan mill set, it includes Scan type, Width, Height, Diameter, Depth, Z Step, T Ratio.

3.) Press " $\begin{bmatrix} X + \\ 1 \end{bmatrix}$ " and " $\begin{bmatrix} X - \\ 5 \end{bmatrix}$ " to move cursor on the option which need modify, press " $\begin{bmatrix} UNPAUSE \\ DELETE \end{bmatrix}$ " to choose mill type(AC or C), also press this button to modify the parameters. Press "  $\begin{bmatrix} ORIGIN \\ OK \end{bmatrix}$ " after modified all the parameters to save them.

**7.) Calculate Work Time-** Calculate the processing time according to the system processing speed. After pre-read processing file, the system will display total processing time. Different processing speed will correspond to different processing time.

**8.) Find Break No-** Look for position line number. If accidentally cutter break and user hasn't saved the break point, reboot system and replace the cutter. After that, user can manually move X, Y axis to the nearest point where the cutter was broken (recommend moving a little further), press " or " or " renter into "Find Break No.", afterwards choose the previous processing file, the system will prompt "searching current position". System will start processing after finished the searching, the system will prompt "Press " or " start processing, Press " or to view the current position of line number".

**<u>9.) Scale Work-</u>** If the actual processing requires different sizes of the same file, you can select the scale work, you need to enter an enlargement or reduction ratio for processing.

Step 1.):Press"	origin Ok	"to get in <u>"Scal</u>	<u>e Work"</u> .
Select Updat	e Fil	le	
UDisk Fi	le		
Internal F	ile		
Recent Fil	e		

Choose Processing File, input correct parameters:



#### **Upgrading System-**

#### PS1. System Upgrade-

Copy upgrade file to U disk, and insert U disk into handle, file format: extension **\*\*\*\*\***. **PKG** & shown as rz-xxxx.

#### U Disk Upgrade Method 1-



1.3.) After upgrade completed, restart the handle.

#### Upgrading System (Cont'd.)-

## PS1. System upgrade (Cont'd.)-

## U Disk Upgrade Method 2-

2.1.) Copy upgrade file to U Disk and insert U Disk into handle.



2.3.) Repeat Method 2 operation 1.2 & 1.3.

#### PS2. Operations of Handle Communicating with Computer-

Users can copy file from computer to handle after <u>"Product ID: A010XXXX & Update Version</u> <u>rz-1967</u>" version. Connect handle and computer by USB cable, users can find portable storage device on the computer, and then copy processing files from computer to handle inner.

This function can ensure that if USB port of the handle is broken or there is no U Disk, the machine can still work normally.

#### **Operation Step:**

1.) Press any two buttons at the same time (For Example: "

2.) Connect handle and computer by USB Cable, it means that the handle is powered by computer, loosen the buttons after the power supply.

"**+**"

MODE

3.) Handle Screen Display:



- Connect Successfully.
- 4.) Open "My Computer", and you will find Portable Storage Device,



A0101203(H:): Handle, Users can copy processing files to handle inner.

5.) Connect Handle and Machine, Choose Internal File to Start Processing.

**NOTE:** Users can check hardware type in **Version View: "Flash Disk Mode"** is necessary, if not, users can not copy processing files from computer to handle inner.

#### PS3. Common Problems and Troubleshooting-

#### Solutions of the Faults display on the Screen-

#### **<u>1.) Indefinite Screen Flicker or Automatically restart Analysis and Solutions:</u>**

a.) Power supply is insufficient. Check power supply if there are problems and change high-quality power supply to solve the problems.

b.) The local power grid unstable. Check local grid voltage instability or increase the regulator filter device.

c.) There are something wrong with the power chip of the handle. This phenomenon also appears when the handle is powered through the USB cable to the computer ,please return the handle to our company.

#### 2.) Cannot set Working Origin Analysises and Solutions:

a.) You may get into the mechanical coordinate system. Press the Button "menu" + "1" to back to the first work coordinate system.

b.) The buttons are broken. Menu-system setup- buttons check to check the buttons are normal or not.

#### Solutions of the Faults display on the Screen-

#### Faults in Practical Operation-

### 1.) The file size does not match the size of the actual set Analysises and Solutions:

- a.) Pulse equivalent is wrong.
- b.) You does not select the right tool.

### 2.) The screen displays "beyond limit" when processing file Analysises and solutions:

a.) The machine is not carried back to zero, the system is not able to confirm the actual position. Make the machine back zero.

b.) After setting the working origin, the reserved range is less than the actual file size .Determine the actual file size and set correct working origin.

c.) You set the wrong working origin in the file. Check the path of the file, and re-export the correct file.

### 3.) Z-Axis (Spindle) fall abnormally (too fast) during processing Analysises and Solutions:

a.) Working speed beyond the fastest speed of Z-Axis. "Machine setup " - "Max speed limit ", set the speed to the safe speed.

b.) Coupling is losing or transmission slippages. Re-adjustment the connecting parts.

#### Solutions of the Faults display on the Screen-

#### **Faults in Practical Operation-**

c.) The lines connect the interface board with the motor drivers has disruption. Re-adjust the lines.

d.) Processing file error. Check processing file, try to download the correct processing file to U disk or handle internal.

e.) There is something wrong with the lines connecting Z axis motor and motor driver. Replace the lines.

# 4.) Each time repeating the same processing file after backing to the machine origin, Z-Axis depth is not the same Analysises and Solutions:

a.) Machining countertop is uneven or processing object not firmly fixed, re-milling countertop adjust the flatness.

b.) Z-Axis Origin detection switch repeat positioning accuracy error, causing each Z axis homing error. Replace a high-quality detection switch.

c.) Too much interference in the Z-axis homing process to form a false origin. Re-adjust the line.

#### Solutions of the Faults display on the Screen-

#### Faults in Practical Operation-

5.) Back to the origin, the machine cannot stop Analysises and Solutions: Double Press on the "Menu" Button, input signal (origin detection switch signal) self-testing, whether the detection signal is triggered or connect normally.

a.) The origin detection switch is damaged. Replace a new one.

b.) The distance of the origin detection switch detection sheet beyond the detection range of the switch, adjust the position of the test piece.

c.) The origin detection switch to the interface board wiring aging or loosening. Again, check the connections.

d.) The interface board is broken. Depot Repair.

e.) 50-pin data cable is broken. Replace it with a new data line.

### 6.) Back to the machine origin, machine move to the reverse direction Analysises and Solutions:

a.) The origin detection switch types do not match with the definition of the corresponding level. Modify the level. (Normally open type corresponds to a level defined the direction of the arrow down, normally closed type corresponds to the level defined arrow up).

#### Solutions of the Faults display on the Screen-

#### Faults in Practical Operation-

b.) The origin detection switch is damaged. replace a new one.

c.) The origin detection switch connects interface board not well. Refresh the line to determine the wiring is correct.

d.) Too much interference, resulting in the illusion of the detection switch has been triggered. Recalibrated the whole circuit.

e.) The interface board is broken. Depot Repair.

f.) 50-pin data cable is broken. Replace the data line.

## 7.) Abnormally working when processing file or the actual file is different from theoretical file Analysises and Solutions:

a.) The program disorder.

b.) External interference is too large. Refresh connection. (Separate strong electric from weak current, "GND" of inverter separated from the other components ).

#### Solutions of the Faults display on the Screen-

#### Faults in Practical Operation-

# 8.) Start automatic tool setting, the tool does not stop after touching feeler block Analysises and solutions:

a.) The "cutter" signal line connects "cutter" terminal not well.

b.) The "GND" terminal of interface board does not connect with spindle shell or connect not well.

#### 9.) Handle LCD digital changes, the machine does not move Analysises and solutions:

If one axis is not moving, it may be a connection problem. Change another normal terminal to this terminal, if it is ok, the motor driver is ok. Maybe there is something wrong with interface board, 50-pin cable. If it is still not moving, it is necessary to detect the corresponding drive and motor.

If all axes are not moving ,firstly check if there are problems in the 50-pin cable and interface, secondly check the power supply of the motor drivers. Lastly, you must check the mechanical part.

**10.) It is normal to the move from one location to another location, but when return from that position to the original position is not normal Analysises and solutions**: Mechanical problems screw may install not well.

#### **Electrical Components and Wiring Problem-**

#### 1.) An Axis or Multi-Axis only one-way movement after handle power-on Analysis and Solutions:

a.) There is something wrong with the lines connect the interface board with the motor driver, check the connection.

b.) Interface board is damaged. Replace the interface board.

c.) The motor driver is damaged. Replace the driver.

### 2.) The certain axis motor does not move after handle power-on Analysises and solutions:

a.) Operator makes pulse line and direction line oppositely, rewiring it.

- b.) 5V common anode end of the motor driver disconnected, check the connection.
- c.) The motor driver is damaged; operator can promote motor after handle power-on.
- d.) The chip of the interface board damages, no pulse signal output.

# 3.) Screen is not bright after handle power-on, and connected handle to computer with a USB cable the screen displays normal Analysises and Solutions:

a.) The handle does not connect to power supply. Check DC24V power supply output normal or not, if normal please check the cable from the power supply to the interface board.

b.) The 50-pin cable is damaged, or the interface is broken.

#### **Electrical Components and Wiring Problem (Cont'd.)**-

## 4.) Screen is not bright after handle power-on, and connect the handle to computer by USB cable, the screen is also not bright Analysises and Solutions:

a.) This phenomenon may be due to the handle shocked by external force or fall on the ground, causing the crystal processor damaged. Depot Repair.

b.) Users connect high voltage power supply, Depot Repair.

# 5.) The screen display "Spindle On", actually the spindle off, the screen display "Spindle Off", the Spindle on Analysises and Solutions:

a.) There is something wrong with wires. organize your wires.

b.) The output level definition is wrong. Modification correct output level definition.

#### 6.) Screen is not bright after handle power-on Analysises and Solutions:

a.) The power supply voltage is too big, or the chip is broken because operator makes positive and negative of the power oppositely. Depot Repair.

- b.) The power supply is damaged. Replace the power supply.
- c.) 50-pin data cable damaged. Replace the data line.
- d.) Handle 50-pin interface damage. Depot Repair.

#### Maintenance-

Performing regular maintenance will ensure optimal performance of the machine. Please follow these maintenance procedures.

Failure to follow maintenance procedures will void the warranty.

Table is based on 30 hours of use a week						
	Daily	Weekly	Monthly	Every Three Months	Every Six Months	Yearly
Clean the machine and lubricate unpainted surfaces with a 30wt oil lubricant. Wipe off excess oil and buff the surface dry with a soft rag. Regular cleaning and lubrication will reduce the likelihood of rust forming on the machine	x					
Remove all tooling from the spindle at the end of the day. Do not leave any tooling in the spindle overnight. This includes tool cones, collets, router bits, etc. Leaving any tooling in the spindle overnight can cause the tooling to get dirty, stuck, rust, and cause damage to the spindle.	x					
Check the tool blades for chips and dullness	х					
Inspect the overall machine for damage and loose or worn parts	х					
Regularly clean the collets and spindle holes. Uncleaned spindle holes may affect cut quality and may pose a safety hazard if significantly dirty	х					
Clean the router bits.	х					
Inspect the tool blades for chips and dullness	х					
Clean all surface dust	х					
Check the dust extraction for blockages, as large pieces could cause blockages						
Verify the electrical connectors are fitted tightly and correctly		х				

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### **Delivery/Warranty Protocols-**

### **Delivery Protocol-**

- Most large machinery will be delivering on a tractor trailer 48'-53' long. Please notify Sales Representative with any Delivery Restrictions.
- Customer is required to have a forklift (6000lb. or larger is recommended) with 72" forks or fork extensions and operator.
- Note any visible damage, torn packaging, scuffs or any abnormal marks on the delivery receipt or Bill of Lading (BOL).



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#### **Dealer Machinery Warranty**

New woodworking machines sold by Laguna Tools carry a two-year warranty effective from the date of dealer invoice to customer/end-user. Machines sold through dealers must be registered with Laguna Tools within 30 days of purchase to be covered by this warranty. Laguna Tools guarantees all new machine sold to be free of manufacturers' defective workmanship, parts, and materials. We will repair or replace, without charge, any parts determined by Laguna Tools, Inc. to be a manufacturer's defect. We require that the defective item/part be returned to Laguna Tools with the complaint. The end-user must request an RMA (return material authorization) number from Customer Service and include the (RMA) number with all returned parts/components requesting warranty coverage.\* Any machines returned to Laguna Tools must be returned with packaging in the same way it was received. If a part or blade is being returned it must have adequate packaging to ensure no damage is received during shipping. In the event the item/part is determined to be damaged due to lack of maintenance, cleaning or misuse/abuse, the customer will be responsible for the cost to replace the item/part, plus all related shipping charges. This limited warranty does not apply to natural disasters, acts of terrorism, normal wear and tear, product failure due to lack of maintenance or cleaning, damage caused by accident, neglect, lack of or inadequate dust collection, misuse/abuse or damage caused where repair or alterations have been made or attempted by others.

\*\*<mark>NOTE: Issuing an RMA number is for referencing materials and issues, it does NOT indicate warranty acceptance/conformity.</mark>

#### **CNC Limited Warranty**

New CNC machines sold by Laguna Tools carry a one-year warranty effective from the date of shipping. Laguna Tools guarantees all new machine sold to be free of manufacturers' defective workmanship, parts, and materials. We will repair or replace without charge, any parts determined by Laguna Tools, Inc. to be a manufacturer's defect. We require that the defective item/part is determined to be damaged due to lack of maintenance, cleaning or misuse/abuse, the customer will be responsible for the cost to replace the item/part, plus all related shipping charges. This limited warranty does not apply to natural disasters, acts of terrorism, normal wear and tear, product failure due to lack of maintenance or cleaning, damage caused by accident, neglect, lack of or inadequate dust collection, misuse/abuse or damage caused where repair or alterations have been made or attempted by others. Laguna Tools, Inc. is not responsible for additional tools or modifications sold or performed (other than from/by Laguna Tools, Inc.) on any Laguna Tools, Inc. woodworking machine. Warranty maybe voided upon the addition of such described tools and/or modifications, determined on a case-by-case basis. Software purchased through Laguna Tools, Inc., is not covered under this warranty and all technical support must be managed through the software provider. Normal user alignment, adjustment, tuning, and machine settings are not covered by this warranty. It is the responsibility of the user to understand basic woodworking machinery settings and procedures and to properly maintain the equipment in accordance with the standards provided by the manufacturer. Parts under warranty are shipped at Laguna Tools, Inc.'s cost either by common carrier, FEDEX ground service or a similar method. Technical support to install replacement parts is primarily provided by phone, fax, e-mail, or Laguna Tools Customer Support Website. The labor required to install replacement parts is the responsibility of the user. Laguna Tools is not responsible for damage or loss caused by a freight company or other circumstances not in our control. All claims for loss or damaged goods must be notified to Laguna Tools within twenty-four hours of delivery. \*\*\*\*Please contact our Customer Service Department for more information. Only NEW machines sold to the original owner are covered by this warranty. For warranty repair information, call 1-800-332-4094. Copyright 2013 Laguna Tools, Inc. \*\*Warning – no portion of these materials may be reproduced without written approval from Laguna Tools, Inc.

## WARRANTY & REGISTRATION

#### THANK YOU!

Welcome to the Laguna Tools® group of discriminating woodworkers. We understand that you have a choice of where to purchase your machines and appreciate the confidence you have in the Laguna Tools® brand.

Through hands-on experience, Laguna Tools® is constantly working hard to make innovative, precision products. Products that inspire you to create works of art, are a joy to operate, and encourage your best work.

> Laguna Tools® Imagination, Innovation, and Invention at Work

#### WARRANTY & REGISTRATION

Every product sold is warranted to be free of manufacturers' defective workmanship, parts, and materials. For any questions about this product, the intended use or what it was designed for, customer service, or replacement parts, please contact our customer service department:

> Laguna Tools® Customer Service 2072 Alton Parkway, Irvine, California 92606, USA 1-800-332-4049 customerservice@lagunatools.com www.lagunatools.com/why/customer-service/ 8AM. to 5PM PST, Monday through Friday

For warranty claims or to report damage upon receiving – please reach out to our warranty department:

> Laguna Tools® Warranty Service 2072 Alton Parkway, Irvine, California 92606, USA 1-949-474-1200 customerservice@lagunatools.com www.lagunatools.com/rpolicies/warranty 8AM to 5PM PST, Monday through Friday

#### REGISTRATION

To prevent voiding this warranty, all products sold must be registered within thirty (30) days of receiving the product. Registering the product will enable the original purchaser to receive notifications about important product changes, receive customer service, and be able to file a warranty claim against defective workmanship, parts, or materials.



#### WHO IS COVERED

The applicable warranty covers only the initial purchaser of the product from the date of receiving the product. To file such claims, the original purchaser must present the original receipt as proof of purchase.

#### WHAT IS COVERED

The warranty covers any defects in the workmanship of all parts and materials that make up the machine unless otherwise specified. Any part, determined by Laguna Tools®, to have a defect will be repaired or replaced (and shipped), without charge. The defective item/part must be returned to Laguna Tools® with the complaint and proof of purchase in the original packaging that it was received in. In the event the item/part is determined to be not covered by this warranty, the customer will be responsible for the cost to replace the item/part and all related shipping charges.

#### WARRANTY LIMITATIONS

This limited warranty does not apply to natural disasters, acts of terrorism, normal wear and tear, product failure due to lack of maintenance or cleaning, damage caused by accident, neglect, or lack-of inadequate dust collection. The warranty may be voided against proof of misuse/abuse, damage caused where repair or alterations have been made or attempted by others, using the product for purposes other than those described as intended use (unless with consent by Laguna Tools®), modification to the product, or use with an accessory that was not designed for the product. It is the responsibility of the user to understand basic woodworking machinery settings and procedures and to properly maintain the equipment in accordance with the standards provided in this manual.

#### LENGTH OF WARRANTY

All new machines and optional accessories sold through an authorized dealer carry a two-year warranty effective the date of receiving the product. Machines sold for either commercial or industrial use have a oneyear warranty. Wearable parts like throat plates, bandsaw guides, etc., have a ninety-day warranty.

#### Table A-1 Warranty Lengths

Year – New Machines Sold Through an Authorized Dealer
 Year – Accessories Sold as Machine Options (excluding blades)
 Year – Machines Sold for Commercial or Industrial Use
 Year – Blades and Accessories outside of Machine Options
 90 Days – Wearable Parts

Aside from being free of defects upon receiving, consumable parts, like cutters and abrasives, are not covered by this warranty unless otherwise stated by Laguna Tools®. These parts are designed to be used at the expense of the operator and are available for replacement or inventory purchase. The determination of a consumable part will be made on a case-by-case basis by Laguna Tools®.

#### SHIPPING DAMAGE

Laguna Tools® is not responsible for damage or loss caused by a freight company or other circumstances not in the direct control of Laguna Tools®. All shipping-related claims for loss or damage goods must be made to Laguna Tools within twenty-four hours of delivery.

#### HOW TO RECEIVE SUPPORT

To file a warranty-claim please contact the warranty department at 1-949-474-1200. To receive customer service or technical support please contact the customer service department at 1-800-332-4094. Parts, under warranty, are shipped at the expense of Laguna Tools® either by common carrier, FedEx ground services or similar method. Technical support to install replacement parts is primarily provided by phone, fax, email, or the Laguna Tools Customer Support Website.



#### No Modifications Allowed or Sold.

Laguna Tools, Inc. is not responsible for additional tools or modifications sold or performed (other than from/by Laguna Tools, Inc.) on any Laguna Tools, Inc. woodworking machine. Warranty maybe voided upon the addition of such described tools and/or modifications, determined on a case-by-case basis. Normal user alignment, adjustment, tuning, and machine settings are not covered by this warranty. It is the responsibility of the user to understand basic woodworking machinery settings and procedures and to properly maintain the equipment in accordance with the standards provided by the manufacturer. Parts, under warranty, are shipped at Laguna Tools, Inc.'s cost either by common carrier, FEDEX ground service or a similar method. Technical support to install replacement parts is primarily provided by phone, fax, e-mail, or Laguna Tools Customer Support Website. The labor required to install replacement parts is the responsibility of the user. Laguna Tools is not responsible for damage or loss caused by a freight company or other circumstances not in our control. All claims for loss or damaged goods must be notified to Laguna Tools within twenty-four hours of delivery. Please contact our Customer Service Department for more information. Only new machines sold to the original owner are covered by this warranty. For warranty repair information, call 1-800-332-4094.

Laguna Tools Warranty-Laguna Tools Packaging/RMA Procedures-Dealer Machinery Warranty

\*\*Any machines returned to Laguna Tools must be returned with packaging in the same way it was received. If a part or blade is being returned it must have adequate packaging to ensure no damage is received during shipping. In the event the item/part is determined to be damaged due to lack of maintenance, cleaning or misuse/abuse, the customer will be responsible for the cost to replace the item/part, plus all related shipping charges.

We require that the defective item/part be returned to Laguna Tools with the complaint. The end-user must request an **RMA (Return Material Authorization) Number** from Customer Service and include the (RMA) number with all returned parts/components requesting warranty coverage.

## Laguna Tools Packaging/Laguna Tools RMA Example-

Γ	12/1/2020	Return Authorization - NetSuite (Laguna Too	is, Inc)
	Return Authorization		
	CR10979 Black Forest wood 0	CO. PENDING RECEIPT	
		Actions	
	CUSTOMER Black Forest wood Co.	CREATED FROM Sales Order #210855	Summer .
DN44 #	DATE 11/5/2020	SALES EFFECTIVE DATE 11/5/2020	SUBTOTAL 1,686.59
<u>RIVIA #</u>	CURRENCY Canadian Dollar	EST. EXTENDED COST 755.64	DISCOUNT
	SUBSIDIARY Laguna Toola, Inc	EST. GROSS PROFIT 930 95	PST 0.00
RIN. AUTH. #	RTN. AUTH. # CR10979	EST. GROSS PROFIT PERCENT 55.1972%	TOTAL 1,770.92
CRIU979	DEPARTMENT Sales : Wholesale	PROMISE DATE 5/12/2020	
	PRODUCT LINE	DEPOSIT RECEIVED	
	LOCATION	ACCOUNTING APPROVAL	
	Laguna Texas Demo / Returns SALES REP	Customer's bandsaw cast iron at the bottom is bent the customer can't insert bolts to stand. No shipping damage	
	Benjamin Helshoj	machine arrived in excellent condition do damage to packaging.	
		PO 981 RETURN REASON	
	Dealer_Canada Dealer-Canada	Manufacturers Warranty Defect SHIP IMMEDIATE	
	PO# PO-981	SPLIT SHIP	
	MEMO	REVISED INVOICE	
		ORDER HOLD REASON	
	SHIPPING COMMENTS		
	Items Pronotors Address Messages	History Workfow Custom Partners Sales Taum	Additional Information OzLINK Pacelet SPS
	EXCHANGE RATE	RATE	
	0.76094		
	USCOUNT		
			07
	ITEM RETURNED REFUNDED QUANTITY UN	INVENTORY PRICE TXX ITS DETAIL DESCRIPTION LEVEL UNIT PRICE AMOUNT CODE	TAX GRFT DROP EST RATE PET OPTIONS CERTIFICATE CLOSED SHIPMENT TYP
	Machine : 0 0 1 Ea Bandsaw :	ch 14-12 110 Retail 1,686.59445773 1,686.59 CA- VOLT Price GST	5.0% 0.0% Iter De
	MBAND1412- 175 14[12	BANDSAW only	Co
	110V 1,75HP		
	Edit Back Receive Close	Actions	

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## Laguna Tools Packaging/Laguna Tools BILL of LADING Example-

Date: 12/02/2020 BILL OF LA	DING	
SHIP FROM Name: Nathaniel Boomer Address: 4700 Burleson Rd Units L M City/State/Zip: AUSTIN,TX 78704	Bill of Lading Number : <u>145787446</u> Carrier Name: <u>Estes Express</u> SCAC: EXLA Pro number:	Bill of Lading Number : <u>145787446</u>
Ph: (512) 645-4170 Contact: Nathaniel Boomer FOB:□ SHIP TO Name: Laguna Tools TX Location# Address: 744 Refuge Way Suite 200 City/State/Zip: GRAND PRAIRIE,TX 75050 Ph: 9494741200 Contact: Vince (ZM) RMACR11096 FOB:□ FREIGHT CHARGES BILL TO Name: Worldwide Express Address: 2828 Routh Street Suite 400 City/State/Zip: Dallas, TX 75201 SPECIAL INSTRUCTIONS: For assistance, please call 833-8WE-SHIP Handling Instructions: RMACR11096	Freight Charge Terms: (freight charges are prepaid by Worldwide Express unless indicated otherwise) Master Bill of Lading: with attached underlying Bill Of Lading WWE Number: W709699351	SPECIAL INSTRUCTIONS: For assistance, please call 833-8WE-SHIP Handling Instructions: RMACR11096
Pickup Instructions: Delivery Instructions: RMACR11096 Pickup Service(s): Liftgate Pickup, Residential Pickup REFERENCE # PKGS REFERENCE	FORMATION E # PKGS Total # of Pkgs	Pickup Instructions: Delivery Instructions: RMACR11096 Pickup Service(s): Liftgate Pickup, Residential Pickup
CARRIER INFORM/           HANDLING         PIECES         COMMONTY DE           UNITS         WEIGHT         M.M.         Commodies may be an applied or state specifically in writing the agreed or declared value of property as follows: The agreed or declared value of the property is specifically stated by the shipper to be not exceeding per	COD Amount:         \$         LTL ONLY           COD Amount:         \$         Acceptable Forms of Payment's Bank Centified Check         T7.5	
Note:         Liability limitation for loss or damage in this shipment may be applicable. See 49           U.S.C. B14706(c)(1)(A) and (B)         RECEIVED. subject to individually determined rates or contracts that have been agreed upon in writing between the carried and Worldwide Express Operations, LLC. a registered motor carried broker, pursuant to 40 USC 14101(b) and all applicable state and federal regulations.           SHSPERTS SIGNATURE / DATE This is certify that he above-named materials are proper classified, describer, pursuant for the responsion for transportation according to the explorable regulations.         Trailer Loaded:         Freight Courted by Shipper           By Shipper         By Shipper         By Shipper         By Shipper         By Oniverplate said to contain By Driver Place	Personal Check     Personal Check     Personal Check     Personal Check     Personal Check     Personal Check     Portune Check     Carrier acknowledges receipt of packages and required     placards. Carrier certifies emergency response information     was made available and ior carrier has DOT emergency     response guidebook or equivalent documentation in vehicle.     Property described above is received in good order, except as     noted.	
(Signature) (Date)	(Signature) (Date)	8

## **Manual Revision Record**

	De later #	
Date of Change	<u>Revision#</u>	Engineering/Design Change Description
10/06/2021	R01	Developed New Manual for the J8 CNC Machine.
11/19/2024	R02	Inserted Maintenace Section